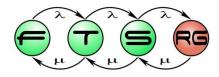
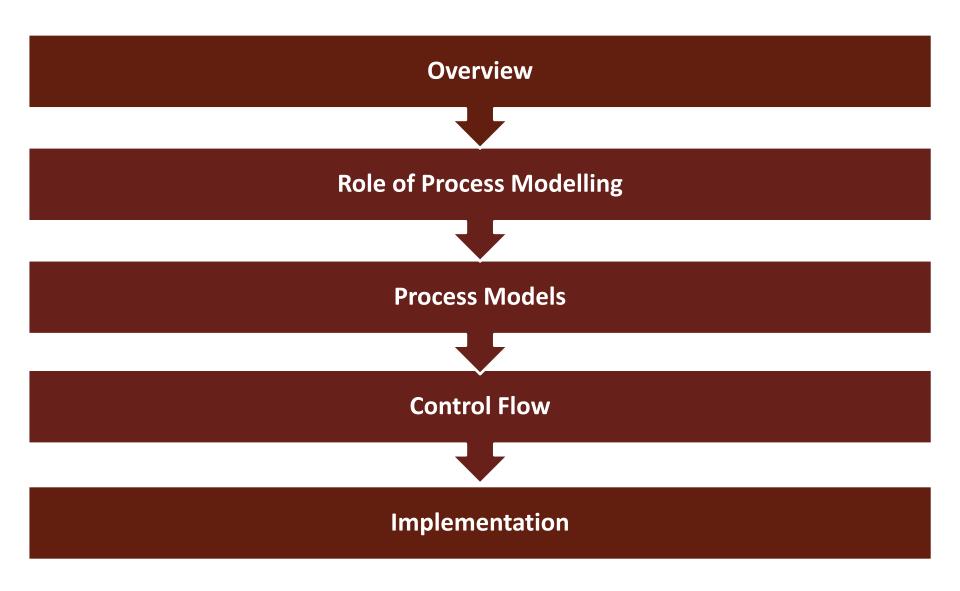
#### **Process Modelling**

# **Budapest University of Technology and Economics Fault Tolerant Systems Research Group**





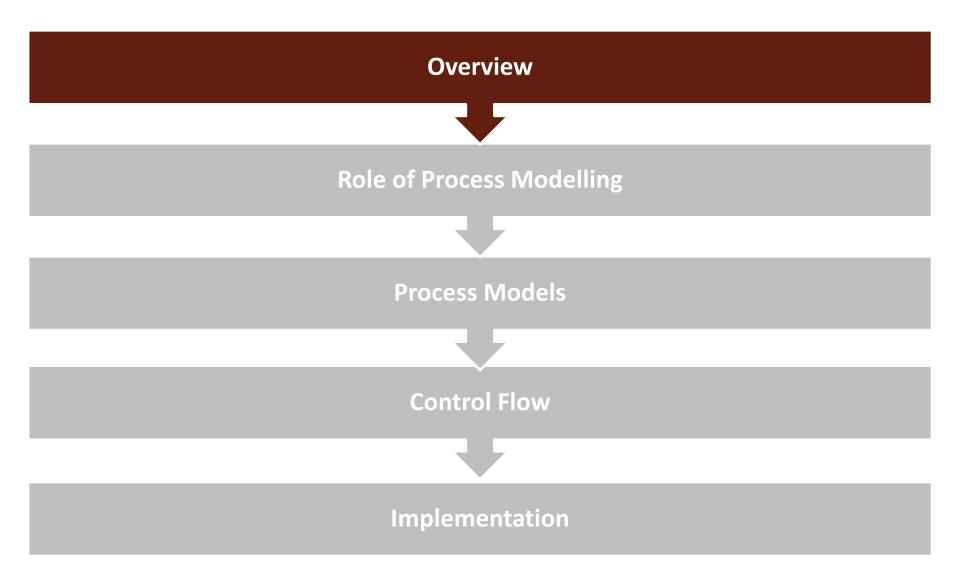
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### Structure and Behaviour Modelling

- Structural
  - Static

- The main components of the robot vacuum cleaner are the control unit, the roller gear and the vacuum cleaner.
- Whole and part, components
- Connections
- Behavioural
  - Dynamic
  - Timeliness
  - State, Process
  - Reaction to the environment (context)
- Modelling does not cover all aspects, aspects cannot be separated...

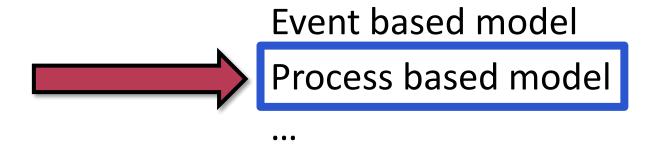
For the command "to right" changes the roller gear its operational mode to "turn".





#### Main Questions of the Behavioural Models

What the system "does"?



What are the properties of the system now, and how is it changing?



State based models





#### Main Questions of the Behavioural Models

- State Based Approach
  - the system changes (its properties)
  - as a reaction to (external) events
  - input/output channels
- Process Based Approach
  - the system changes the work item
  - as a series of activities
  - data flow





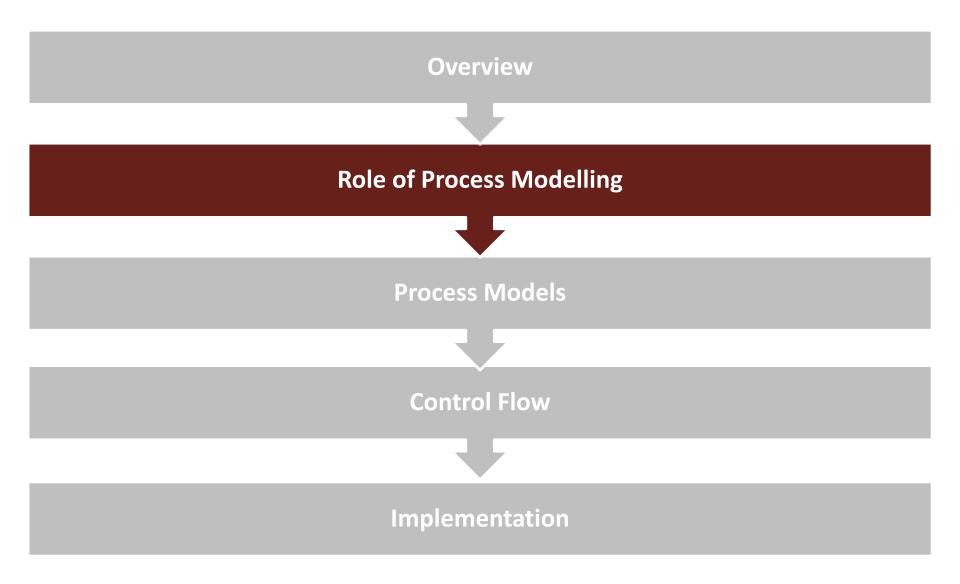
#### **Definition: Process**

**Process:** series of steps that achieve purpose when executed in the right order





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# Role of Process Modelling

- Specification
- Design
- Implementation
  - Executable models
  - Code generation
- Model verification
  - Simulation
  - Monitoring
  - Automated model checking
- Documentation





#### Example: How Does the Product Arrive?

#### Package 1

Product's predicted arrival to our store: 23.03.2016

When the products are ready to pick up, we will send you a notification in text message and e-mail. You will be able to pick up the product immediately after you recieved the notification.

Please do not come to our store before recieving a notification. Thank you!

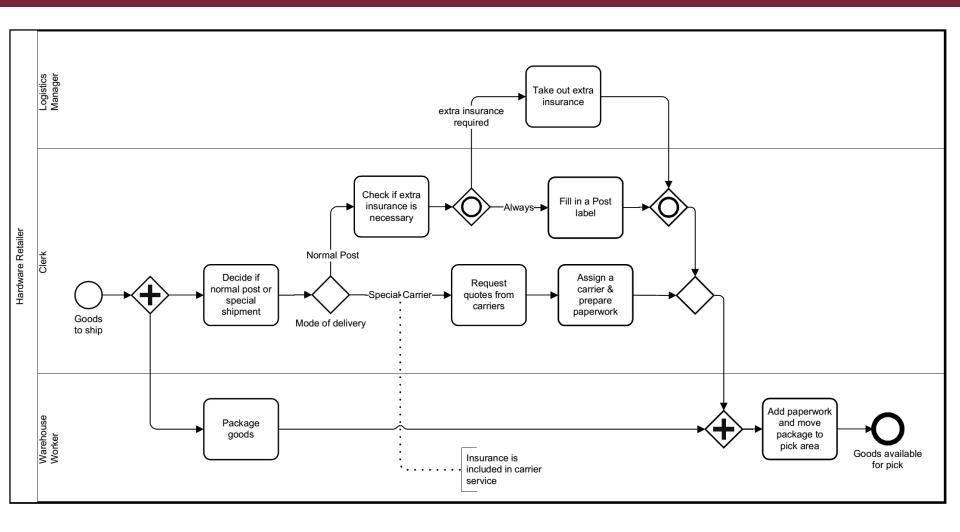
#### Ordered products in the package:

	Name of product	Prize
1 x	FISKARS Xsharp axe and knife sharpener 120740	3 590 HUF
1 x	FISKARS Twisted splitting wedge 120020	6 990 HUF
1 x	MOTOROLA TLKR T41 Walkie talkie, Orange	8 590 HUF
	Payment fee	490 HUF
	Package price: (including shipment fee and VAT)	19 660 HUF





# Example: HW Delivery

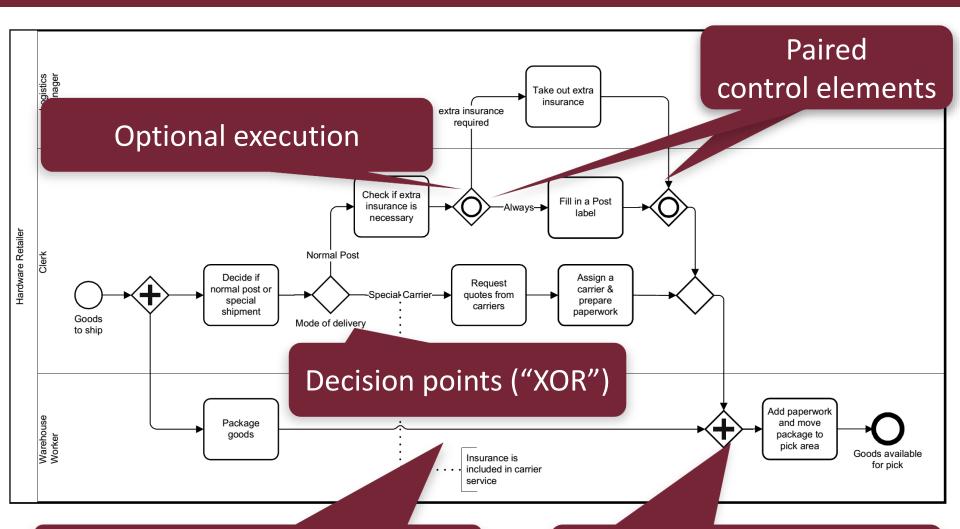


omg.org, BPMN 2.0 by Example





### Example: HW Delivery



Order of execution

"Parallel" (independent) execution ("AND")





#### What It's Based On

#### History

- Programs control structures
- Scheduling (eg. GANTT diagrams)
- Modelling manufacturing/office processes
- IDEF-0: 1980's, US AirForce
- Describing logistic processes
- System operator's/administrator's "runbook"

