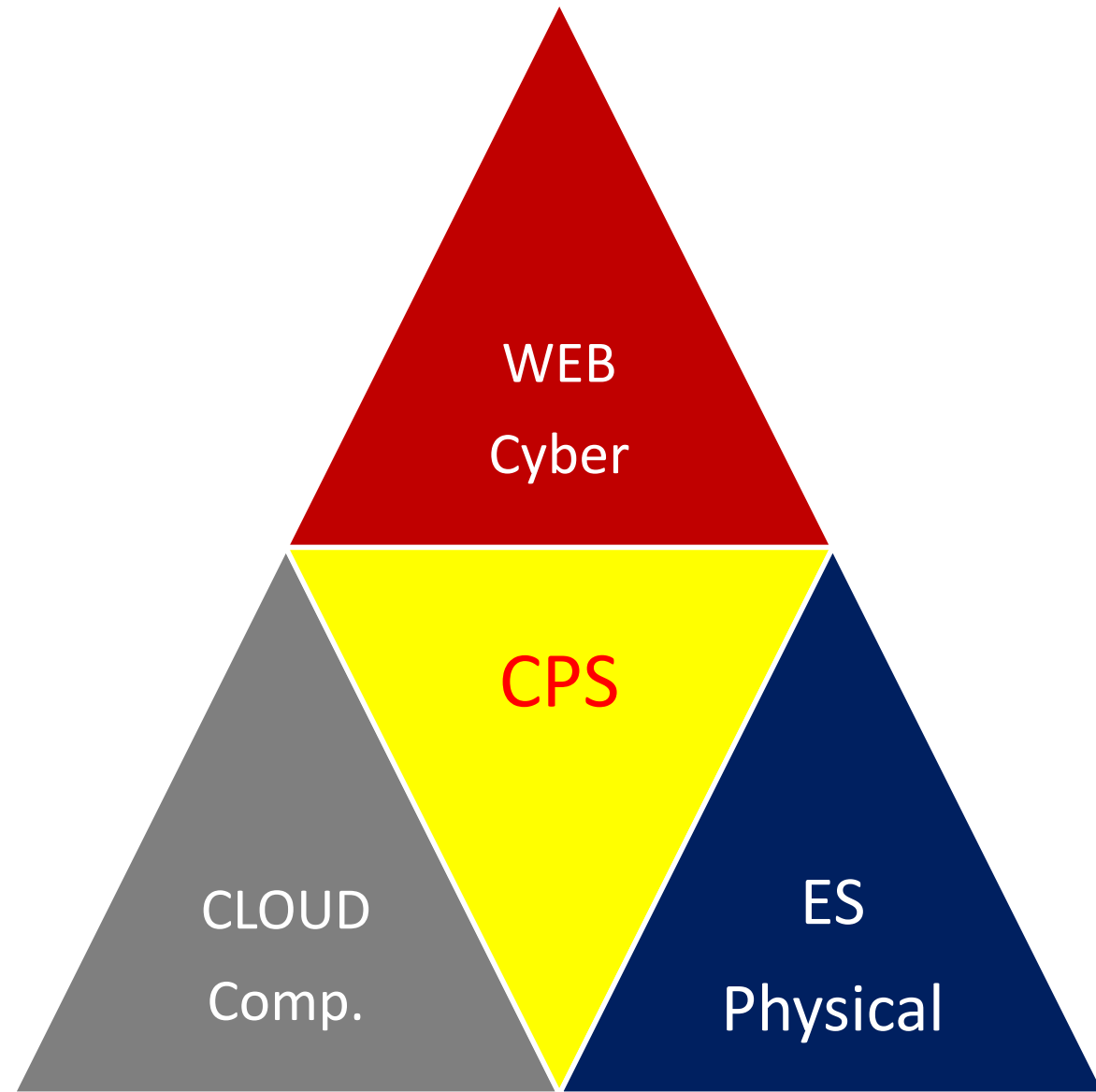


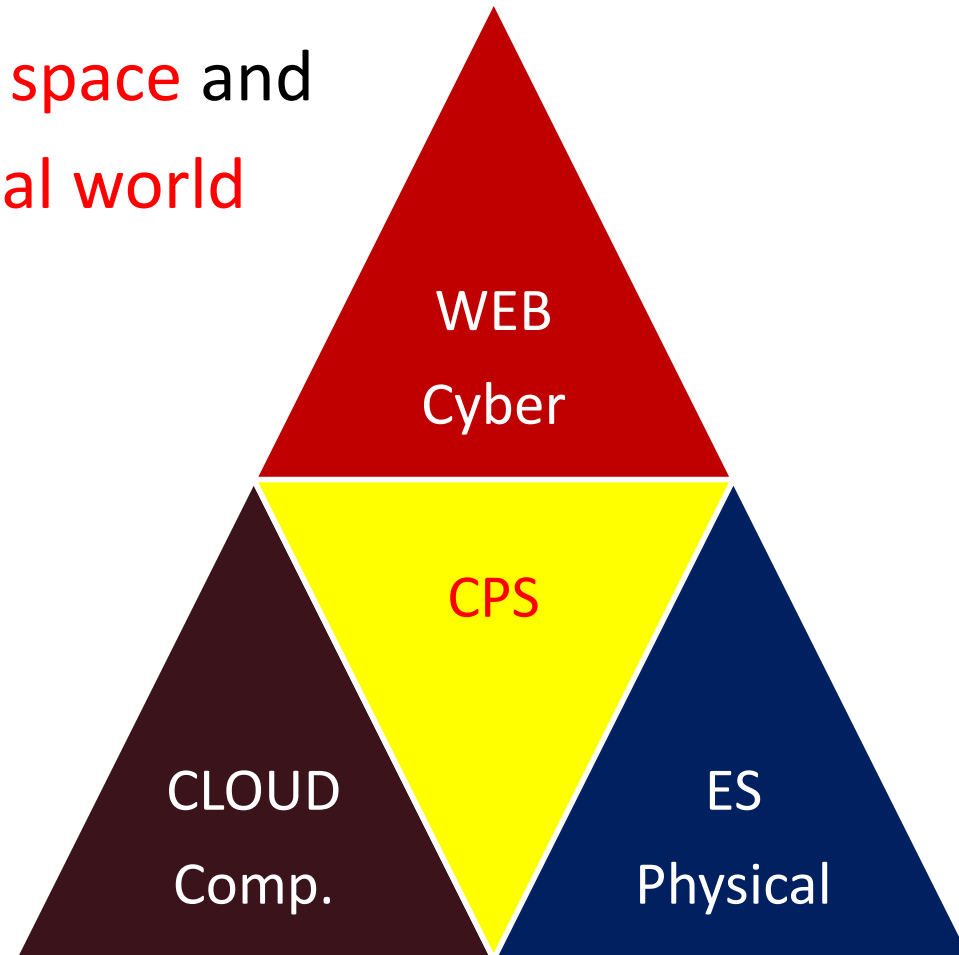
The design triangle

1



The new era: dynamic CPS (?)

- Unlimited intelligence by the synergy of
 - intelligence in the cyber space and
 - ES interfacing the physical world



Reusable sensors

Multiple, on-demand algorithms

Intention



DSN 2013

The 43rd Annual IEEE/IFIP International
Conference on Dependable Systems and
Networks

24-27th June 2013, Budapest

Reality: record flood



- A lot of e-mails:
 - Is it safe to come to Budapest?
- Fortunately: no request for
“Life west under your *conference* seat”

