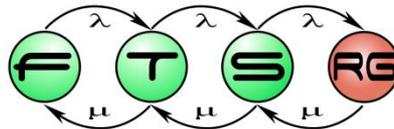


# Structure-based test design

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# Main topics of the course

- **Overview (1)**
  - V&V techniques, Critical systems
- **Static techniques (2)**
  - Verifying specifications
  - Verifying source code
- **Dynamic techniques: Testing (7)**
  - Developer testing, **Test design techniques**
  - Testing process and levels, Test generation, Automation
- **System-level verification (3)**
  - Verifying architecture, Dependability analysis
  - Runtime verification

# Test design techniques

**Goal: Select test cases based on test objectives**

## Specification-based

- SUT: black box
- Only spec. is known
- Testing specified functionality

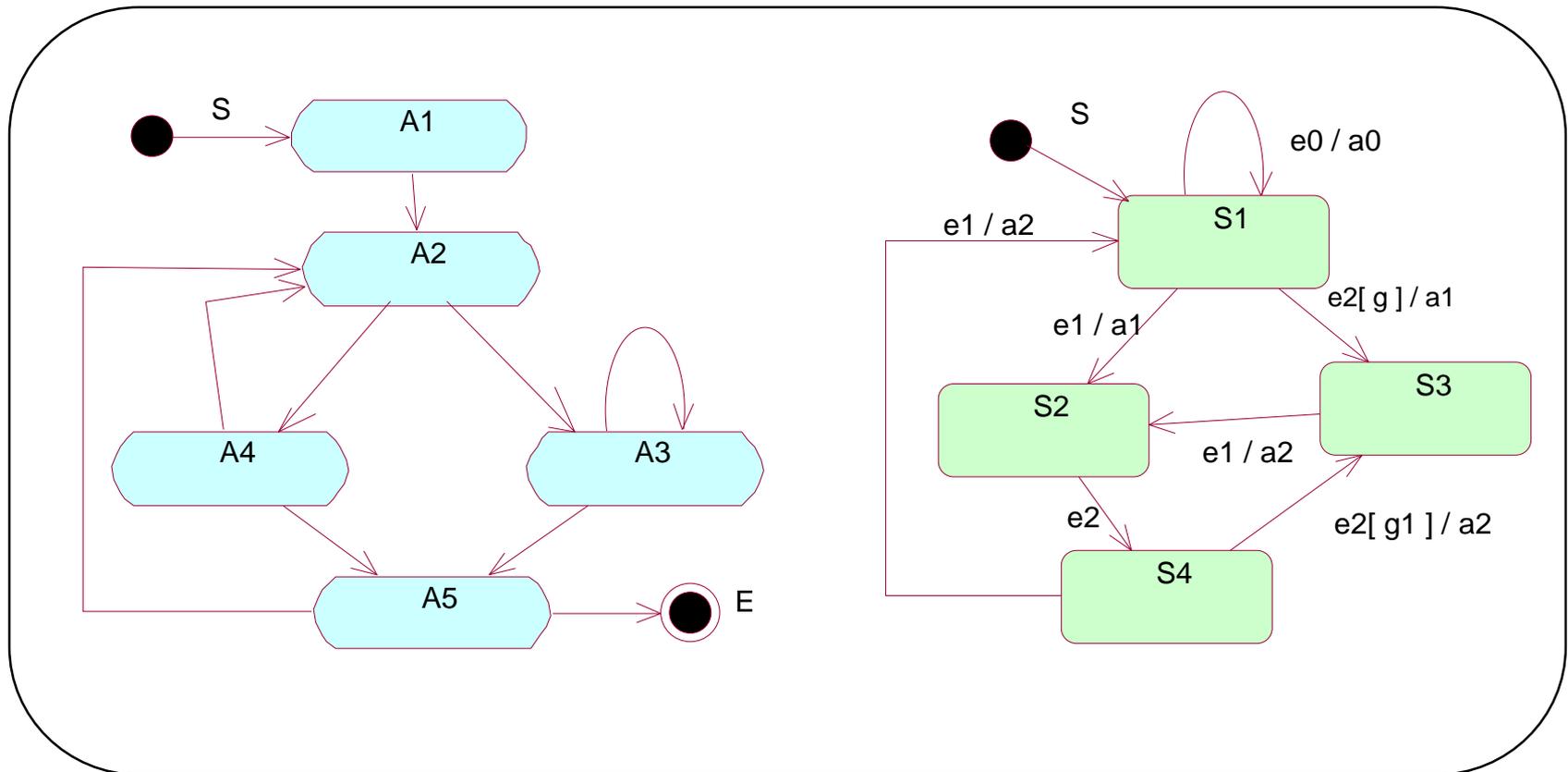
## Structure-based

- SUT: white box
- Inner structure known
- Testing based on internal behavior

# STRUCTURE-BASED TESTING

# What is “internal structure”?

- In case of models: structure of the model



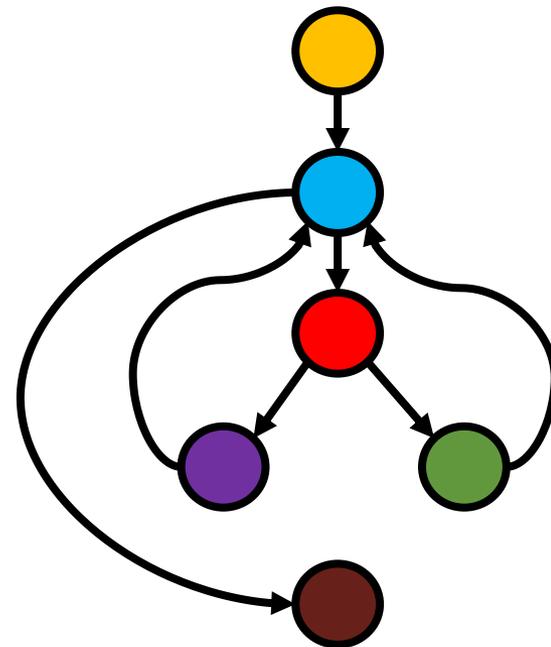
# What is “internal structure”?

- In case of models: structure of the model
- In case of code: structure of the code (CFG)

Source code:

```
int a = 1;
while(a < 16) {
  if(a < 10) {
    a += 2;
  } else {
    a++;
  }
}
a = a * 2;
```

Control-flow graph:



# Coverage metrics

- What % of **testable elements** have been tested
- Testable element
  - Specification-based: requirement, functionality...
  - Structure-based: statement, decision...
- **Coverage criterion**: X % for Y coverage metric
- This is not **fault coverage**!

# How to use coverage metrics?

## Evaluation (measure)

- Evaluate quality of existing tests
- Find missing tests

## Selection (goal)

- Design tests to satisfy criteria