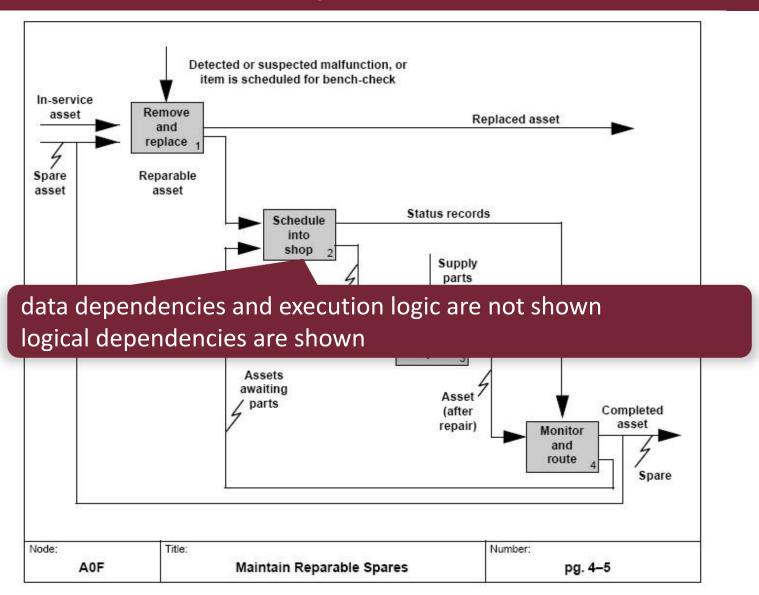
#### Common elements

- There are atomic steps
- Dependencies between them (time? data? order?)
- Decision points
- → general-purpose process modelling languages (eg. BPMN)





#### Example: IDEF-0

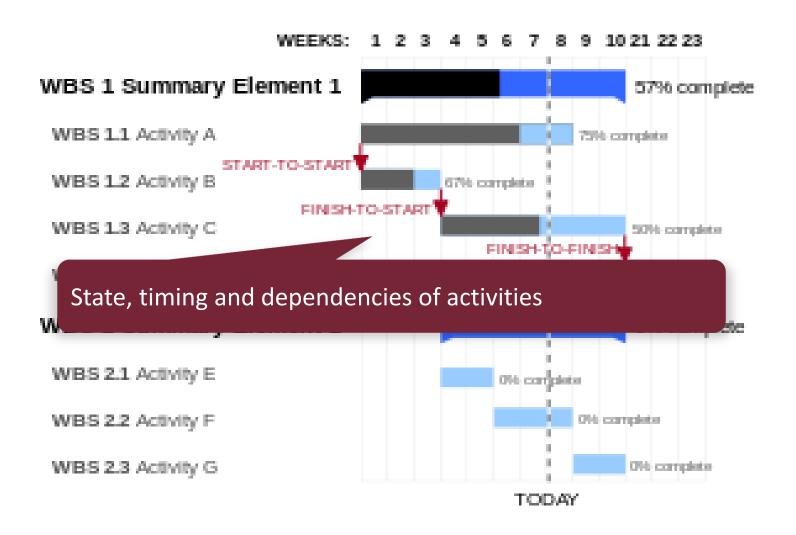


Defense Acquisition University - Systems Engineering Fundamentals. Defense Acquisition University Press, 2001





#### Example: GANTT





wikipedia.org



#### What It Uses

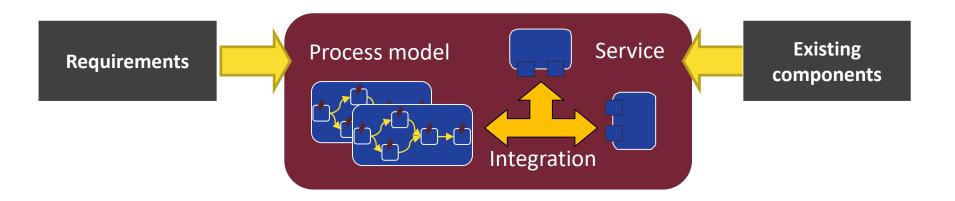
- Idea in system/software design:
  - Use existing elements
  - Describe how the complex system operates
- Basic elements can be many
  - webform validation, sending email, database operation, remote web service, human interaction, sending text message, drawing diagram, etc.





#### What is Derived from the Control Logic?

- Program code directly (C/C++, C#, Java, ...)
- Input of an executing environment
  - "Create this process for me"







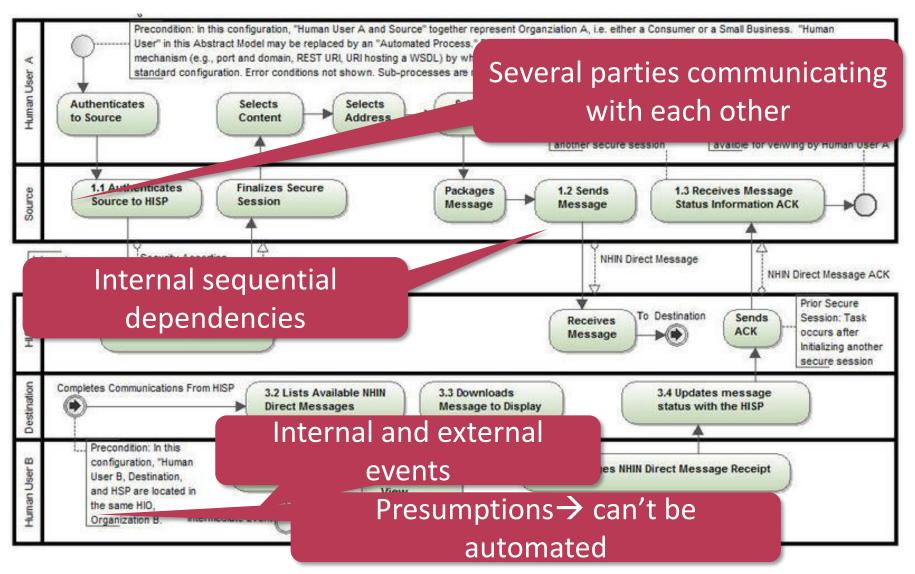
#### Other Uses of Process Models

- Operating IT systems
  - ITIL, UK Gov. initiative
- Protocol specification
  - Cooperation between elements of a complex system
  - Roles of components
- Designing executable processes
  - Order evaluation, credit assessment preparation, ...
- Data processing/analysing processes





### Example: Managing Health Data

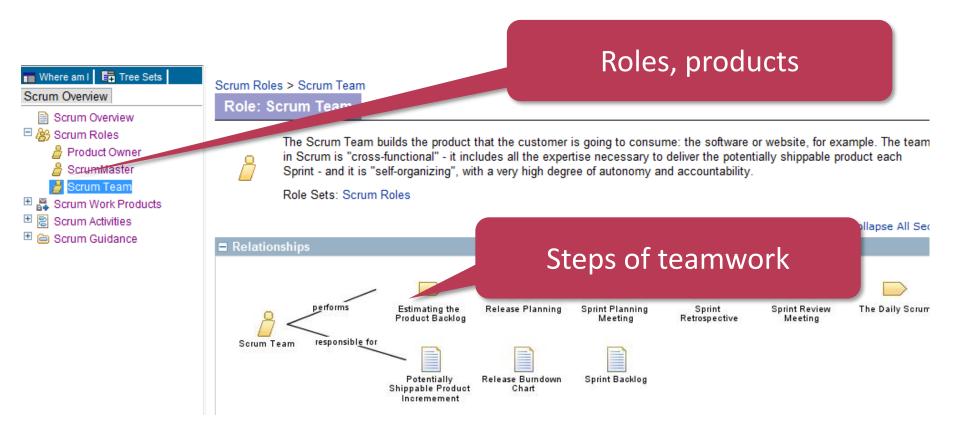


http://wiki.directproject.org/Abstract+Model+Examples





#### Example: Agile Development, as a Process



http://www.eclipse.org/epf/





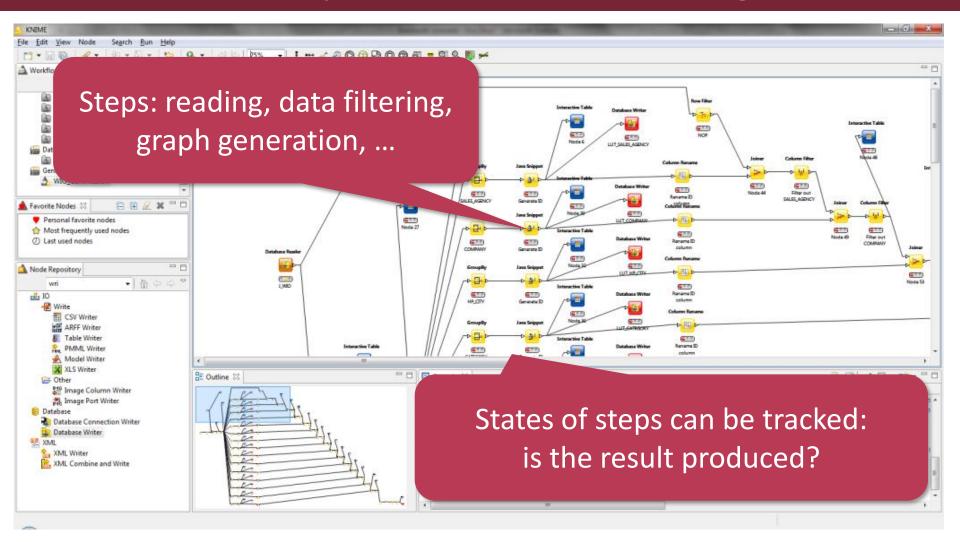
#### Examples

- Modelling banking processes
  - What activities are executed closing time?
  - Could the bank switch to transferring multiple times a day?
- Modelling manufacturing process
  - Optimal production scheduling: convert or fabricate?
  - O What happens in the factory?
  - (see the lecture on Simulation)
- Modelling business transactions
  - Where are recurring communication patterns?
  - Model based data processing





### **Example: Data Processing**







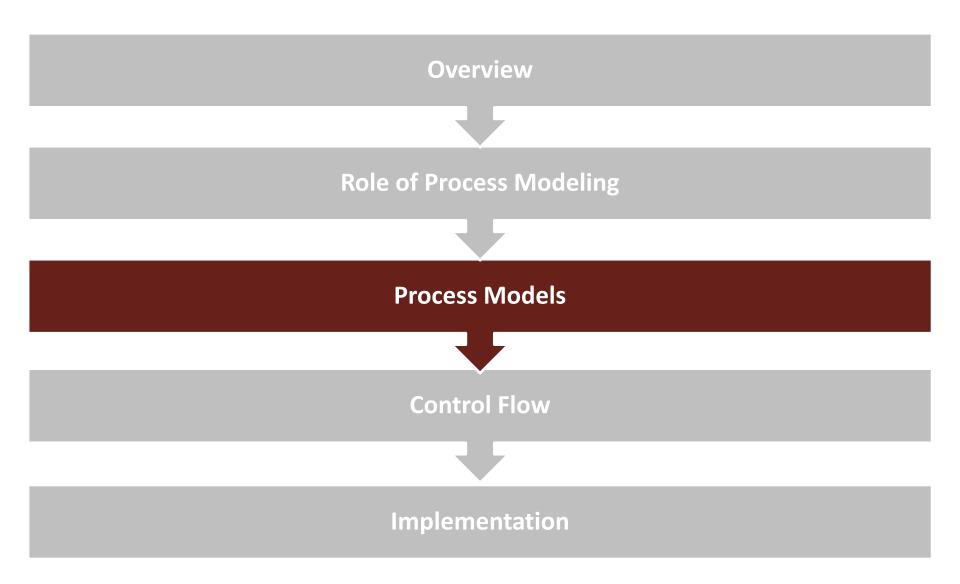
# Basic concepts of designing processes

- Process description languages
  - o BPMN, jPDL, XPDL, BPEL, UML AD, ...
- Process model
  - Control, dataflow
  - Data structures can be linked to a process model
  - Definition of steps to execute
  - Timings, resources
- Process (template) vs. process instance
  - E.g. "Booking tickets" as a process
  - "László Gönczy books a ticket to Lisbon" is an instance





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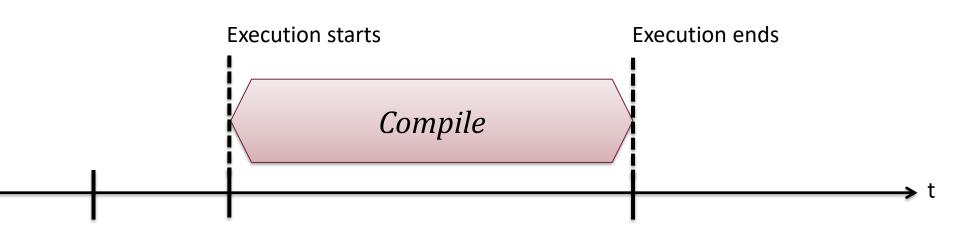






# **Elementary Activity (Task)**

Compile







# **Definition: Elementary Activity**

#### An **elementary activity** is an activity that

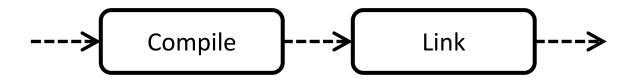
- has a positive temporal duration
- is not modelled beyond its start and end.