Solution

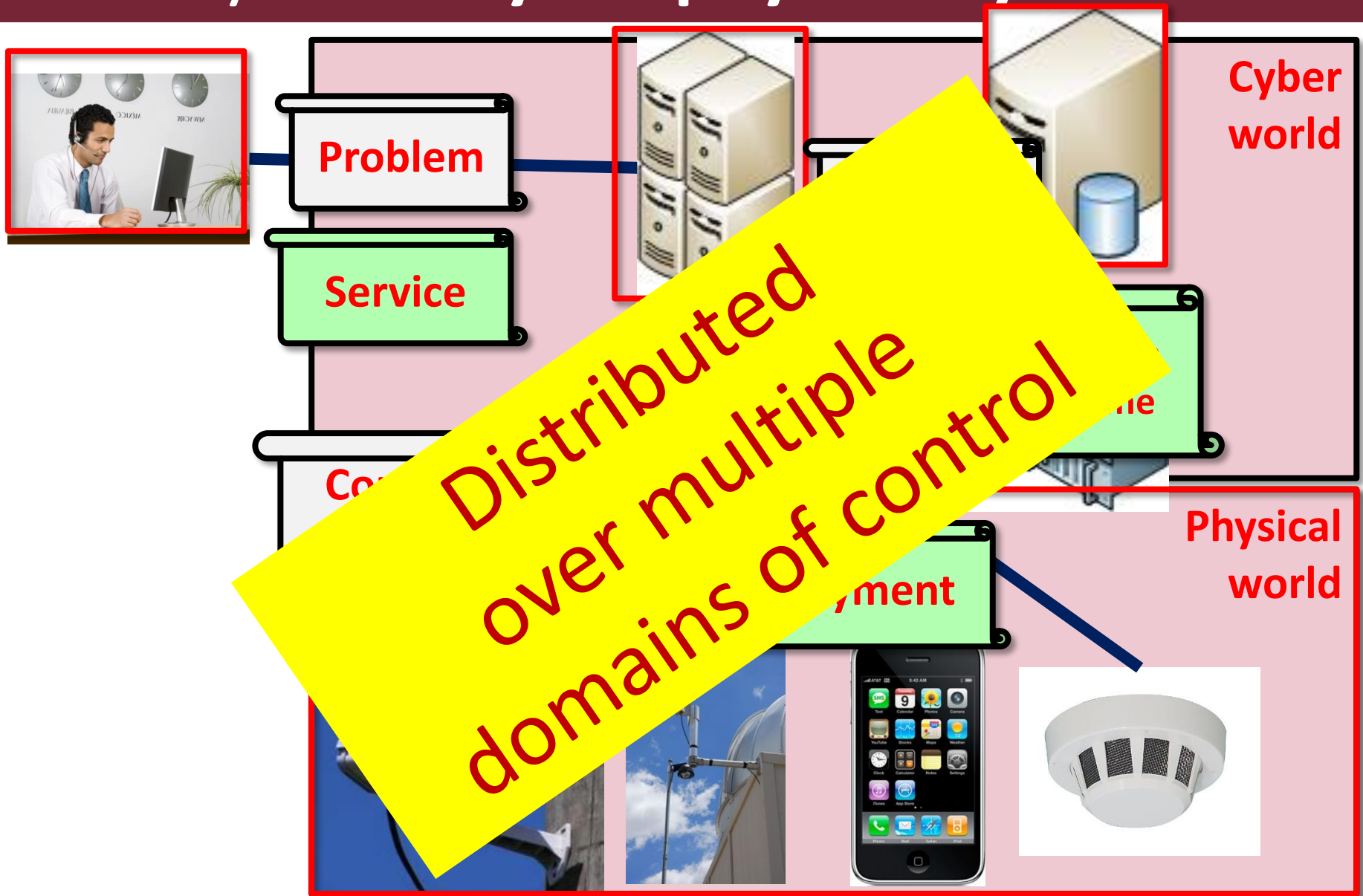
Example

Cameras on riverside

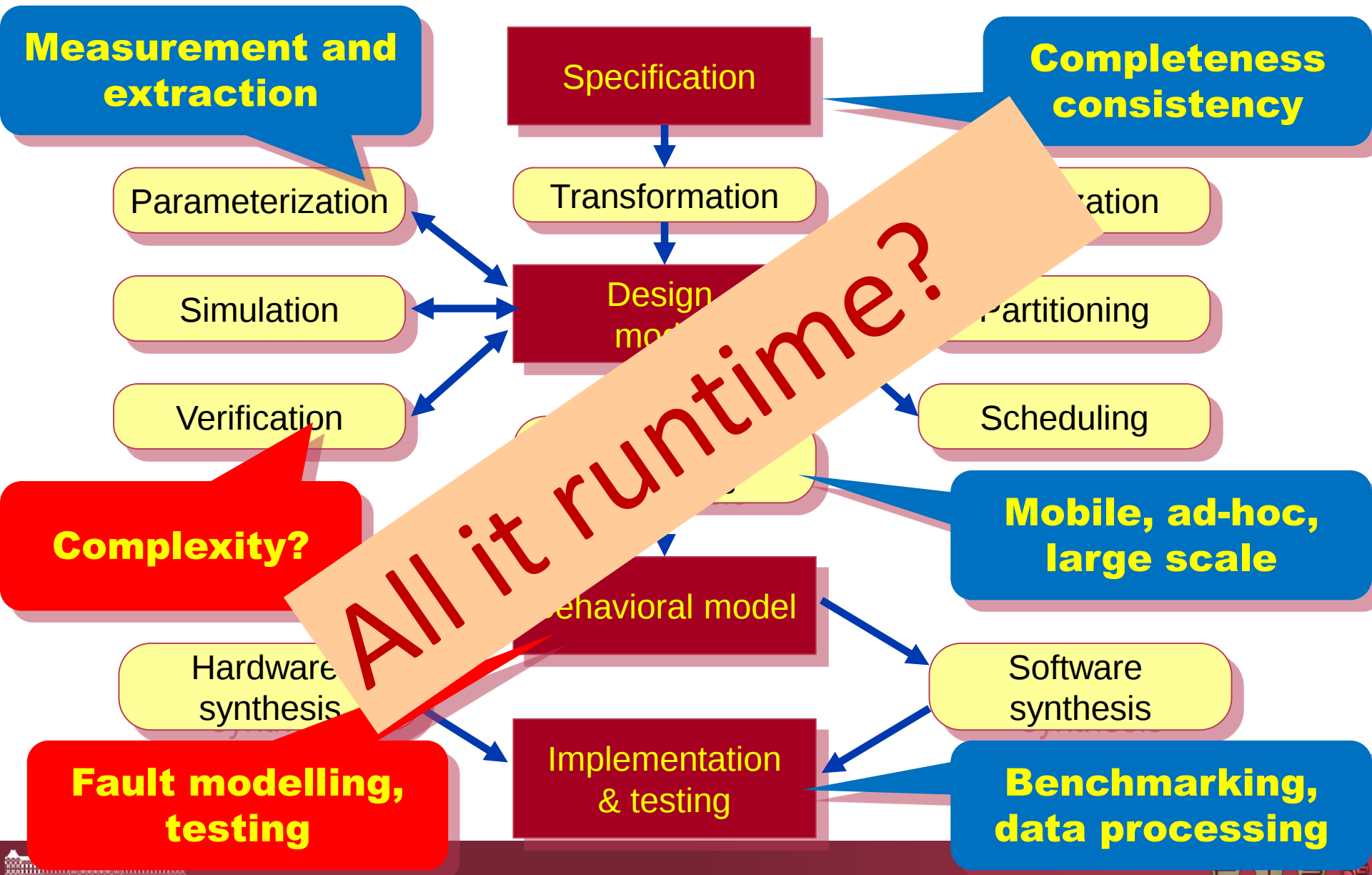
- Different applications concurrently using the same primary information
- Tasks can change according to time/season/requirements
 - Identification of ships
 - Monitoring the break-up of ice
 - Monitoring the water level
 - Monitoring the speed of flood
 - Pollution check
 - Supervision of hostile entrance to the ship