# CONTROL-FLOW CRITERIA

# Learning outcomes

- Explain the differences between different control-flow based coverage criteria (K2)
- Design tests using control-flow based coverage criteria for imperative programs (K3)

# Basic concepts

```
int t = 1;  
Speed s = SLOW;
```

Statement

Block

```
if (! started){  
    start();  
}
```

```
if (t > 10 && s == FAST){  
    brake();  
} else {  
    accelerate();  
}
```

Condition

Decision

Branch

# Basic concepts

- **Statement**
- **Block**
  - A sequence of one or more consecutive executable statements containing no branches
- **Condition**
  - Logical expression without logical operators (and, or...)
- **Decision**
  - A logical expression consisting of one or more conditions combined by logical operators
- **Path**
  - A sequence of events, e.g., executable statements, of a component typically from an entry point to an exit point.

# Example: decision and condition

- A decision with one condition:

```
if (temp > 20) {...}
```

- A decision with 3 conditions:

```
if (temp > 20 && (valveIsOpen || p == HIGH)) {...}
```

# Control Flow Graph (CFG)

- A CFG represents the flow of control
- **$G = (N, E)$  directed graph**
  - Node  $n \in N$  is a basic block
    - Basic block: Sequence of statements with exactly one entry and exit points.
  - Edge  $e = (n_i, n_j) \in E$  is a possible flow of control from basic block  $n_i$  to basic block  $n_j$

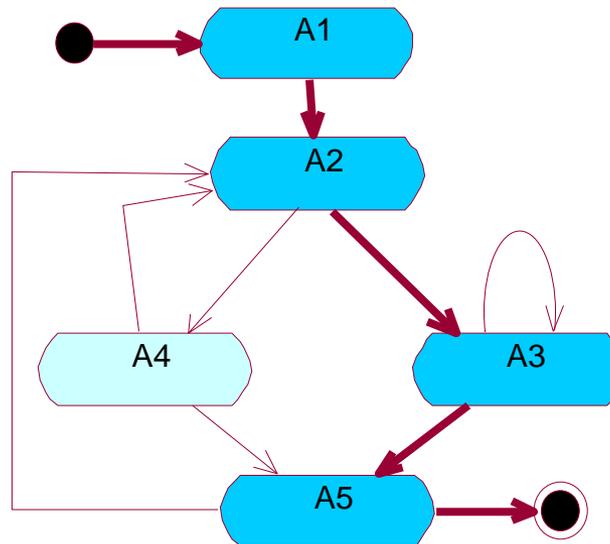
# EXERCISE Building a CFG

```
public void insertionSort(int[] a) {
    for(int i = 0; i < a.size(); i++) {
        int x = a[i];
        int j = i - 1;
        while(j >= 0 && a[j] > x) {
            a[j+1] = a[j];
            j = j - 1;
        }
        a[j+1] = x;
    }
    System.out.println("Finished.");
}
```