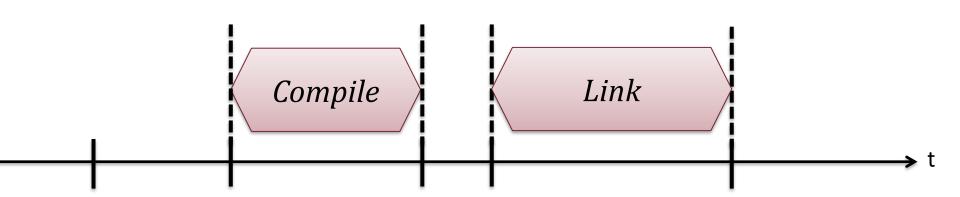
Compile





# Sequence, Control Flow



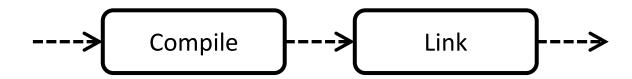






#### Definition: Sequence

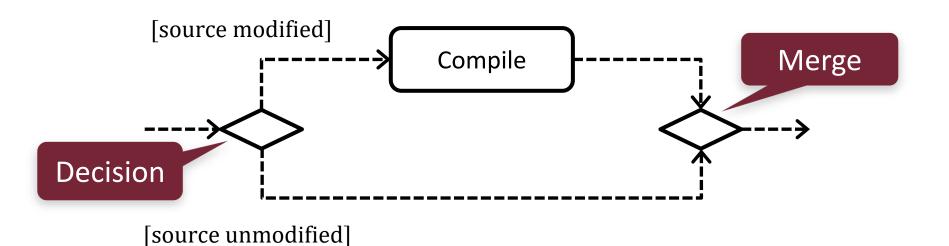
**Sequence** defines the order of execution of activities.







# Guard Condition, Branches



Semantics:

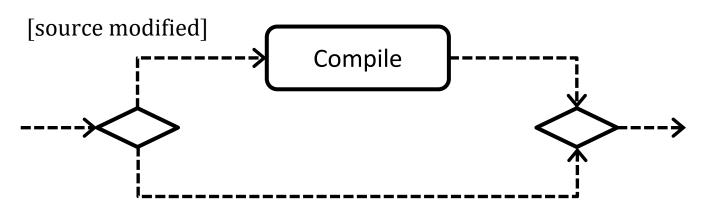
- Only one branch is executed
- Possibility of nondeterminism
  - Overlapping guard conditions
  - Or simply no guard conditions





#### **Definition: Control Element**

A **control element** is a junction of the process choosing one or more activities to execute.



[source unmodified]





#### Definition: Decision-Merge

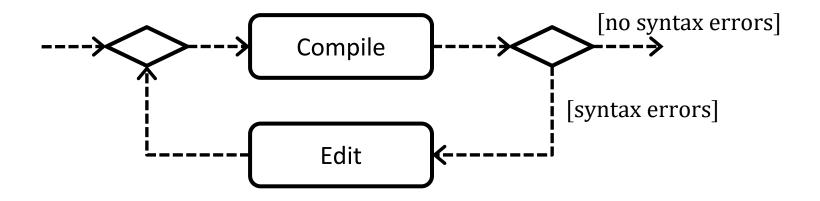
#### **Decision-Merge** is a control structure

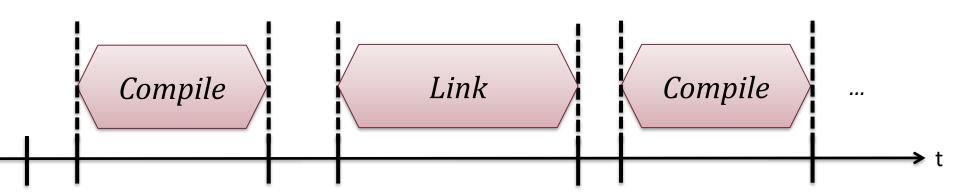
- consisting of a **Decision** and a **Merge** control element, where
- the decision node has at least two outputs from which we choose where to put the control token by evaluating the guard conditions,
- the chosen output (branch) can contain an arbitrary number of elements, and
- each branch leads to the merge node.
- Here we use branch as an exclusive or (XOR gate), which means that as a result
  of an evaluation only one of the decision branch is chosen.
- A branch can be multiple or binary, in the course we use binary decisions (two outputs).





# Loop







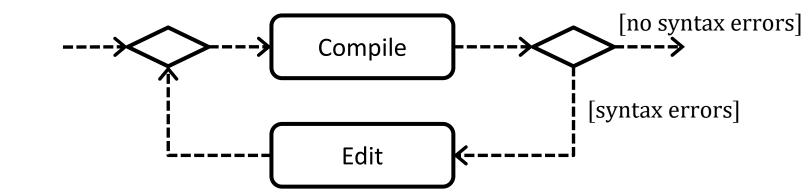


#### **Definition: Loop**

A **loop** is a control structure that defines multiple execution. The loop

- consists of a Merge and a Decision element, where
- one of the branches of the decision node leads back to the merge node.

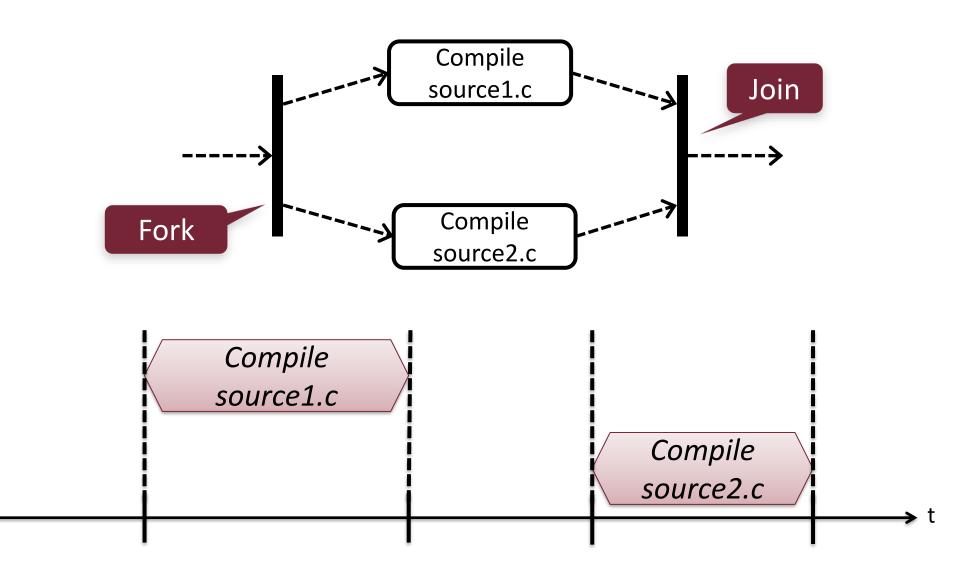
Note: this corresponds to a repeat - until loop







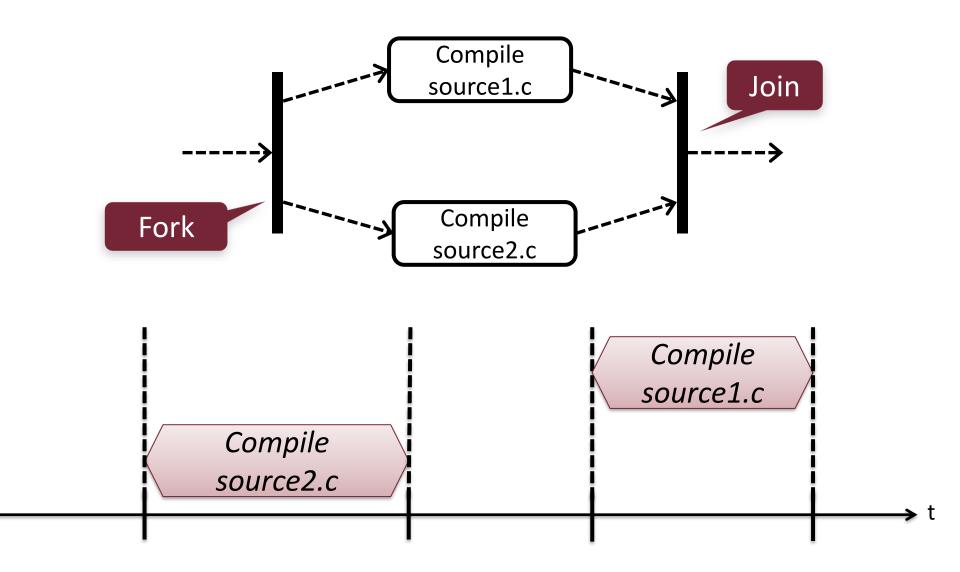
# Fork / Join







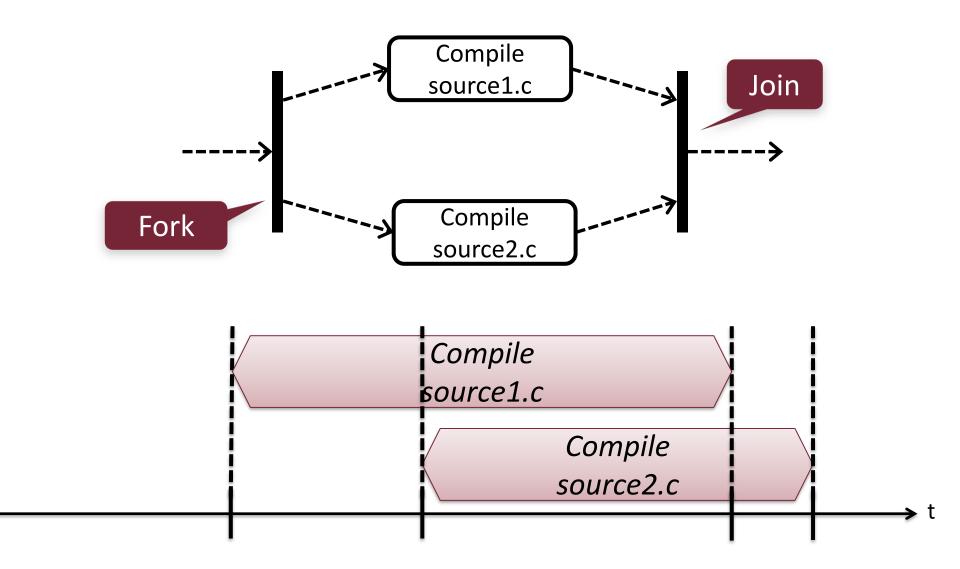
# Fork / Join







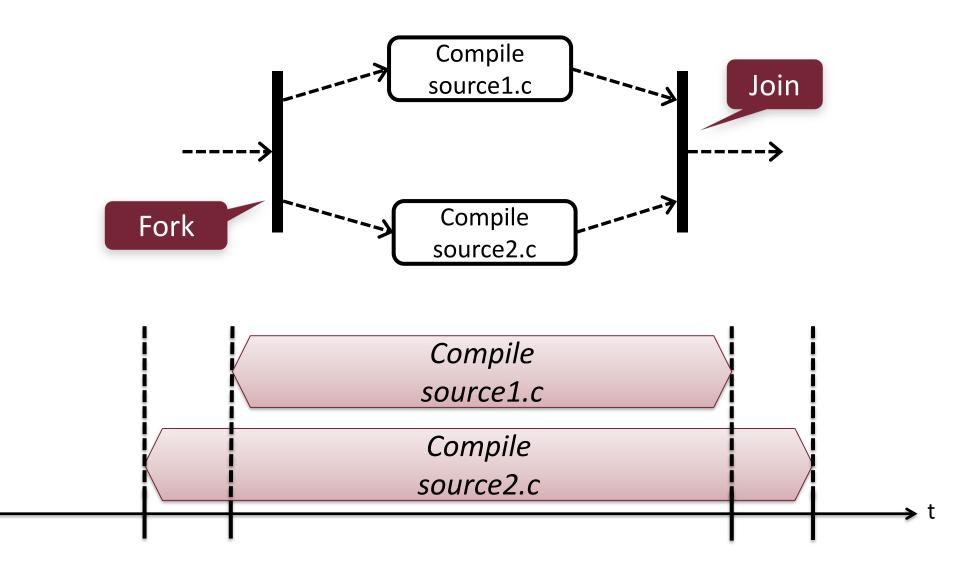
# Fork / Join







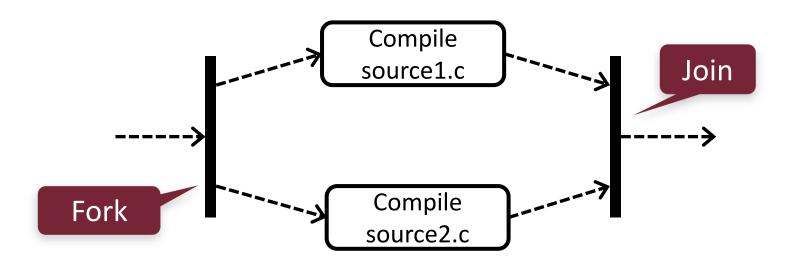
# Fork / Join







### Fork / Join



- Semantics:
  - Execution sequence is not specified
  - Parallel/ overlapped execution is possible
- See: Computer architectures course





#### **Definition: Parallel Execution**

#### Parallel execution (Fork-Join)

- contains a Fork and a Join control element, where
- the fork can have an arbitrary number of outputs (branches).
- branches can be executed concurrently,
- all branches lead to the join node, and
- parallel execution ends, when all branches terminate.