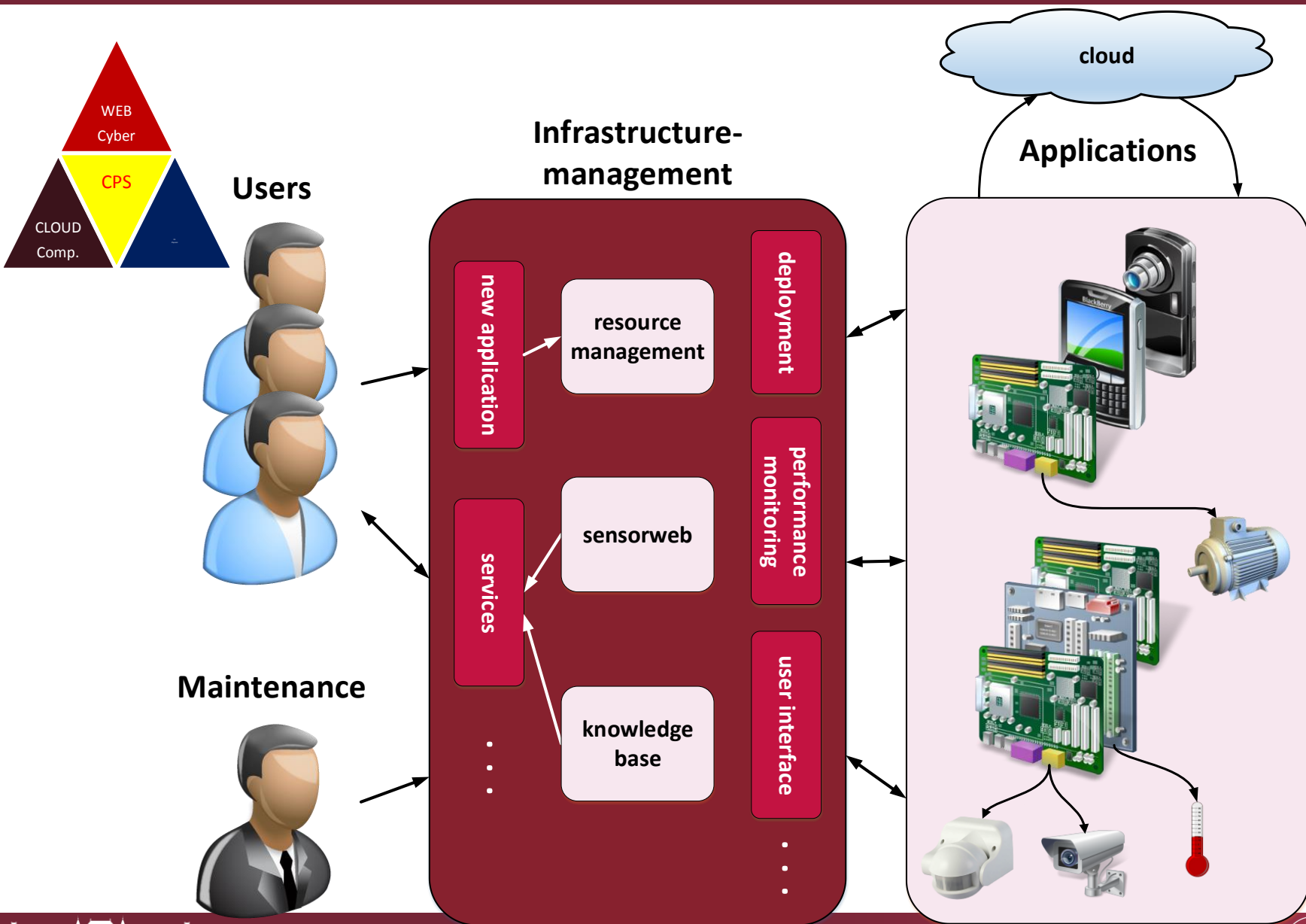
Dynamic cyber-physical systems



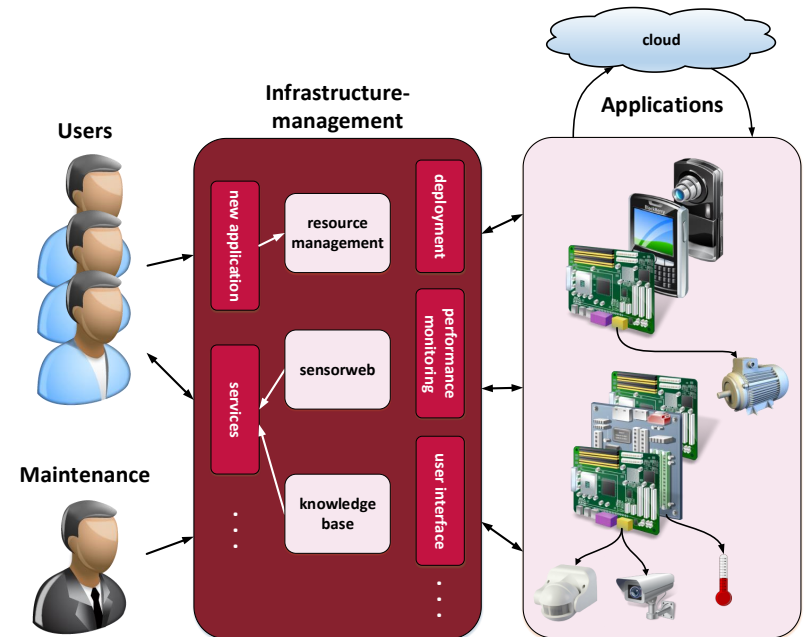
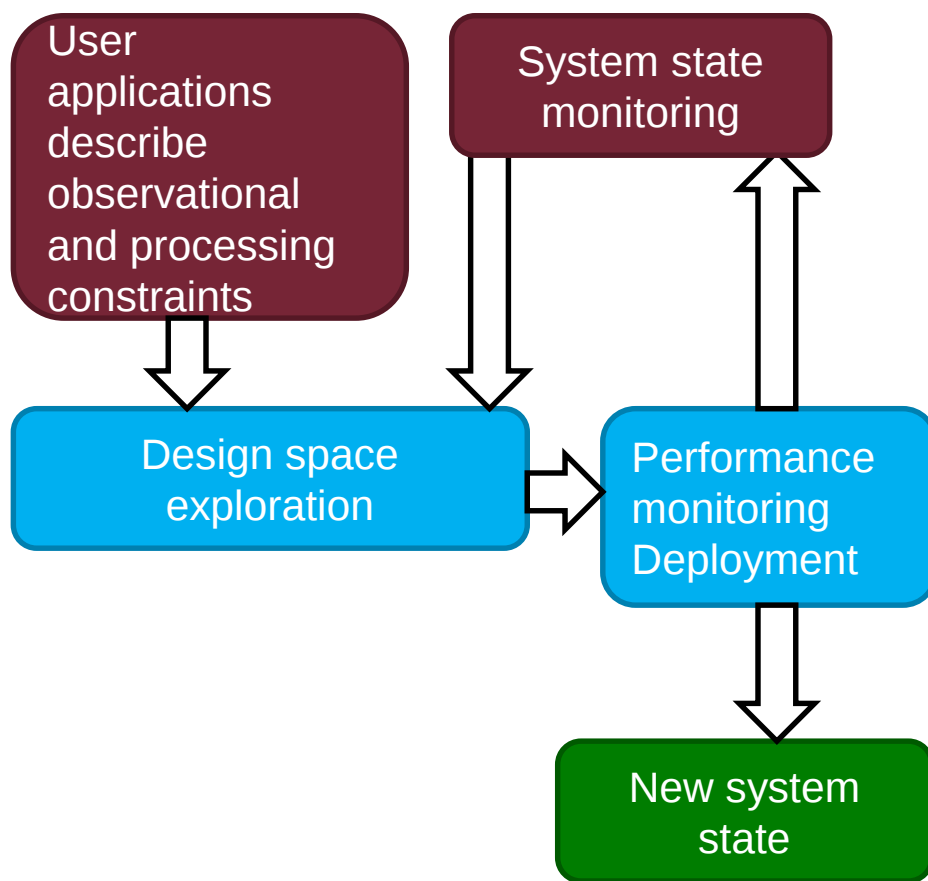
Critical CPS design and challenges