Build the CFG of  
this program  
code

# 1. Statement coverage

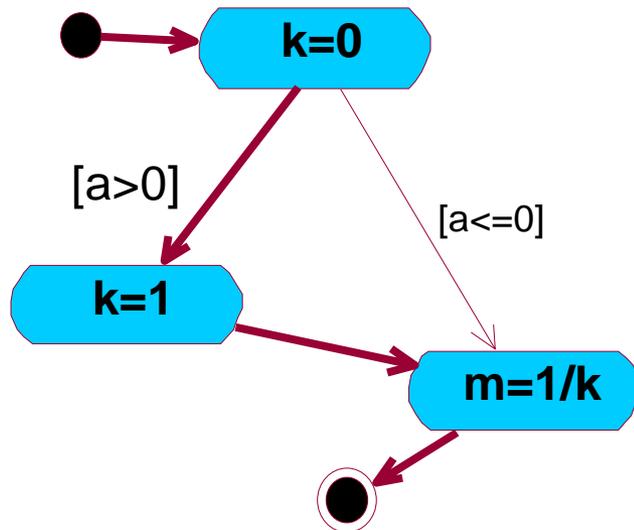
Number of statements executed during testing  
Number of all statements



Statement coverage:  $4/5 = 80\%$

# Assessing statement coverage

All statement is executed at least once



Statement coverage: 100%

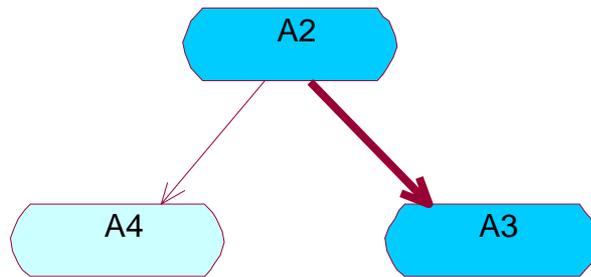
BUT:  $[a \leq 0]$  branch missing!

Does not guarantee coverage of empty branches

## 2. Decision coverage

Outcomes of decisions taken during testing

Number of all possible outcomes



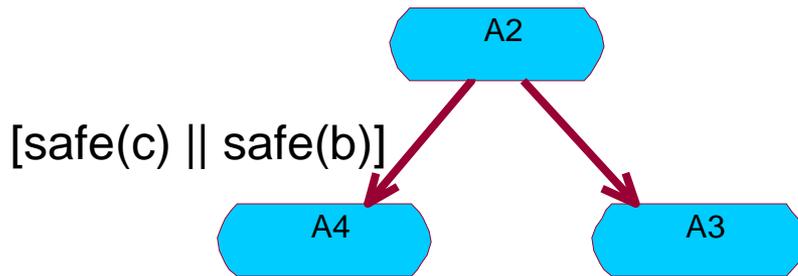
Decision coverage:  $1/2 = 50\%$

How many outcomes can a decision have?

# Assessing decision coverage

All statement is executed at least once

All outcomes of decisions are covered



100% decision coverage:

#	safe(c)	safe(b)
1	T	F
2	F	F

safe(b) == True missing!

Does not take into account all combinations of conditions!

# 3. Condition coverage

Generic coverage metric for conditions:

$$\frac{\text{Number of tested combinations of conditions}}{\text{Number of aimed combinations of conditions}}$$

Definition (what conditions are aimed):

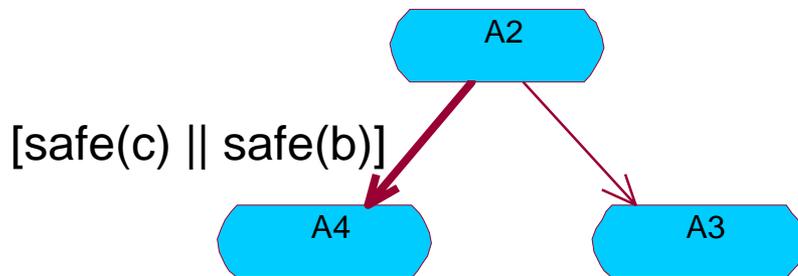
- Every condition must be set to true and false during testing

Other possible definition:

- Every condition is **evaluated** to both true and false
  - Not the same as above due to *lazy evaluation*

# Assessing condition coverage

Every condition has taken all possible outcomes at least once



100% condition coverage:

#	safe(c)	safe(b)
1	T	F
2	F	T

False outcome of decision missing!

Does not yield 100% decision coverage!