Two activities are **concurrent** if the order of their execution is not controlled.

- Note: we are going to work with two parallel branches.
- NOT equivalent to Decision-Merge!





# Flow Begin / Flow End







# Definition: Flow Begin/End

Process starts with a Flow Begin control element and ends with a Flow End element.

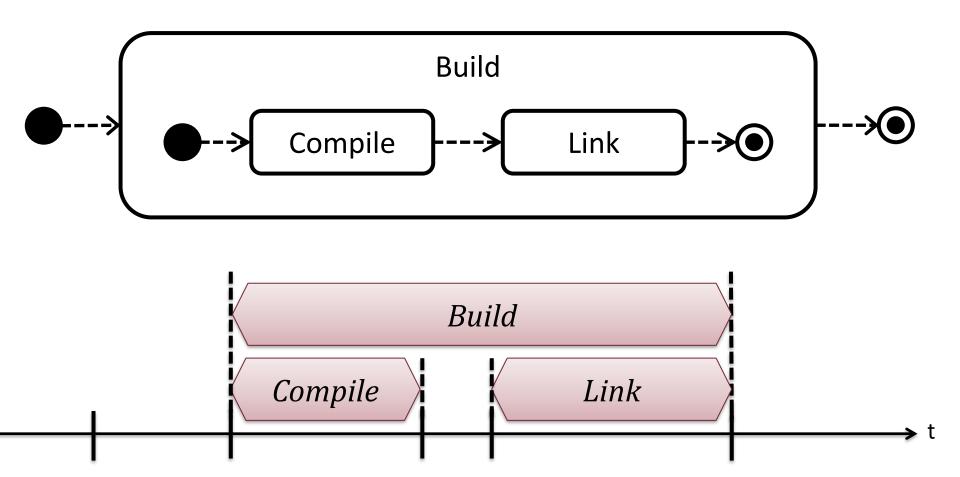
- The begin node is the first node of the process, with exactly one output.
- The end node is the last node of the process with exactly one input.

Note: we do not model what causes the process to start





# Hierarchy







### Definition: Hierarchy

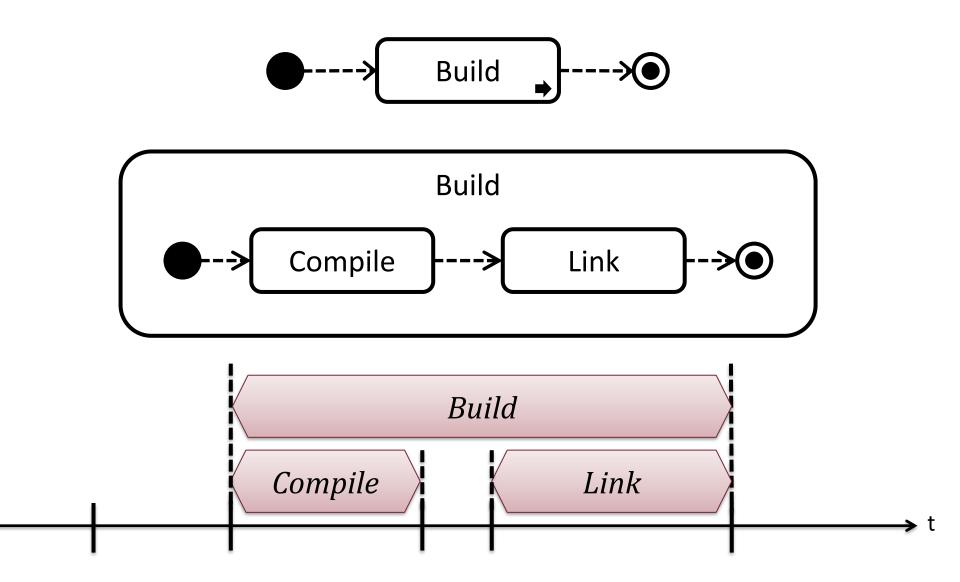
#### Hierarchical process model:

 Instead of an atomic activity it can contain a submodel described by a process model (hierarchical refinement).





# References / Calls



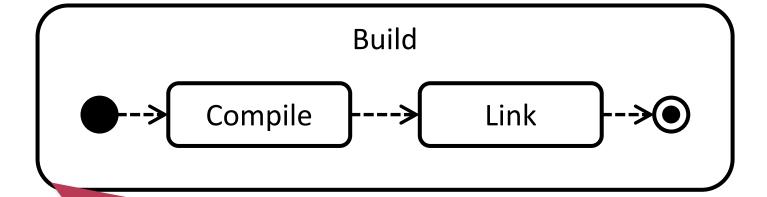




#### References / Calle

Elementary task?
Actually a subprocess!





Can be embedded into the main process if the refinement is valid:

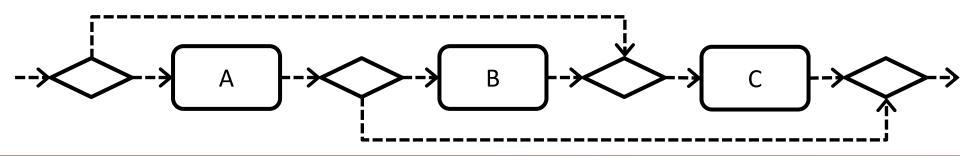
- The steps combined produce the same thing as the process
- No unhandled case on caller level (Input/output consistency)





#### Well Structured Process

- Building from control blocks
  - One entry point, one exit
  - Sequence, decision-merge and fork-join blocks, loop, elementary activity, (empty control section)
- Analogy: structured programming
  - Control structures instead of goto
- Example of a non-well-structured process

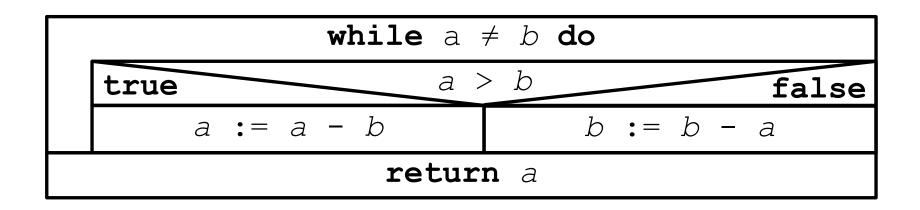






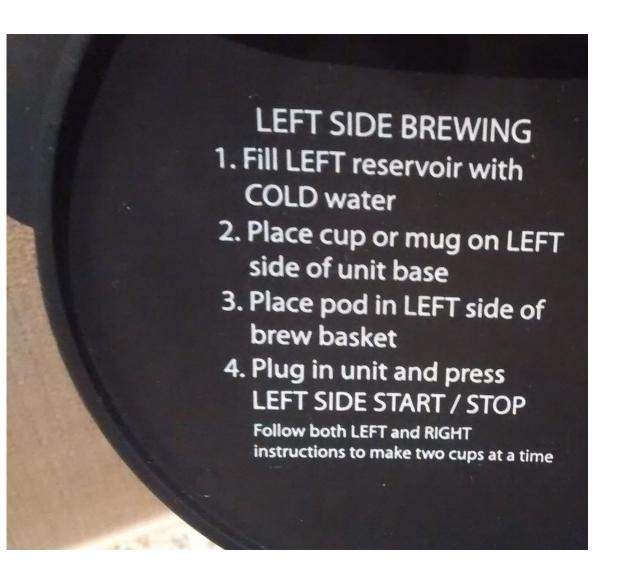
#### Well Structured Process

- Some formalisms enforce it
  - o eg. BPEL (business process over web services)
  - o eg. Structogram (Nassi-Shneiderman)
  - programming languages without goto, break, etc.