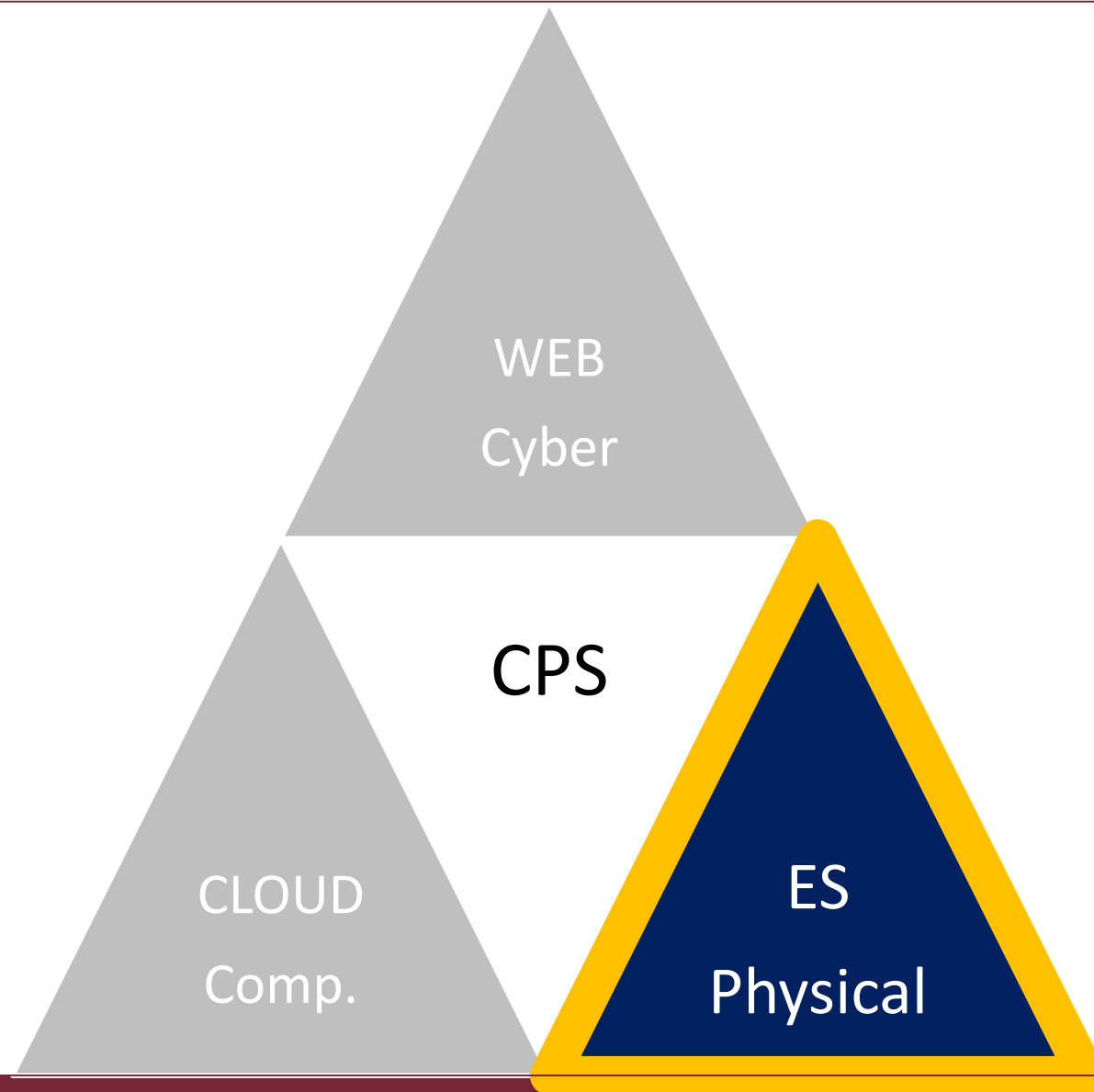
Dynamic composition of cyber-physical systems



Dynamic reconfiguration of resources ^{8 / 16}



The change in ES design



Service Oriented Approach

SOA

Embedded systems
provide services

- Information of
 - sensors
 - Internet
- High level information derived
- Actuation possibility (limited)

Services in a database

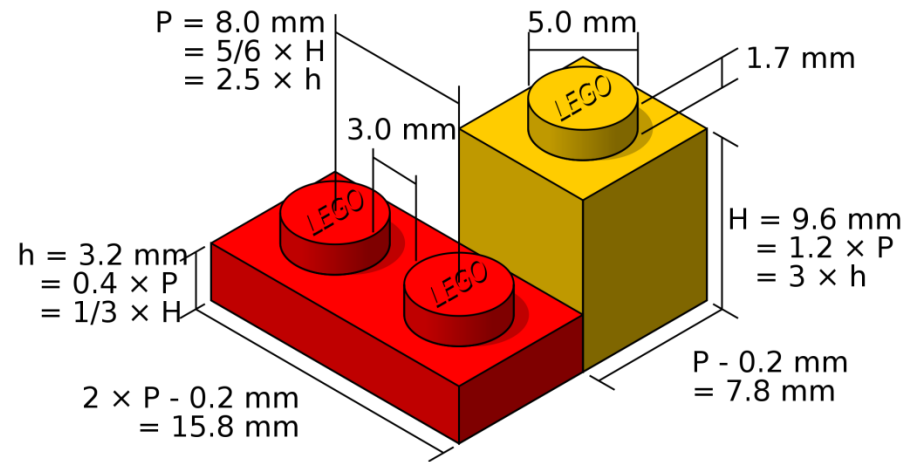
MDD

Upon a new task:

- solution based on
 - design patterns and
 - available resources

New solution deployed

- no interference with the already running ones

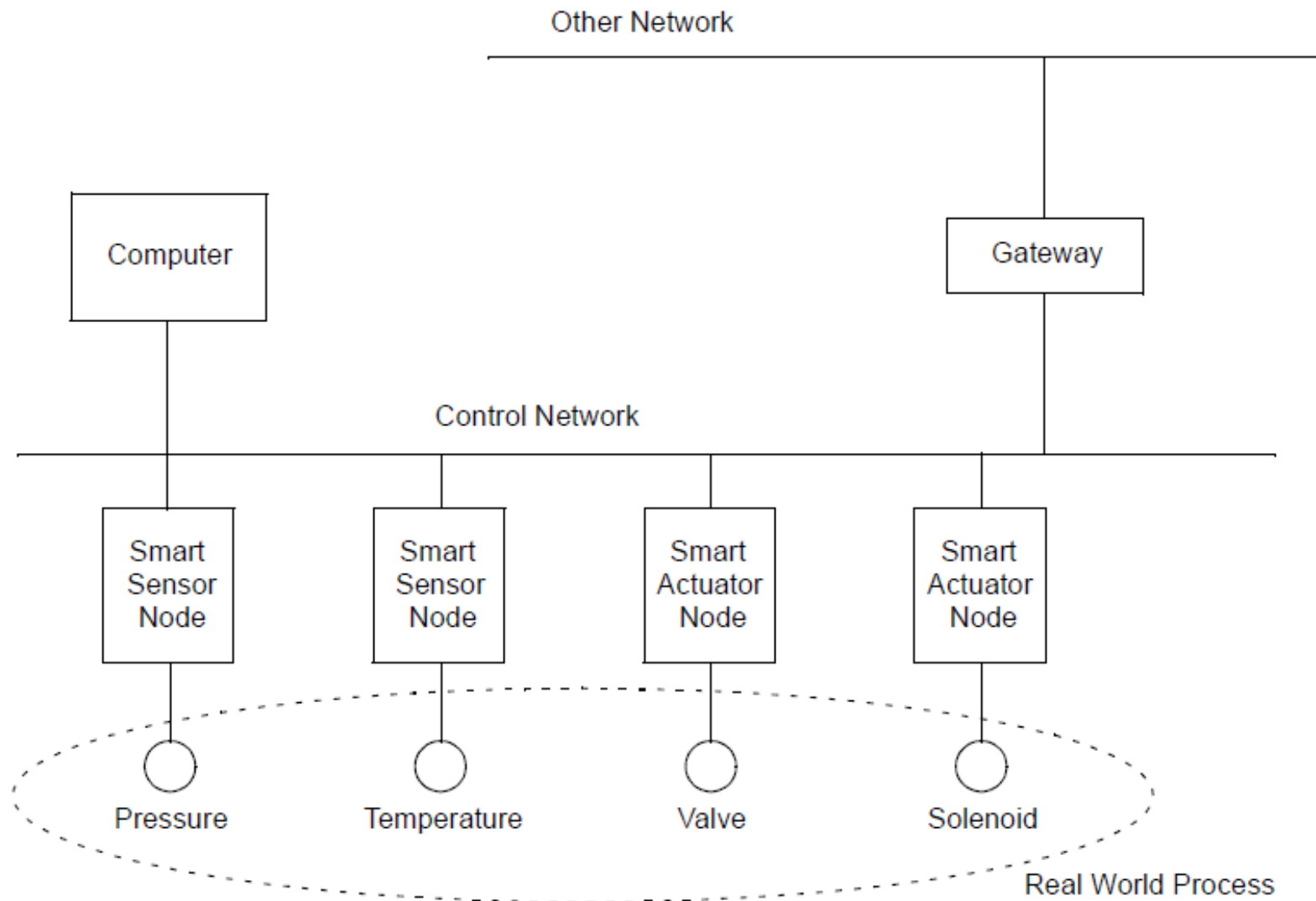


UNIFICATION IS THE KEY

Ontologies and Semantic Technologies

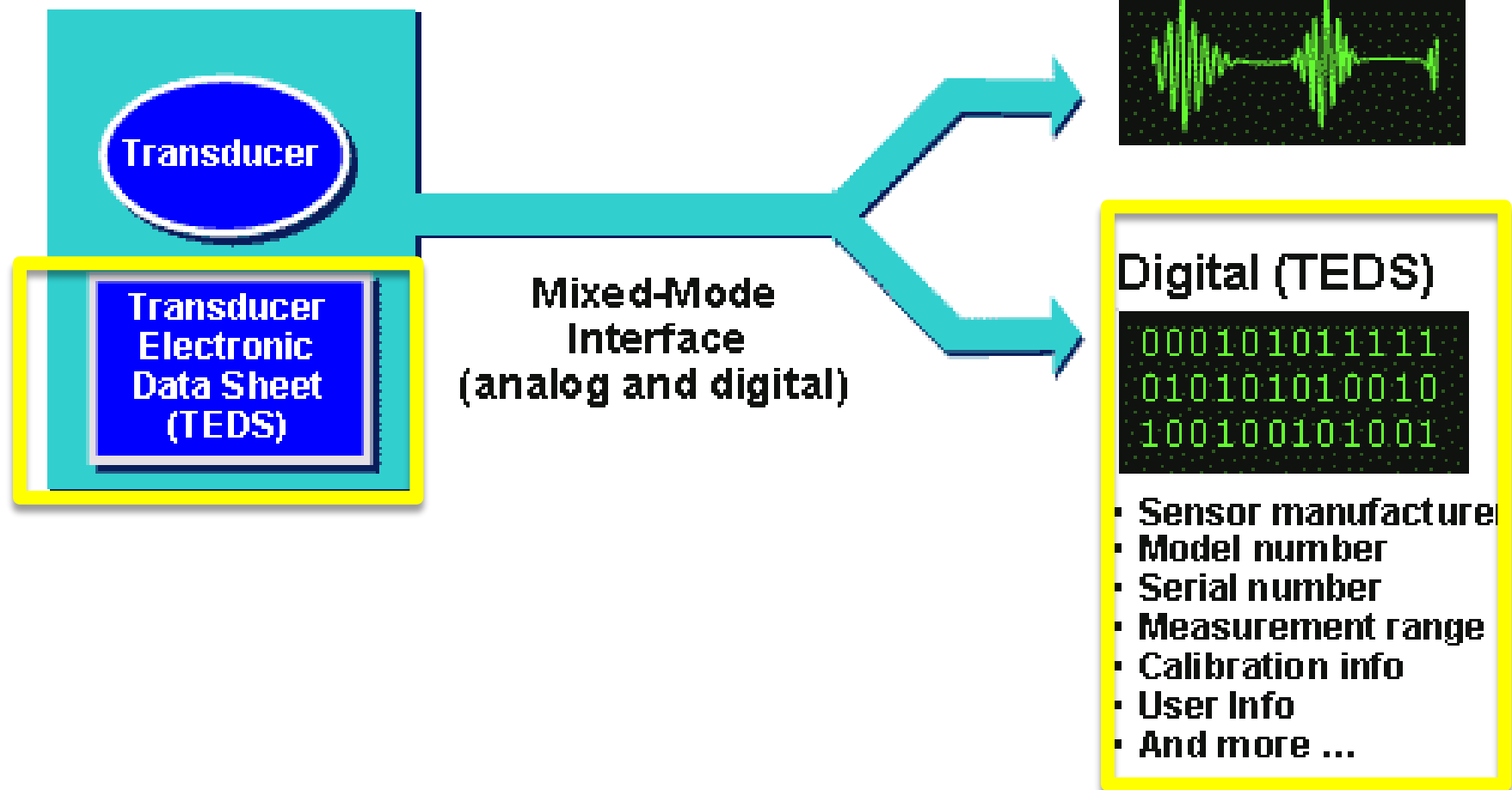


Smart transducers



Plug and play (vs. SOA ?)

Plug and Play Sensor

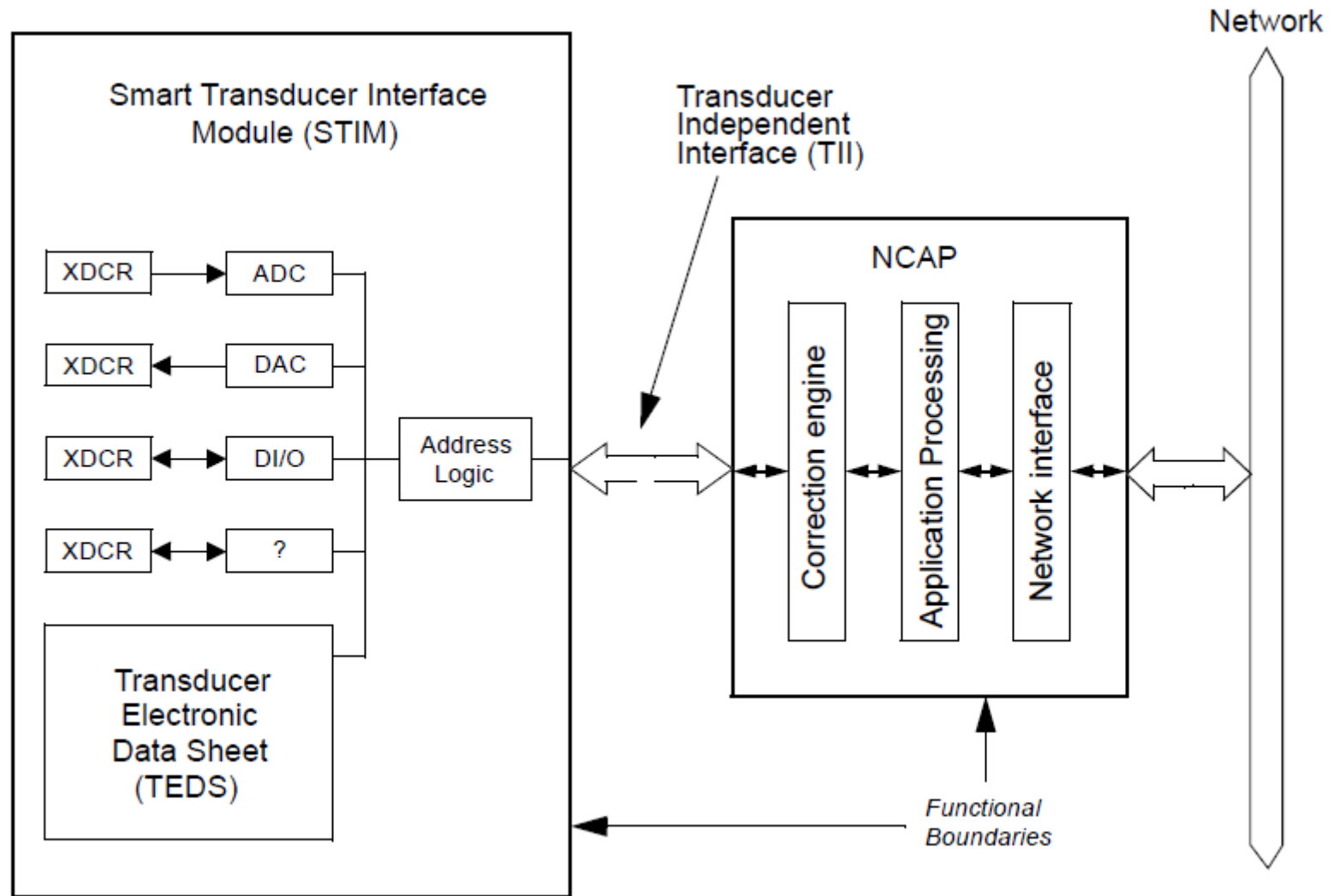


Electronic data sheet (NIST example)

Basic TEDS	Manufacturer ID	43 (Acme Accelerometer Company)
	Model Number	7115
	Version Letter	B
	Serial Number	X001891
Standard and Extended TEDS (fields will vary according to transducer type)	Calibration Date	Jan 29, 2000
	Sensitivity @ ref. condition (S ref)	1.0094 E+03 mV/g
	Physical measurement range	± 50 g
	Electrical output range	± 5 V
	Reference frequency (f ref)	100.0 Hz
	Quality factor @ fref (Q)	300 E-3
	Temperature coefficient	-0.48 %/°C
	Reference temperature (T ref)	23 °C
	Sensitivity direction (x,y,z)	x
User Area	Sensor Location	Strut 3A
	Calibration due date	April 15, 2002

Figure 2. Example TEDS for Accelerometer

Implementation



Use cases of IEEE 1451

Remote Monitoring Application



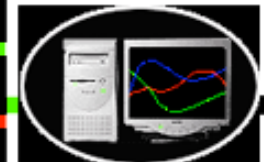
Distributed Control (Actuating Based on Local Measurement)