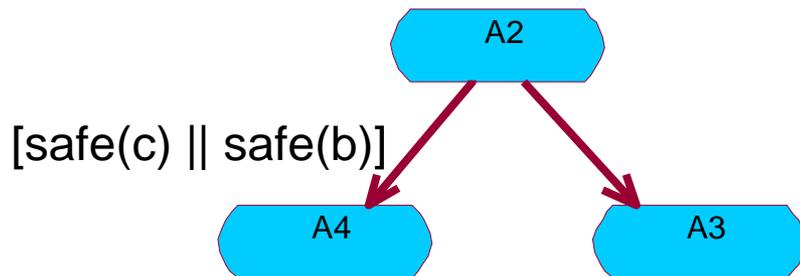
# 4. Condition/Decision Coverage (C/DC)

Combination of condition and decision coverage

# Assessing C/DC Coverage

Every decision has taken all possible outcomes at least once.

Every condition has taken all possible outcomes at least once



100% C/DC coverage:

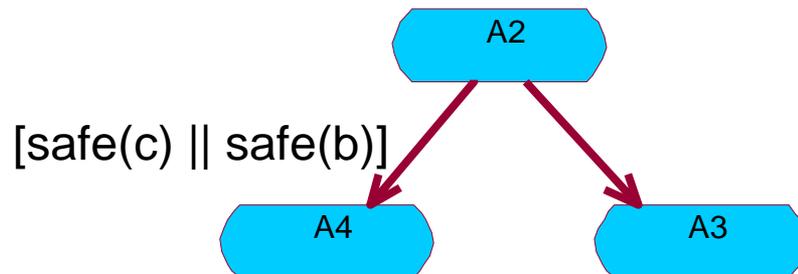
#	safe(c)	safe(b)
1	T	T
2	F	F

Does not take into account whether the condition has any effect!

# 5. Modified Condition/Decision Coverage (MC/DC)

- Each entry and exit point has been invoked at least once,
- every condition in a decision in the program has taken all possible outcomes at least once,
- every decision in the program has taken all possible outcomes at least once,
- each condition in a decision is shown to independently affect the outcome of the decision.

100% MC/DC coverage:



#	safe(c)	safe(b)
1	T	F
2	F	T
3	F	F

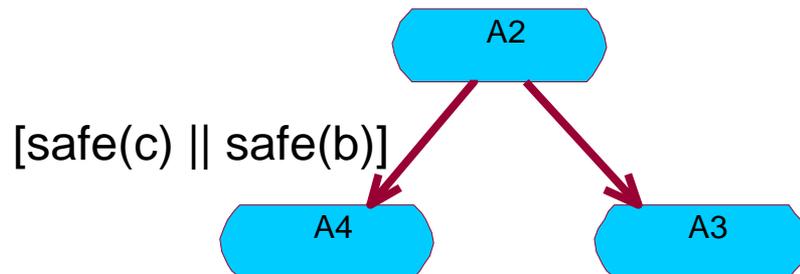
# 6. Multiple Condition Coverage

Every combinations of conditions tried

- For n conditions  $2^n$  test cases may be necessary!
- (Bit less with lazy evaluation)
- Sometimes not practical, e.g. in avionics systems there are programs with more than 30 conditions!

100% MCC coverage:

#	safe(c)	safe(b)
1	F	F
2	F	T
3	T	F
4	T	T



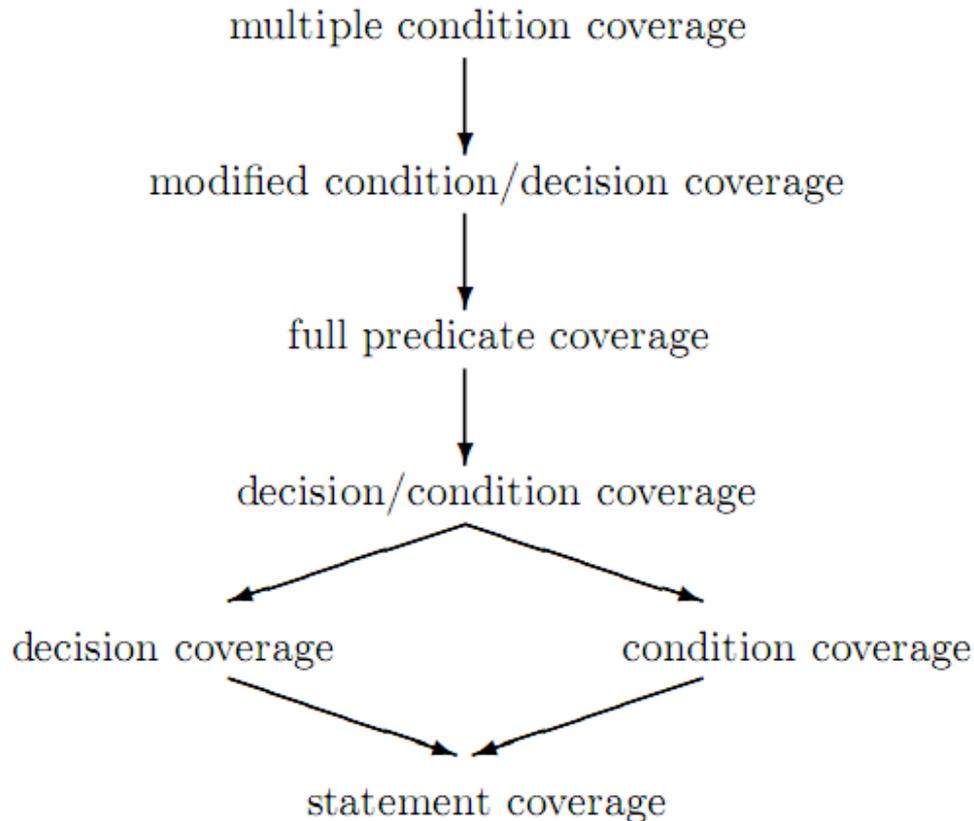
# Comparing control-flow criteria

Table 1. Types of Structural Coverage

Coverage Criteria	Statement Coverage	Decision Coverage	Condition Coverage	Condition/Decision Coverage	MC/DC	Multiple Condition Coverage
Every point of entry and exit in the program has been invoked at least once		•	•	•	•	•
Every statement in the program has been invoked at least once	•					
Every decision in the program has taken all possible outcomes at least once		•		•	•	•
Every condition in a decision in the program has taken all possible outcomes at least once			•	•	•	•
Every condition in a decision has been shown to independently affect that decision's outcome					•	• <sup>8</sup>
Every combination of condition outcomes within a decision has been invoked at least once						•

Source: Kelly J. Hayhurst et al. „A Practical Tutorial on Modified Condition/Decision Coverage”, NASA/TM-2001-210876, 2001

# Comparing control-flow criteria



Source: S. A. Vilkomir and J. P. Bowen, "From MC/DC to RC/DC: formalization and analysis of control-flow testing criteria," *Formal Aspects of Computing*, vol. 18, no. 1, pp. 42-62, 2006.

# EXERCISE Specification-based test design

```
Product getProduct(String name, Category cat){
    if (name == null || ! cat.isValid)
        throw new IllegalArgumentException();

    Product p = ProductCache.getItem(name);

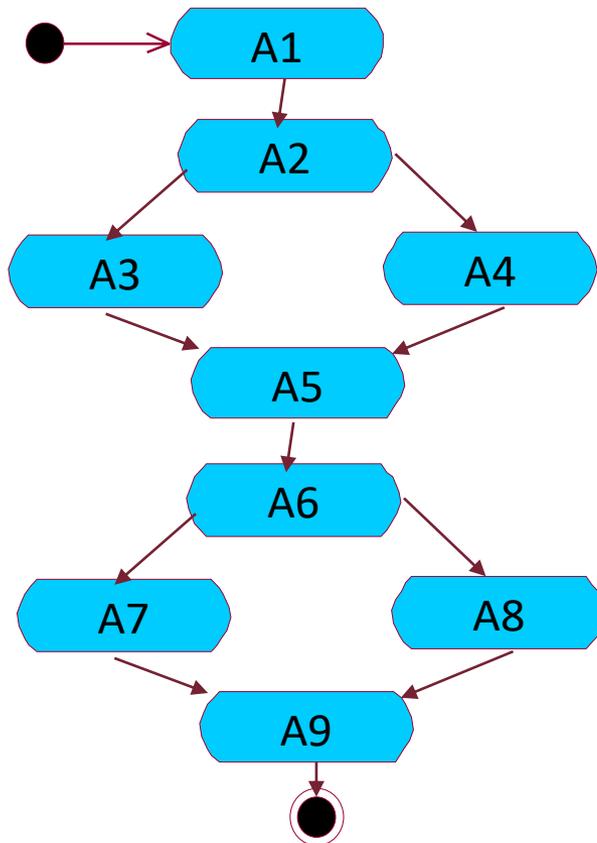
    if (p == null){
        p = DAL.getProduct(name, cat);
    }

    return p;
}
```

- Design tests for
1. Statement
  2. Decision
  3. C/DC coverage

# 7. Basis path coverage

Number of independent paths traversed during testing  
Number of all independent paths



## Tests

1. A1, A2, A3, A5, A6, A7, A9
2. A1, A2, A4, A5, A6, A8, A9

Statement coverage: ?

Decision coverage: ?

Path coverage: ?

# Assessing full path coverage

- 100% path coverage implies:
  - 100% statement coverage, 100% decision coverage
  - 100% multiple condition coverage is not implied
- Full path coverage is usually not practical in case of loops

# Additional coverage criteria

- Loop
  - Executing loops 0, 1 or more times
- Race
  - Executions from multiple threads on code
- ...