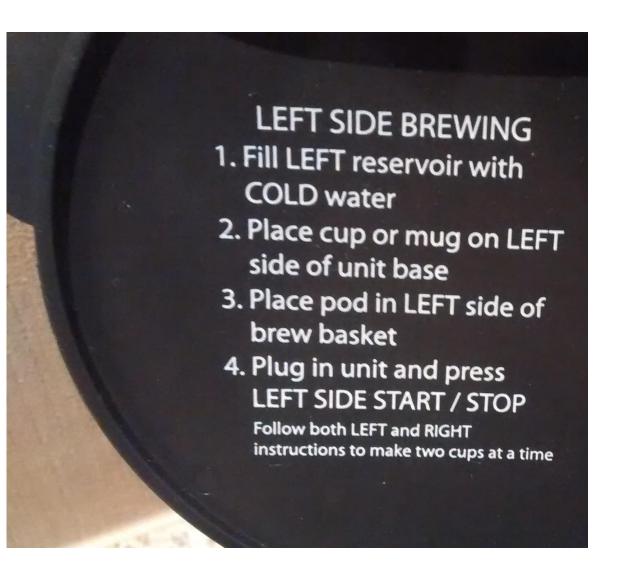


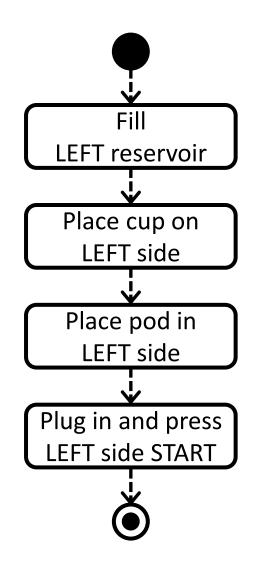






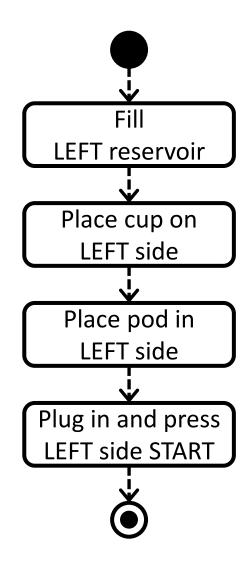






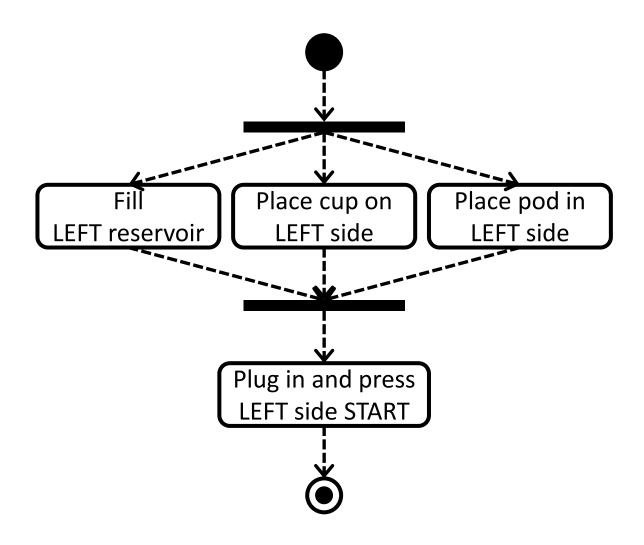












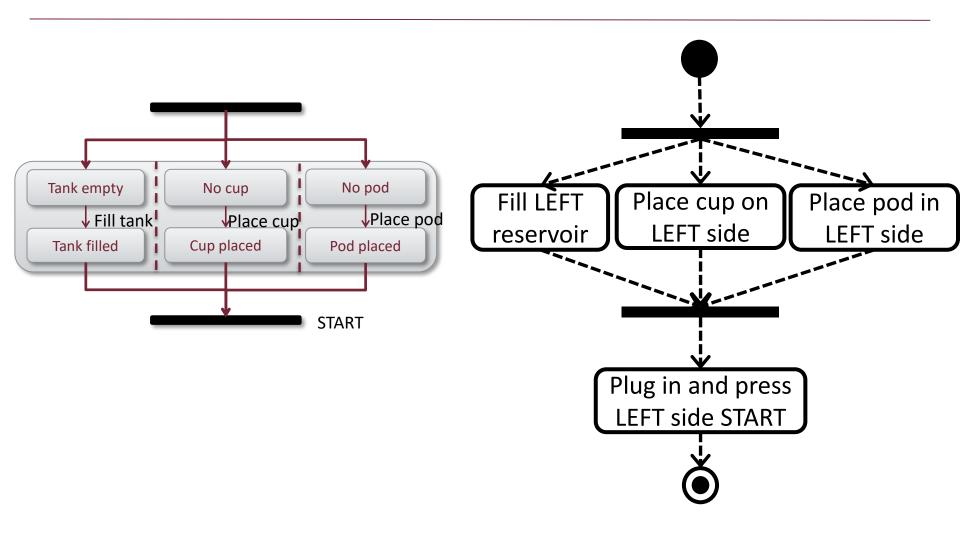




#### Comparison

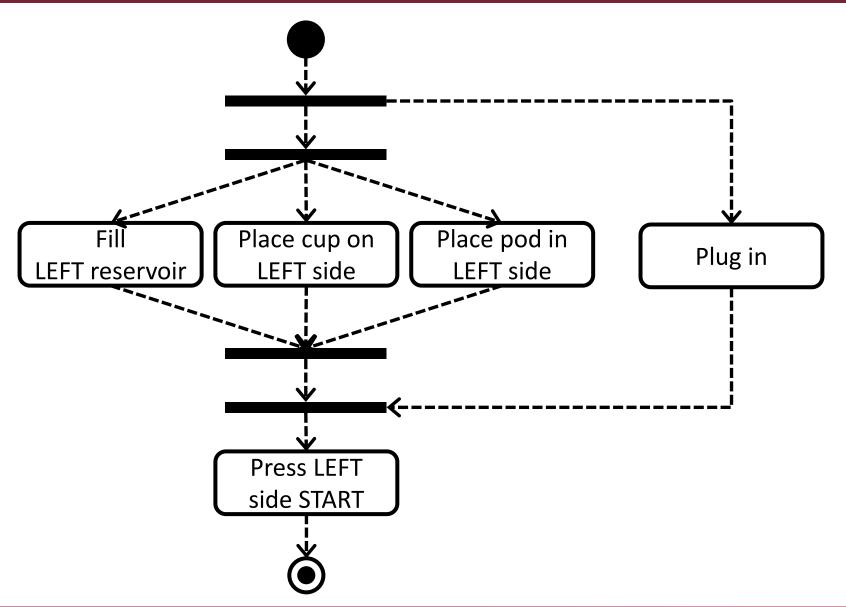
State machine

Process



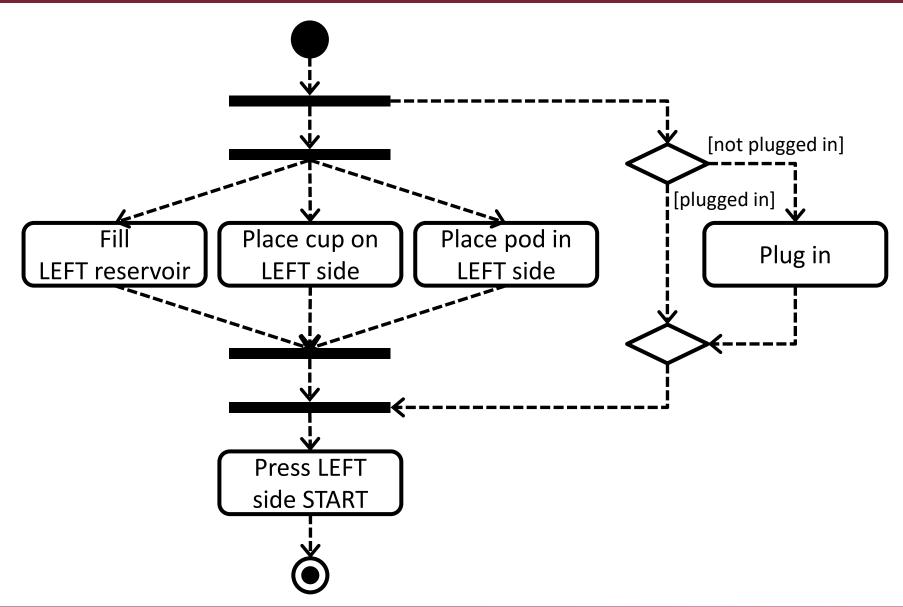






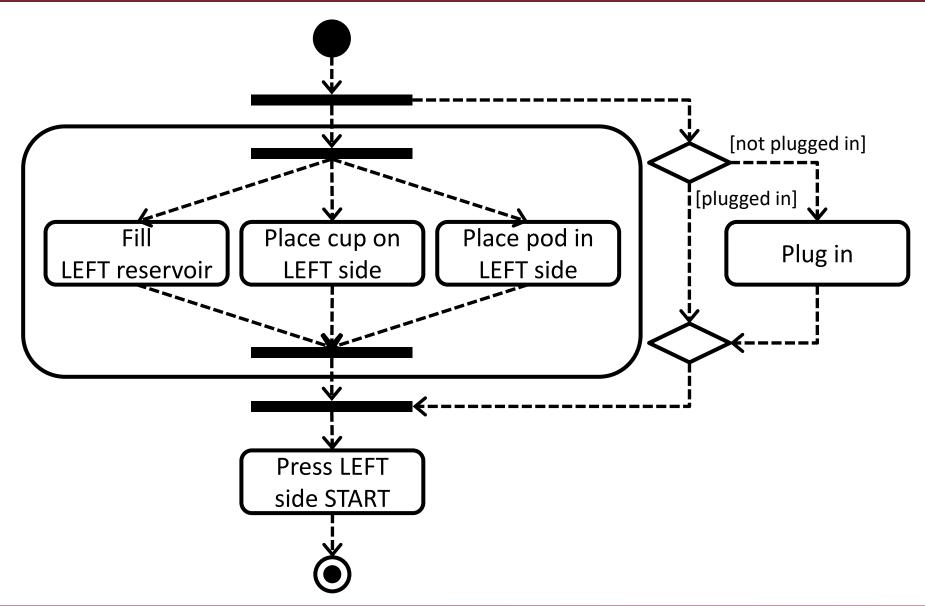






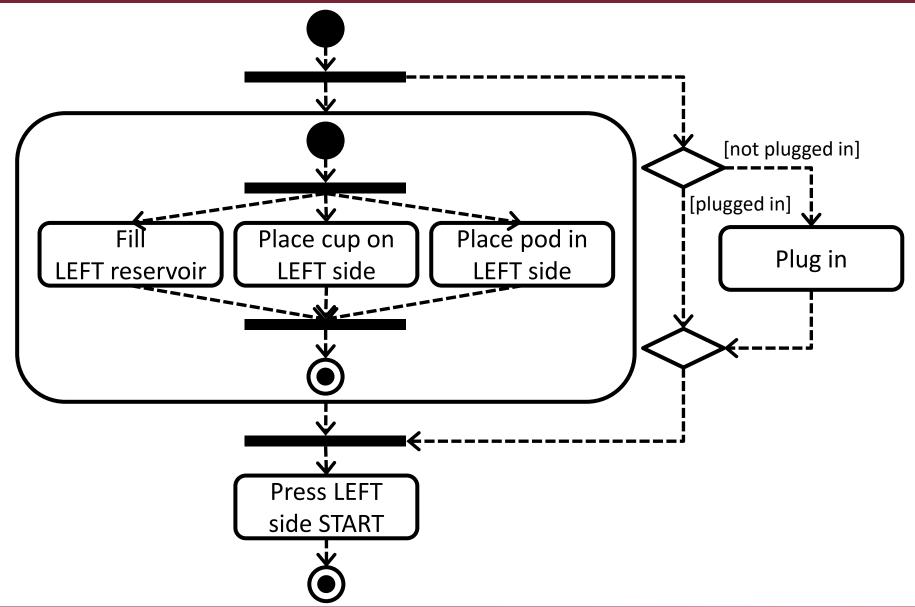






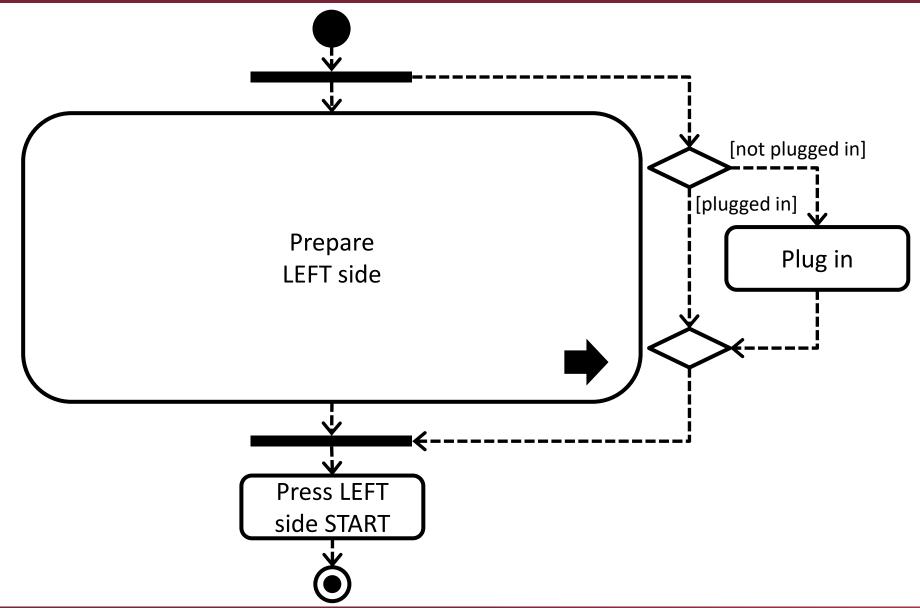






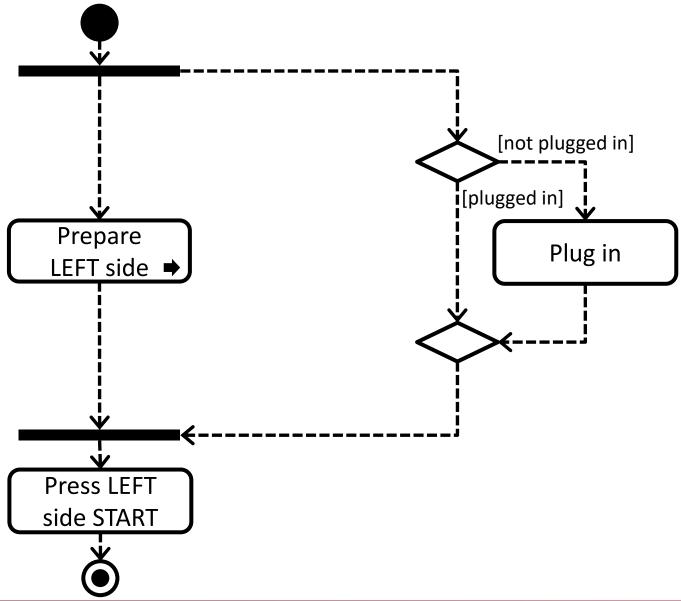






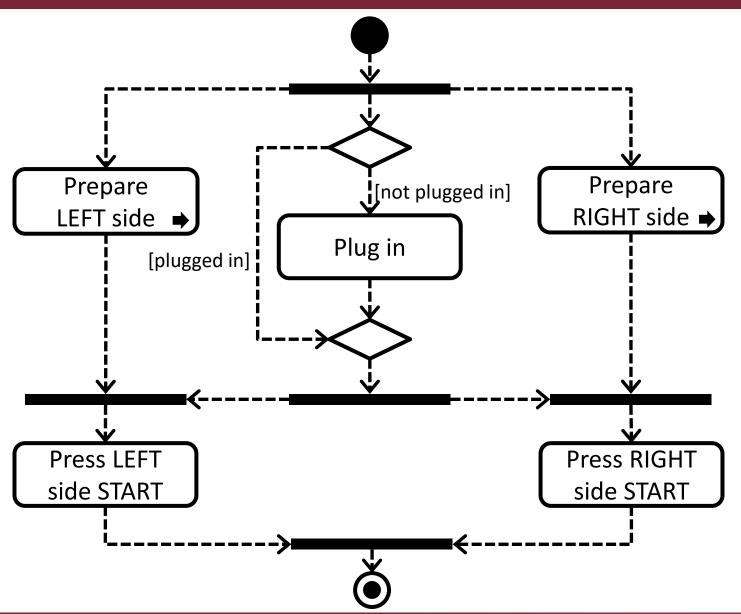






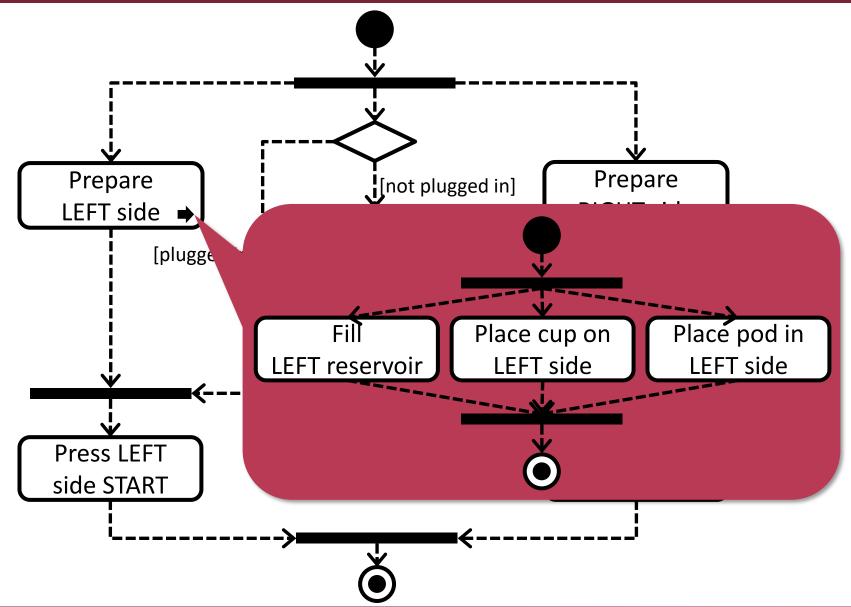
















# Modeling based on different aspects







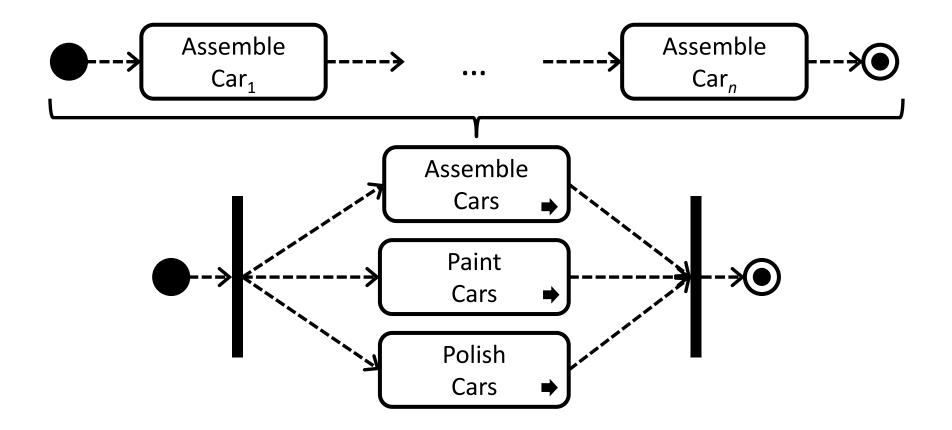