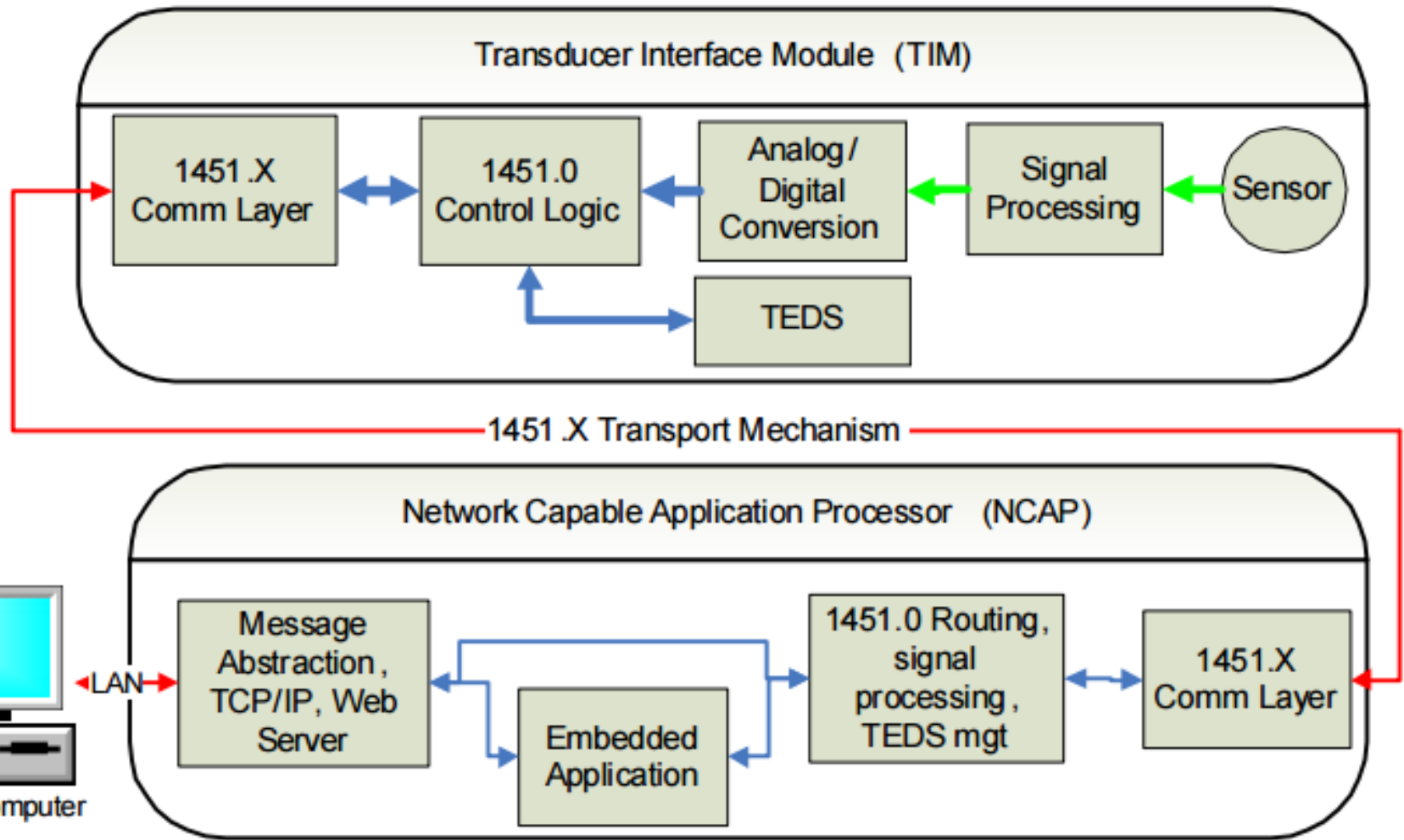
Remote Actuating



Collaborative Measurement and Control

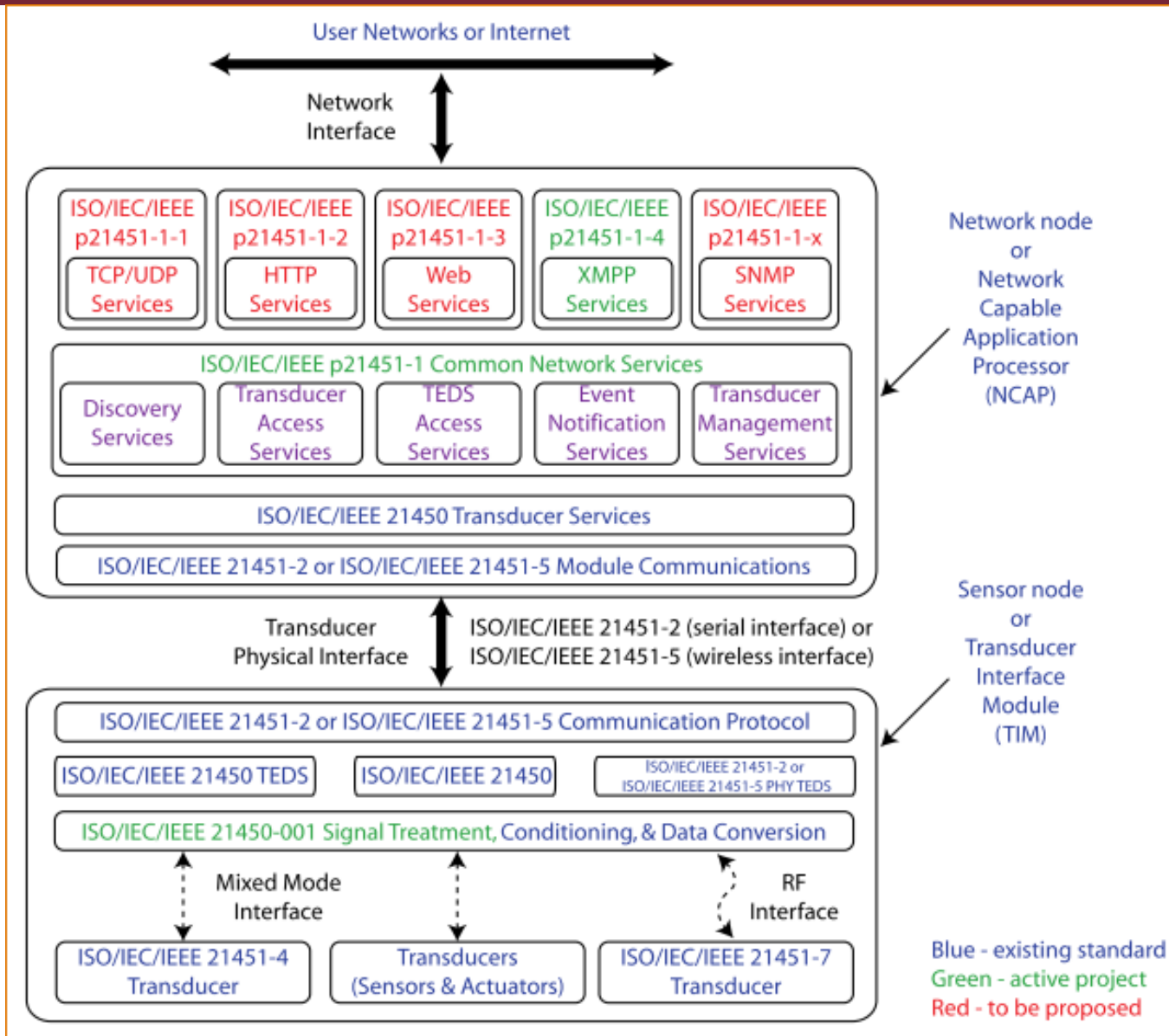


IEEE 1451 concept



IEEE1451 Standard Description

IEEE 1451 standards



STARTING POINT: FORMALIZED CONCEPTS

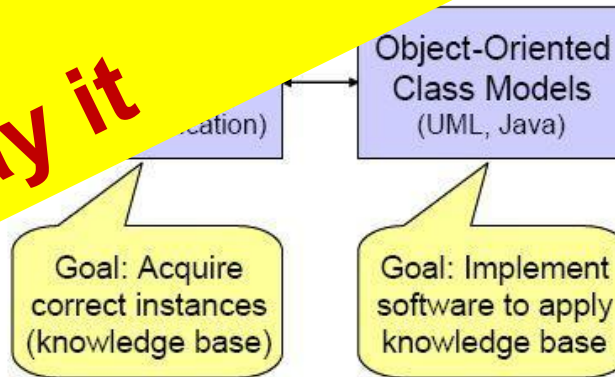
Design and analysis need clear concepts

From ontologies to metamodels

Vision: Synchronized Model-Oriented Development



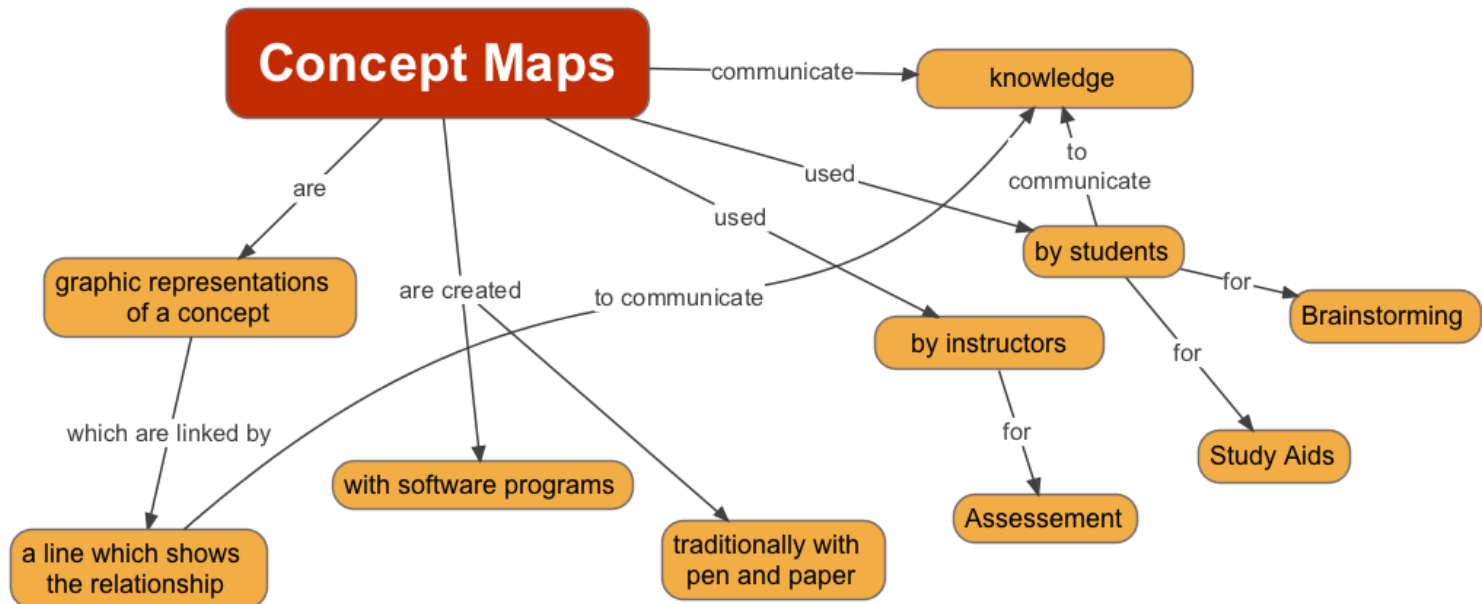
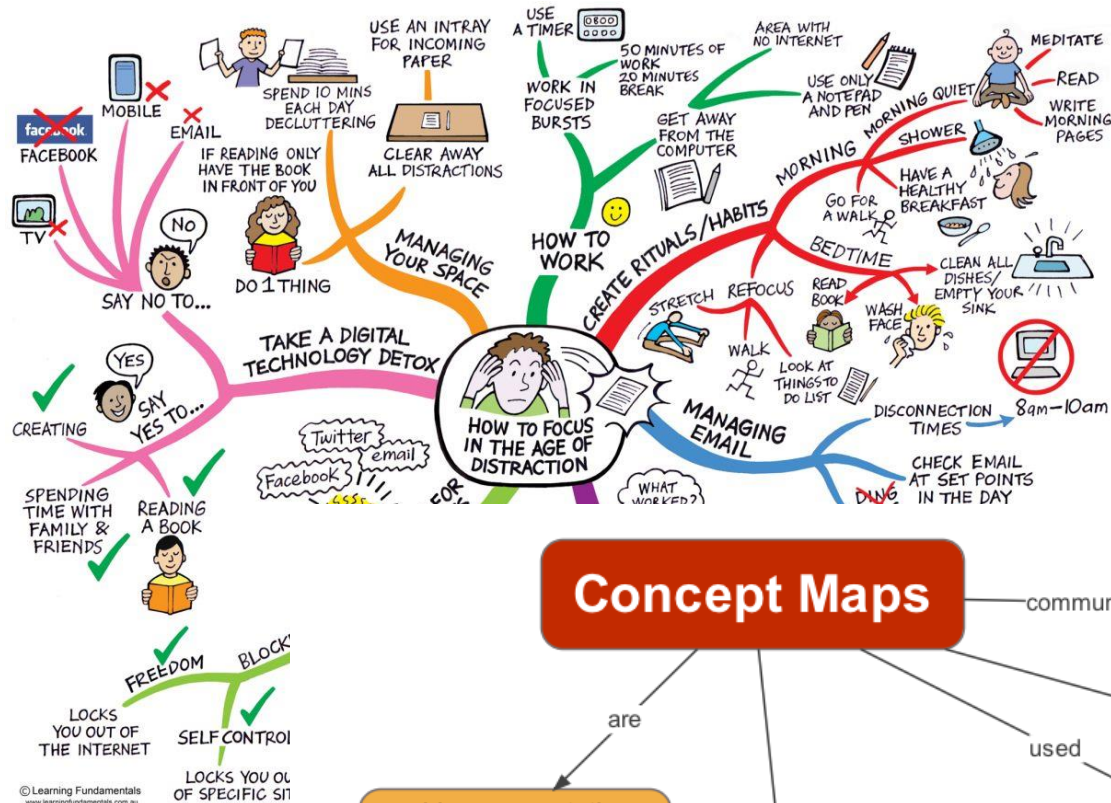
- Let define first
- what we want to say
- and only after
- how to say it



With each translation: More and better optimized tools

H. Knublauch:
Ontology Design and Software
Technology, Colloquium -
Stanford Medical Informatics,
2003

Hierarchical data representation



Ontology



A **data model** that

- represents a **domain** and
- Has a **logic** in the background
- is used to **reason** about
 - the **objects** in that domain and
 - the **relations** between them.

Ontologies generally describe:

- **Individuals:**
basic objects
- **Classes:**
sets, collections, or types of objects
- **Attributes:**
properties, features... that objects can have and share
- **Relations:** ways that objects can be related

Reasoning :

Concept space traversal

- **subsumption test** wrt. different profiles
- **consistency check:**
satisfiability
- **circular containment** of classes

Ontology foundations

- Ontology
 - Formal description of concepts (terminology)
 - OWL 2: ontology language for the Semantic Web
 - Reusable knowledge models
- Description Logic (DL)
 - knowledge representation,
 - similar to rule languages
 - decidable, efficient decision problems