# Calculating coverage in practice

- Every tool uses **different definitions**
- Implementation
  - **Instrument** source/byte code
  - Adding instructions to count coverage

```
if (a > 10){  
    CoveredBranch(1, true);  
    b = 3;  
} else {  
    CoveredBranch(1, false);  
    b = 5;  
}  
send(b);
```

See also: [Is bytecode instrumentation as good as source code instrumentation](#), 2013.

# DATA-FLOW COVERAGE

# Learning outcomes

- Summarize the basic ideas of data-flow coverage criteria (K2)

# Goal of data-flow coverage

- **Idea:**
  - Track the assignment and usage of variables
  - Label CFG with data-flow events
- **Faults to detect:**
  - Erroneous assignments
  - Effect of assignments

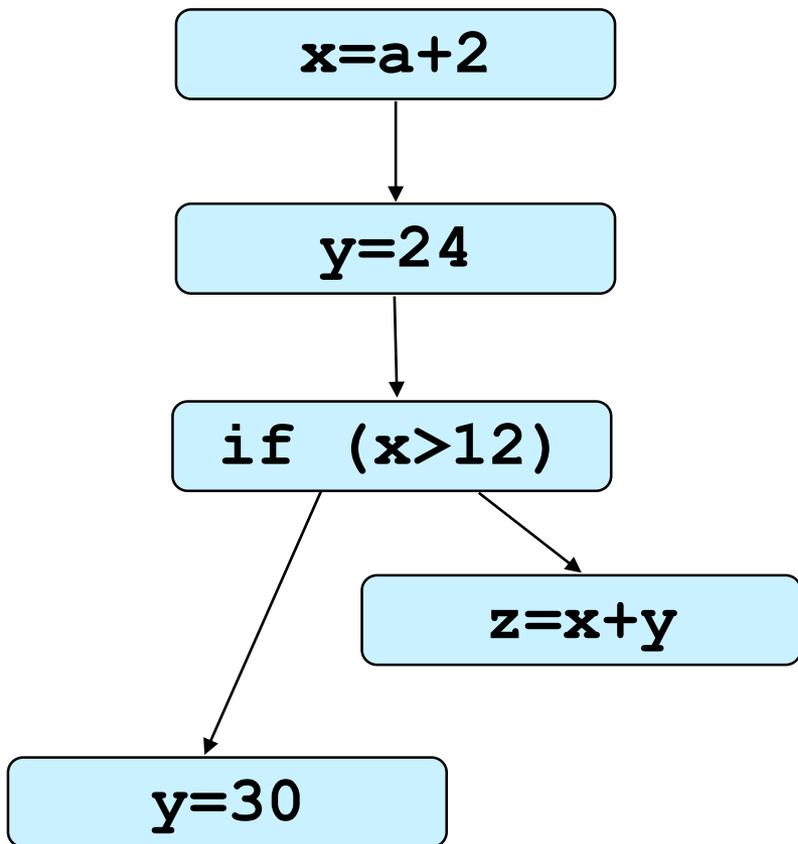
# Labeling the control flow graph

- **def(v)**: variable **v** is assigned in the given location
- **use(v)**: variable **v** is used in the given location
  - **p-use(v)**: value of variable **v** is used in a condition
  - **c-use(v)**: value of variable **v** is used in a computation