# What happens to a car?







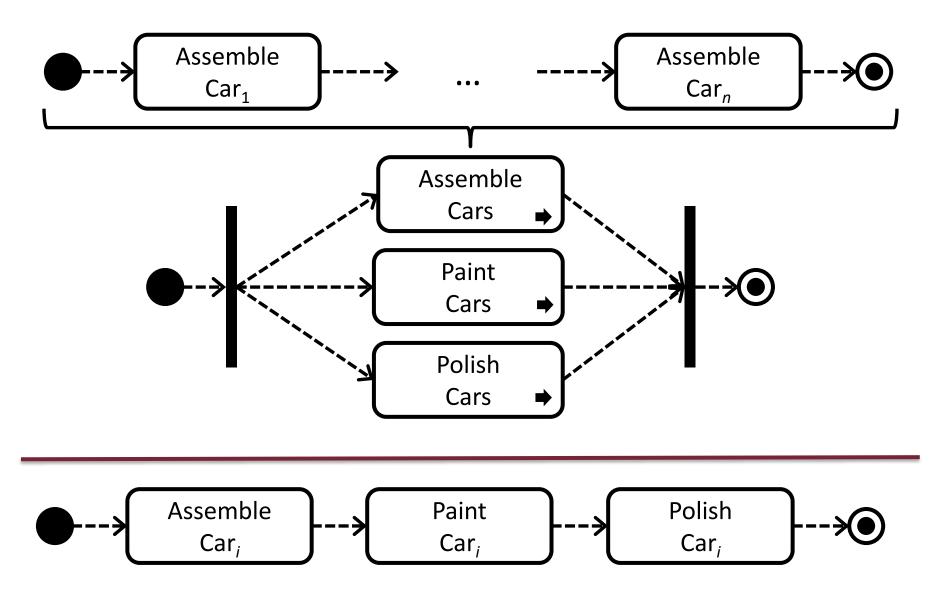
### What happens on the production line?







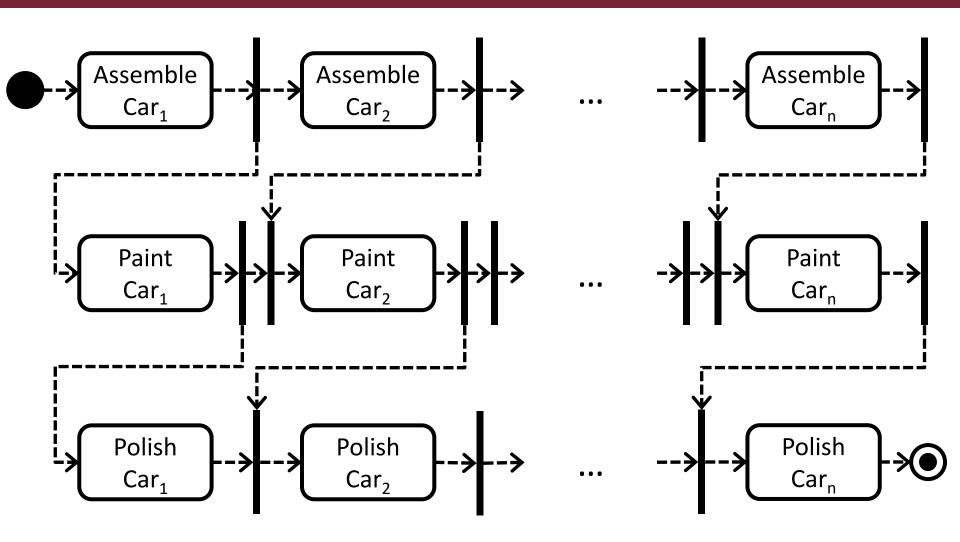
### Modeling based on different aspects







#### Joint View

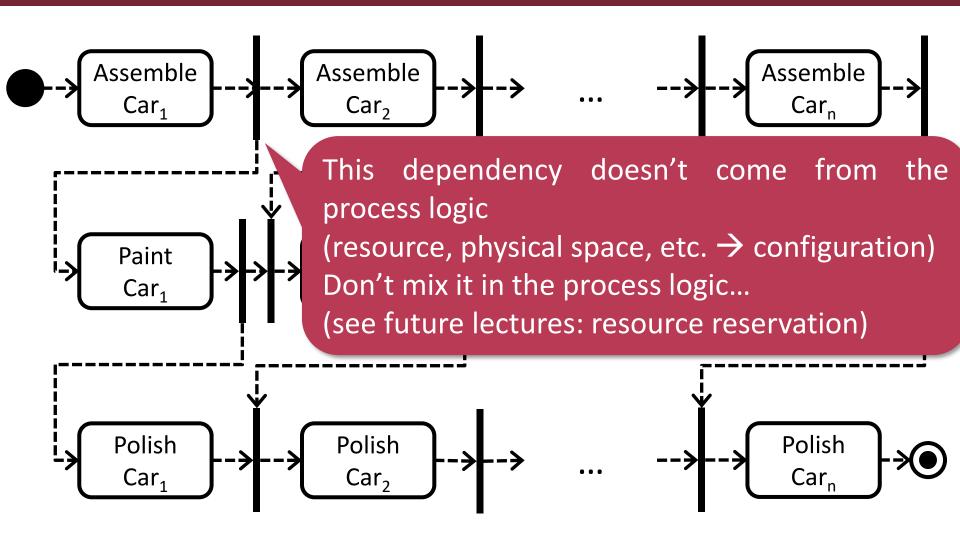


Includes everything but not very practical





#### **Joint View**



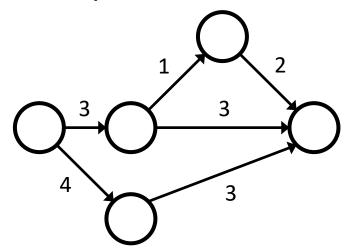
Includes everything but not very practical





#### Joint View

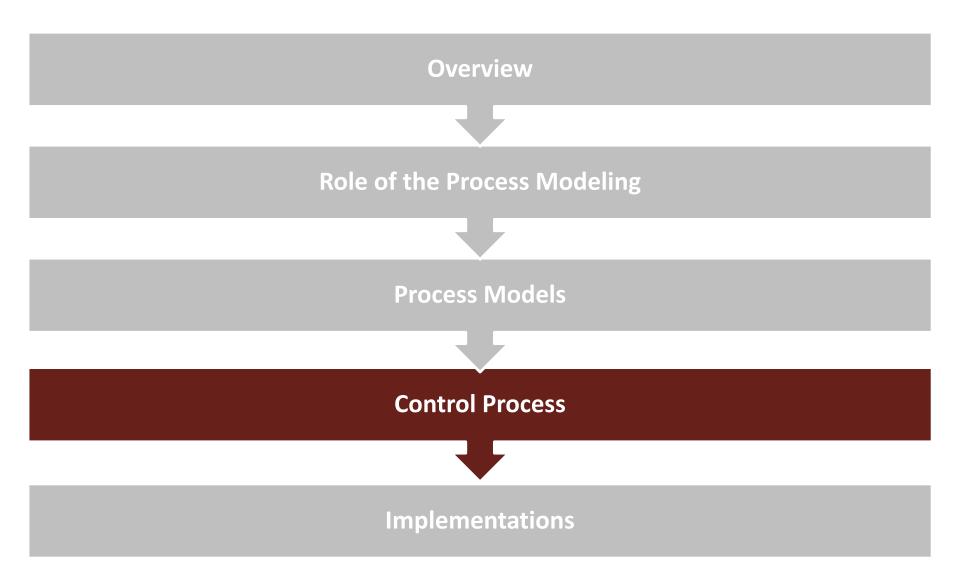
- 2D fork-join net isn't very practical
  - Different processes for different aspects (car's and machine's lifetime)
- Multiple fork-join pairs in a compact way?
  - → PERT chart
    - Program Evaluation and Review Technique
      - For analyzing execution time
      - (No branching here)