 - justifications for inferences
 - terminology (concepts & properties, TBox) and data / cases (individuals, ABox) are separated
 - schema language with complex constraints
- OWL 2 is based on the DL “SROIQ”.

Example: part of the security ontology

The screenshot displays the Protege OWL editor interface. At the top, there are tabs for OWLClasses, Properties, Individuals, and Forms. The main window is divided into three panes. The left pane, titled 'SUBCLASS EXPLORER', shows an 'Asserted Hierarchy' for the project 'Security'. It lists various classes, with 'AssetLifeCyclePhase' highlighted. The middle pane, titled 'CLASS EDITOR for AssetLifeCyclePhase', shows the 'For Class' field and a table of properties. The right pane shows the 'owl:Thing' class.

Subclass Explorer (Asserted Hierarchy):

- owl:Thing
 - Asset
 - AssetLifeCyclePhase**
 - Attack ≡ Threat
 - Countermeasure
 - DefenseStrategy
 - Goal
 - AuthenticationGoals
 - ConfidentialityGoals
 - IntegrityGoals
 - literature:Definition
 - literature:Literature
 - Model
 - AccessControlModel
 - CryptographyModel
 - NaryRelation
 - Product
 - protege:ExternalResource
 - Threat ≡ Attack
 - ActiveAttack
 - Disclosure ≡ PassiveAttack
 - PassiveAttack ≡ Disclosure
 - User
 - Vulnerability
 - TargetConnectedToNetwork
 - VulnerabilityInCode
 - VulnerabilityInConfiguration
 - VulnerabilityInUse

Class Editor (For Class: file:///C:/Users/Pataric/Desktop/CASED/Se...):

Property	
owl:versionInfo	TODO: Work with this
rdfs:comment	Denotes when a count Proof-of-concept sta

Class Editor (owl:Thing):

- DefenseStrategy
- Asset
- Goal
- Threat
- Product
- ThreatThreatensGoalOfAsset
- User