# EXERCISE

# Labeling variable def and use

Variable: x      y      z      a



def x

c-use a

def y

p-use x

c-use x

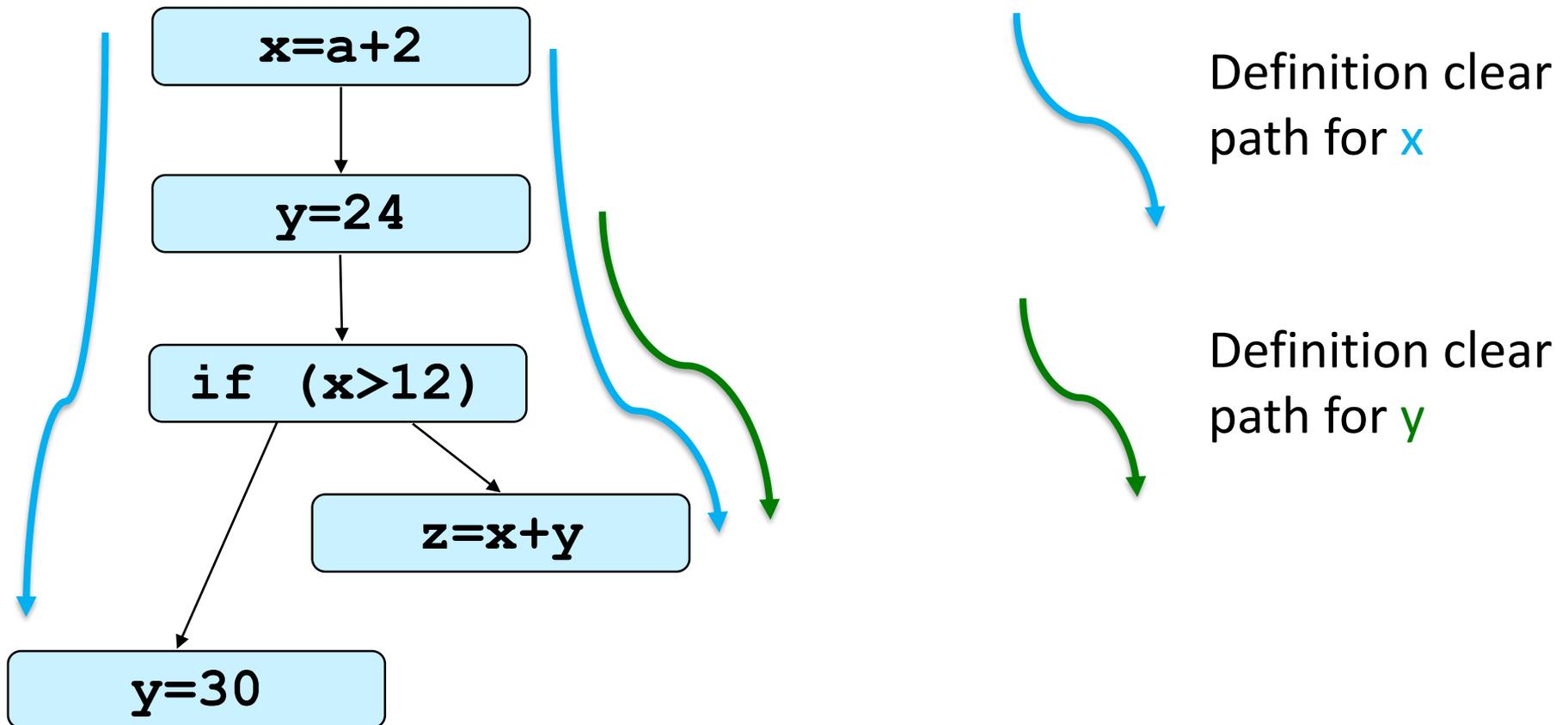
c-use y

def z

def y

# Program paths

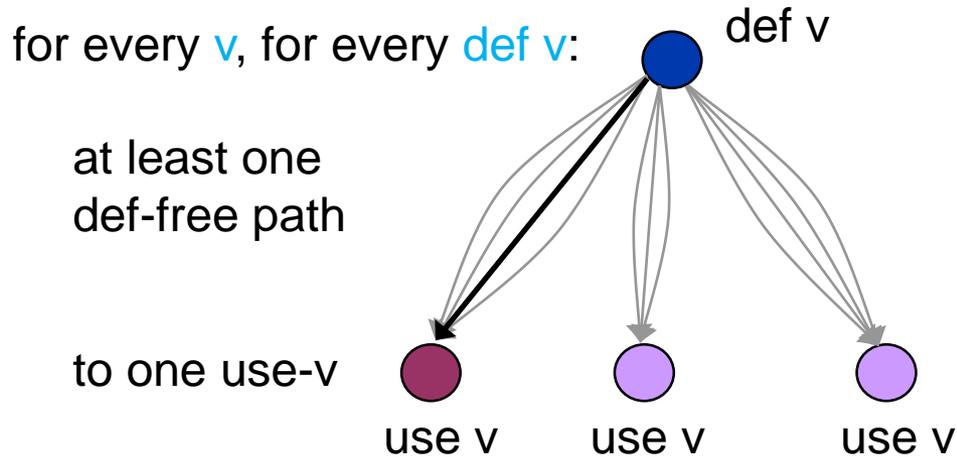
- **Definition clear path** for variable  $v$ 
  - $v$  is not assigned in the nodes of the path



# Data-flow criteria

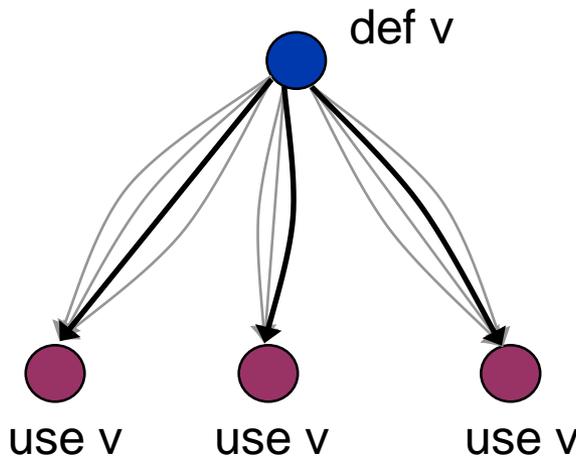
## ■ All-defs:

- def  $v$
- use  $v$

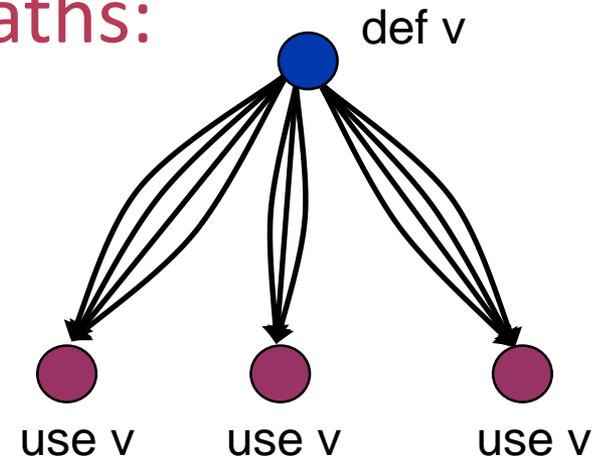


## ■ All-uses:

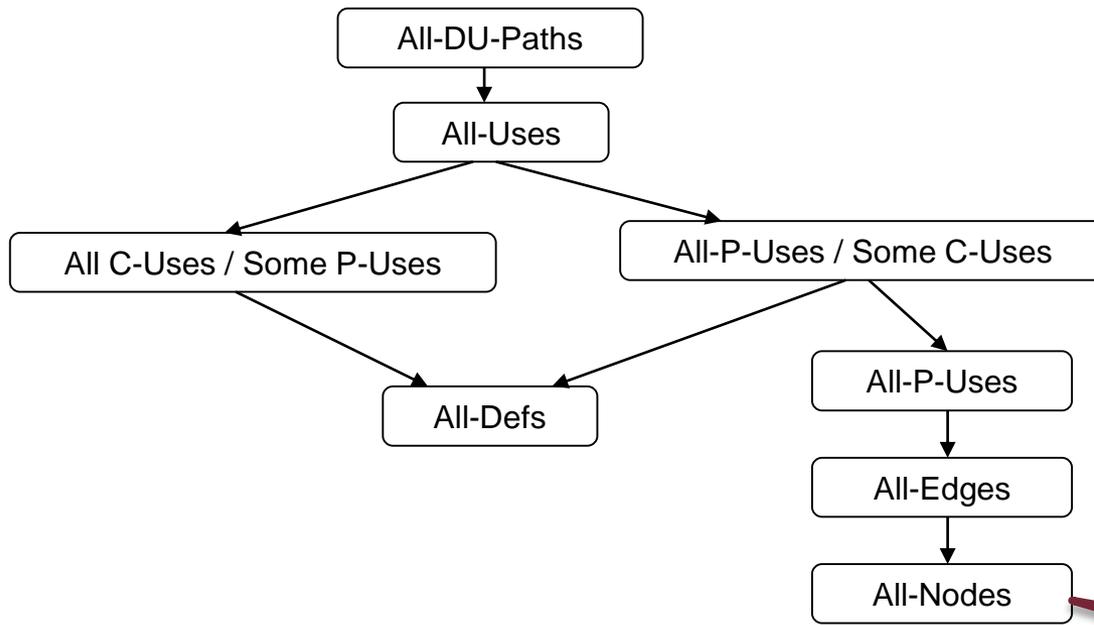
- p-uses,
- c-uses



## ■ All-paths:



# Comparing structural coverage criteria



Standards for safety-critical prescribe more complex criteria

Average projects do not measure coverage or aim only for statement coverage

# SUMMARY

# Using test coverage criteria

## ■ Can be used for:

- Find not tested parts of the program
- Measure “completeness” of test suite
- Can be basis for exit criteria
- [Spoiler] Test generation (see lectures later)

## ■ Cannot be used for:

- Finding/testing missing or not implemented requirements
- Only indirectly connected to code quality

# Using test coverage criteria

## ■ Experience from Microsoft

- „Test suite with **high code coverage** and **high assertion density** is a good indicator for code quality.”
- „**Code coverage alone** is generally **not enough** to ensure a good quality of unit tests and should be used with care.”
- „The **lack of code coverage** to the contrary clearly indicates a **risk**, as many behaviors are untested.”

(Source: „Parameterized Unit Testing with Microsoft Pex”)

## ■ Related case studies:

- „*Coverage Is Not Strongly Correlated with Test Suite Effectiveness*”, 2014. DOI: [10.1145/2568225.2568271](https://doi.org/10.1145/2568225.2568271)
- „*The Risks of Coverage-Directed Test Case Generation*”, 2015. DOI: [10.1109/TSE.2015.2421011](https://doi.org/10.1109/TSE.2015.2421011)