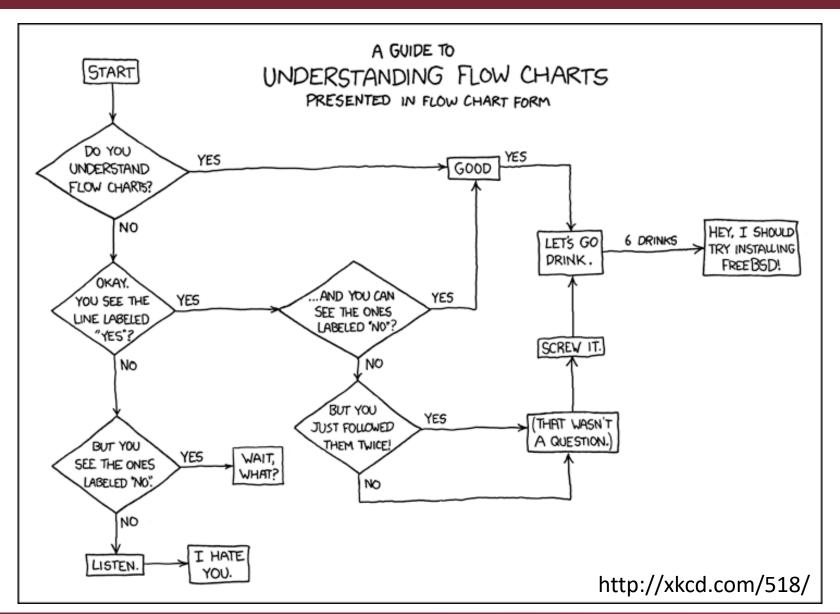
#### Table of contents







#### **Flowchart**



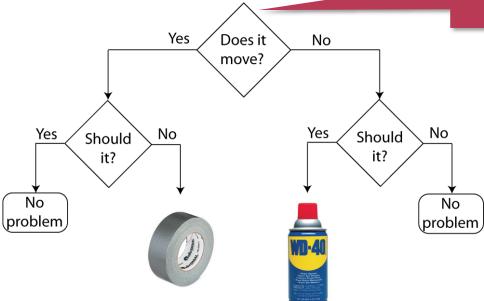




#### **Flowchart**

- Flowchart / decision diagram
  - Describes a train of thought for decision making
    - Leads to a conclusion
  - No temporal sequence
- Special case: decision tree

Describing decision points and their order is difficult for real problems

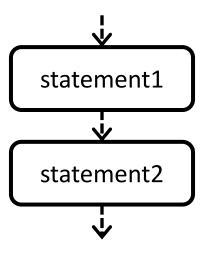






#### **Control Flow**

- <statement1>
- <statement2>

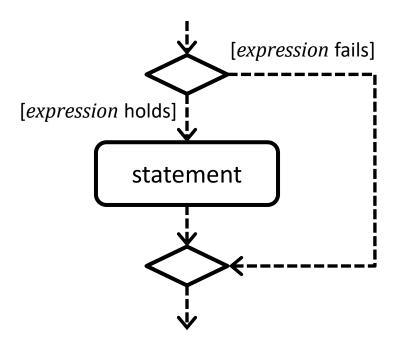






#### **Control Flow**

if (<expression>)
 <statement>





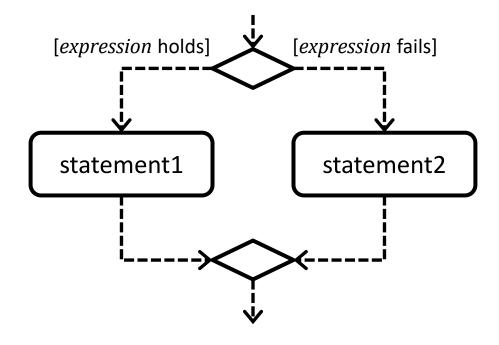


#### **Control Flow**

if (<expression>)
 <statement1>

else

<statement2>

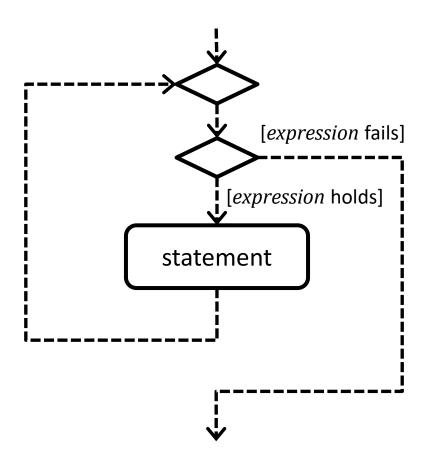






## **Control Flow**

while (<expression>)
 <statement>

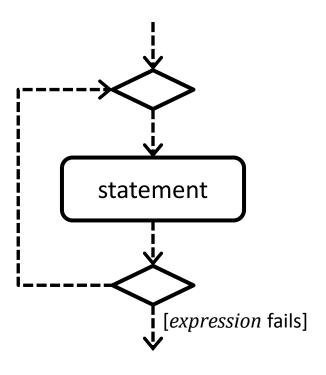






# Control Flow

```
do
     <statement>
while (<expression>)
```





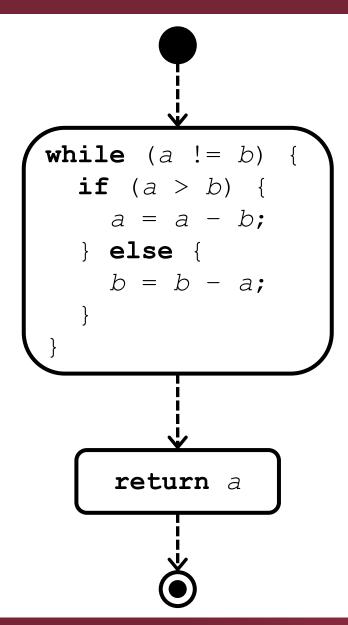


```
while (a != b) {
  if (a > b) {
    a = a - b;
  } else {
    b = b - a;
return a;
```



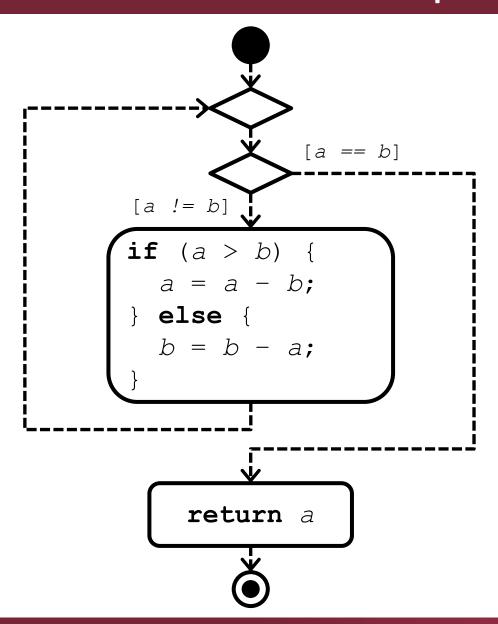
```
while (a != b) {
  if (a > b) {
  a = a - b;
  } else {
   b = b - a;
return a;
```





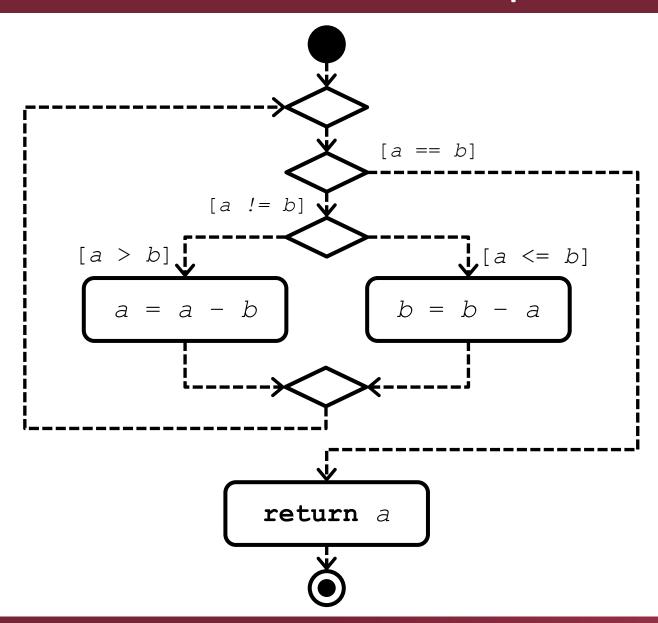








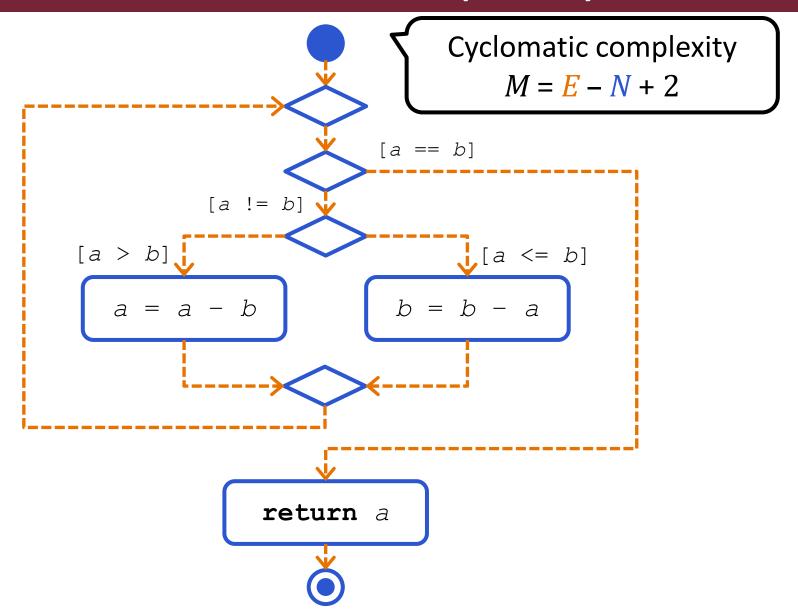








## **Control Flow - Complexity**







#### Control Flow - Recursion

```
int fact(int n) {
   return
   (n == 0) ? 1 : n * fact(n - 1);
}
```





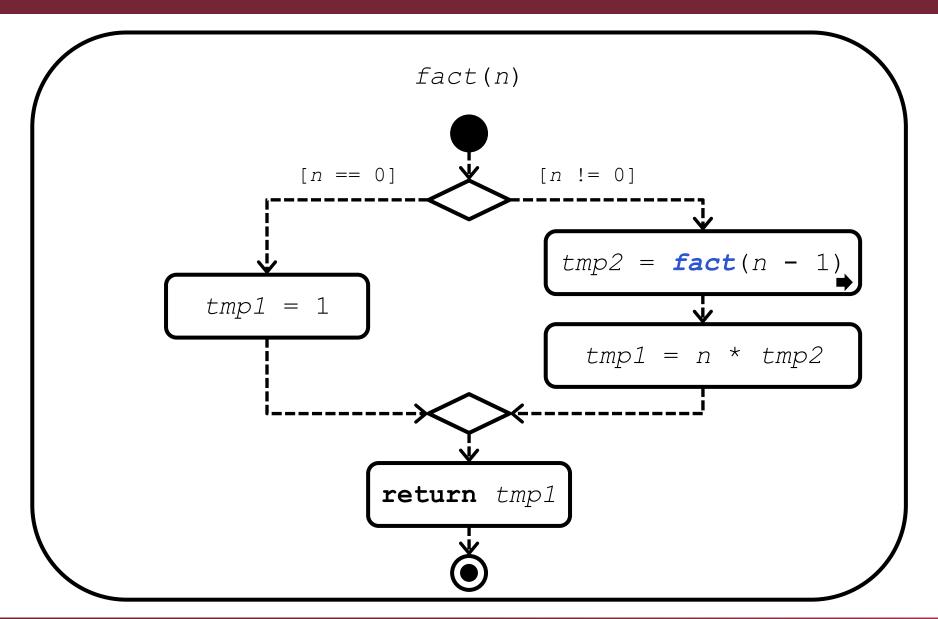
#### **Control Flow - Recursion**

```
int fact(int n) {
  int tmp1;
  if (n == 0)
    tmp1 = 1;
  } else {
    int tmp2 = fact(n - 1);
    tmp1 = n * tmp2;
  return tmp1;
```





## Control Flow - Recursion







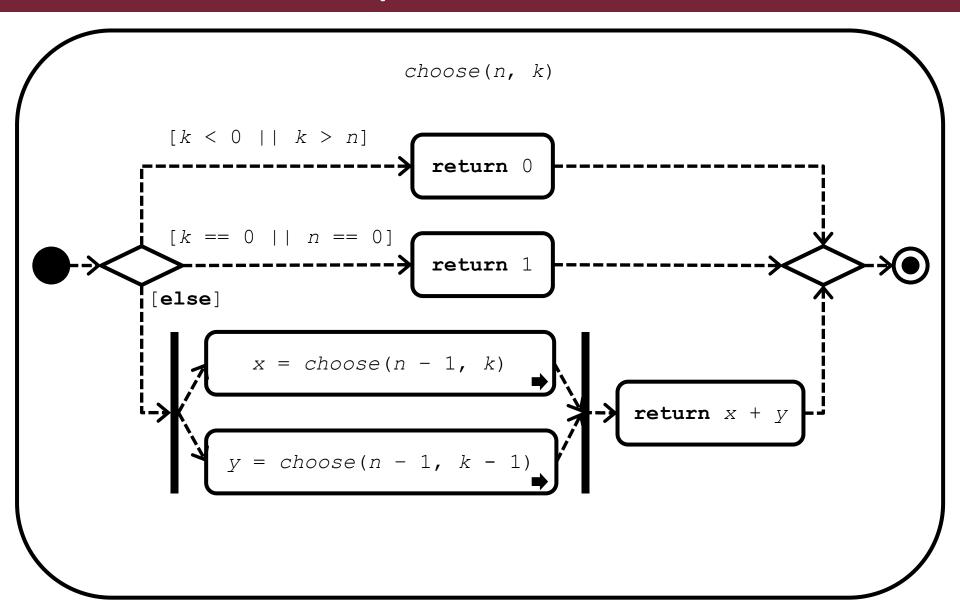
## Example: *n* choose *k*

```
int choose(int n, int k) {
  if (k < 0 | | k > n) {
    return 0;
  } else if (k == 0 \&\& n == 0)
    return 1;
  } else {
    int x = spawn choose(n - 1, k);
    int y = spawn choose(n - 1, k - 1);
    sync;
    return x + y;
                               \binom{n}{k} = \binom{n-1}{k} + \binom{n-1}{k-1}
```





## Example: *n* choose *k*







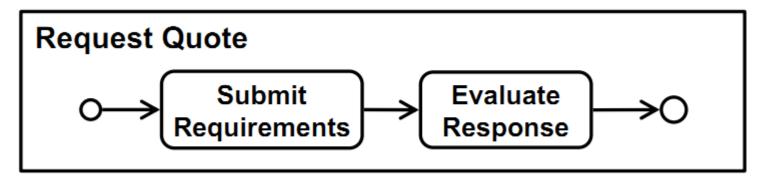
# EXECUTION OF BUSINESS PROCESSES



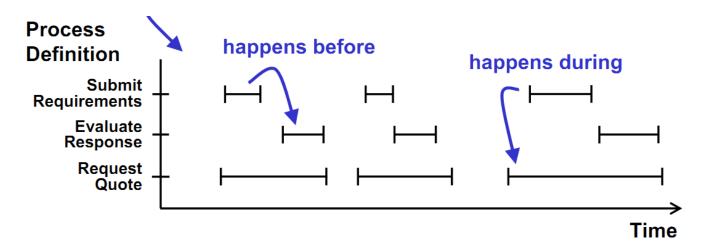


#### The Semantics of Processes

The modelling perspective



The intended execution

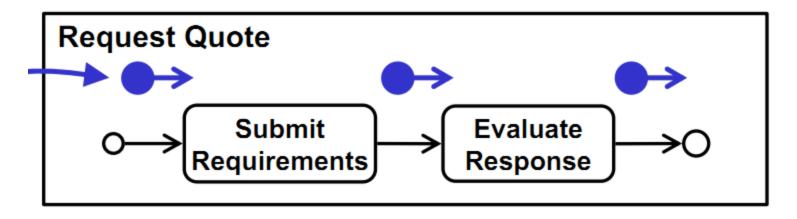




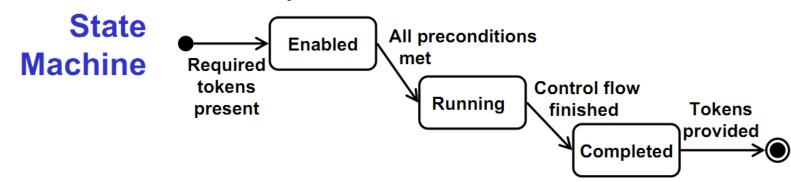


#### **Process Execution**

Token flow



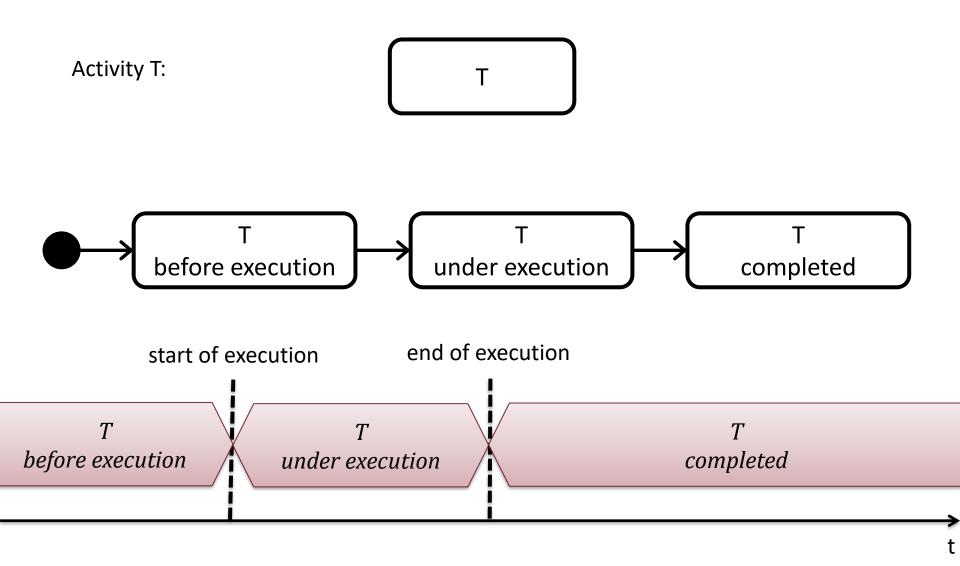
The states of the process







# States of an Elementary Activity

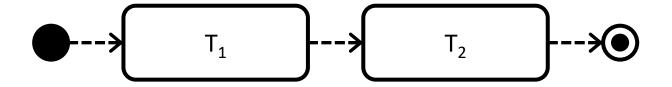


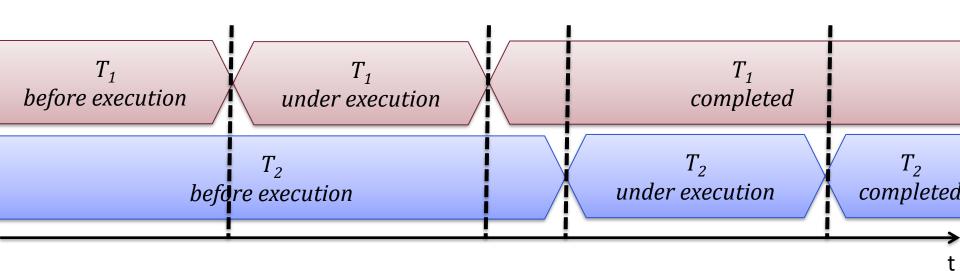




## States of a Process

Process T=  $T_1$ ; $T_2$ 







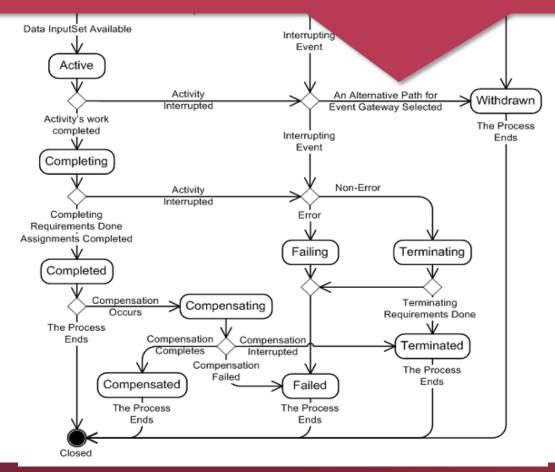


# Symplified State Machine of an Activity

Managed by the executing environment

Inactive

- Standard describes the states and transitions
- Not the same as the states of the executing resources/applications

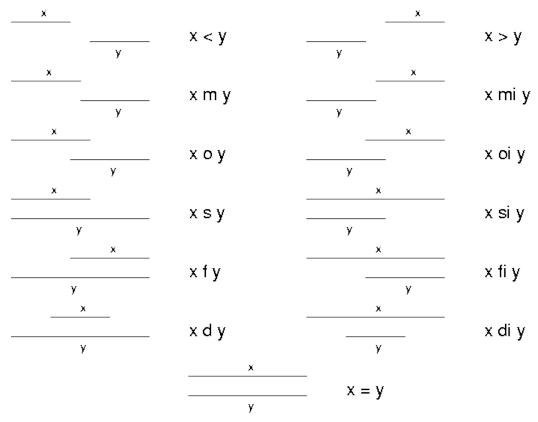






# Background: Mathematical Model

- Allen's interval algebra (1983)
  - Used among others at testing, 13 (6 + 1 + 6) cases



James F. Allen: Maintaining knowledge about temporal intervals.

In: Communications of the ACM. 26 November 1983. ACM Press. pp. 832–843, ISSN 0001-0782

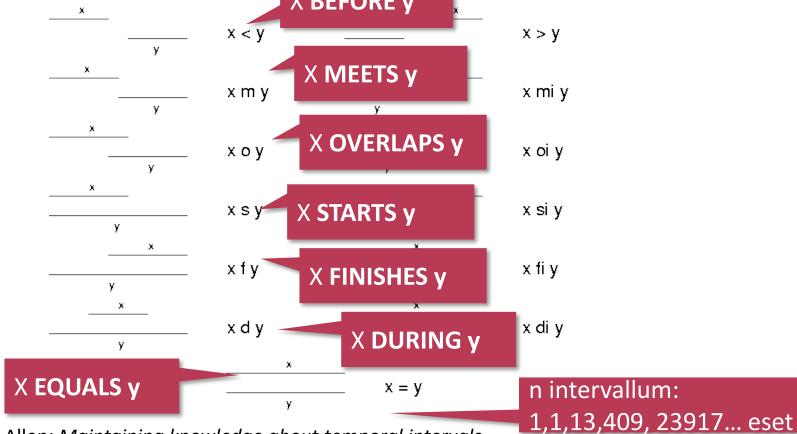




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#### What Can Be Checked?

- The execution is not based on the given process
  - Satisfaction of assumptions (order, independence)?
- What is the "process" behind system/execution?
  - Workflow mining
- If e.g. the execution environment is permissive
  - Steps can be skipped, ....
  - O Are the requirements still satisfied?
- Tooling: formal methods
  - (Temporal )Logics, Petri nets, model checking, etc.