A. Herzog et al:
An Ontology of Information Security
Int. J. of Inf. Security and Privacy (1), 4

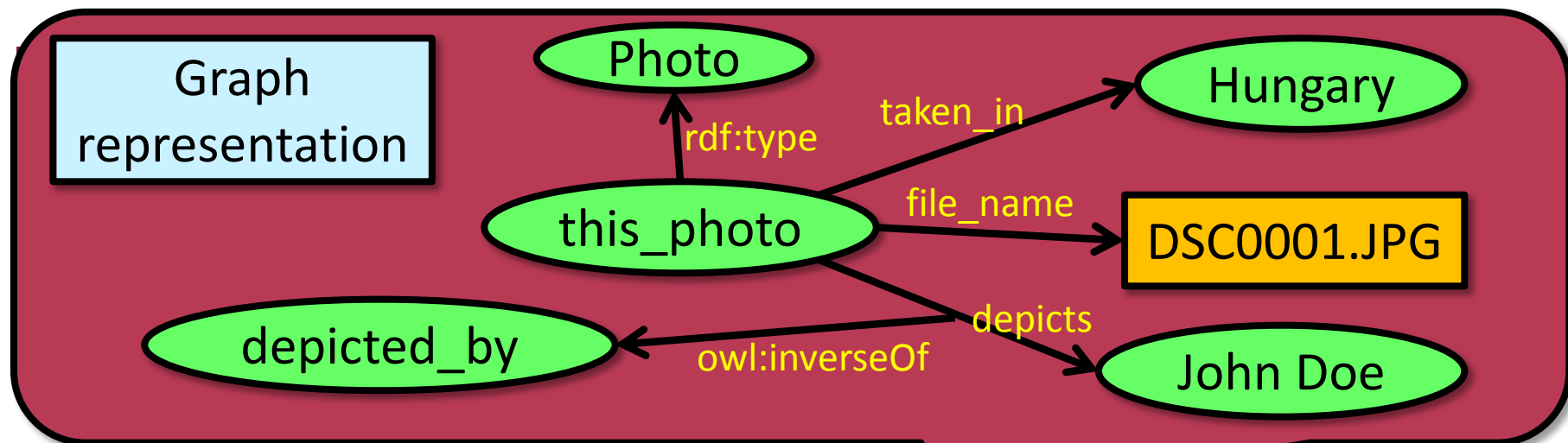
RESOURCE DESCRIPTION FRAMEWORK (RDF)

Resource Description Framework

- W3C: Resource Description Framework (**RDF**)
- *Graph based* structure
 - Node: **rdf:Resource** → something we talk about
 - e.g. a document, this photo, a table or “something”
 - Edge: **rdf:Property** → relation type between resources
 - e.g. depicts, taken_in, type etc.
- Node name and relation type name: **IRI** (Internationalized Resource Identifier)
- **Literal** nodes: 5^^xsd:integer, „John”



RDF Statements



■ Example triples

- (this_photo, taken_in, Hungary)
- (this_photo, file_name, „DSC0001.JPG”)
- (this_photo, depicts, John Doe)
- (this_photo, **has_type**, Photo)
- (rdf:type, rdf:type, rdf:Property)

Object is an rdf:Literal

rdf:type is defined
in the RDF standard

WEB ONTOLOGY LANGUAGE (OWL 2)

Formal Background

■ Axiomatic language

○ S : Mother $\equiv \exists \text{child. Person}$ // have child who is a person

○ R : ObjectProperty knows // everybody knows oneself

Characteristics: Reflexive

○ O : Visibility $\equiv \{p \mid \text{parent}(p) \text{ is a person}\}$

○ I : child $\equiv \text{parent}$

○ Q : FootballCoach

○ // a football coach

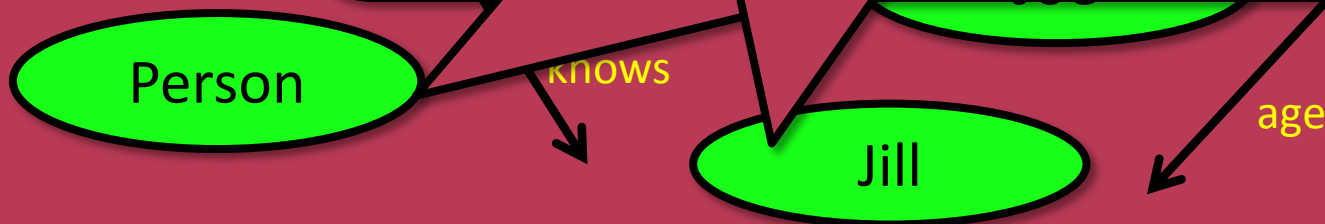
○ $(\mathcal{D})$: Individual

Facts

OWL2 EL profile:

- useful for reasoning
- only exists
- polynomial complexity
- used w.r.t. size

OWL defines the semantics of some new relation types, e.g. owl:intersectionOf or owl:cardinality

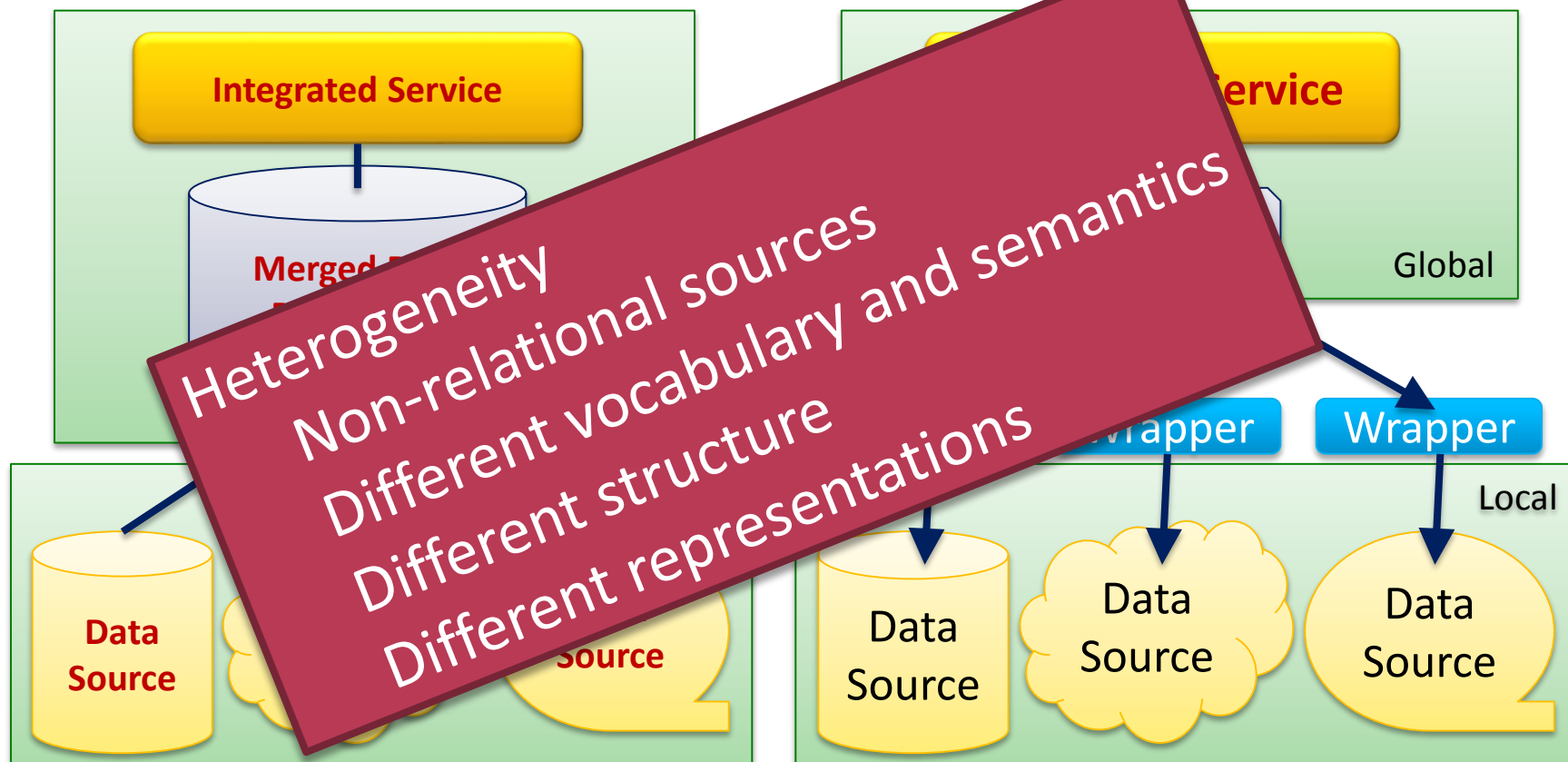


SEMANTIC INTEGRATION

Data integration

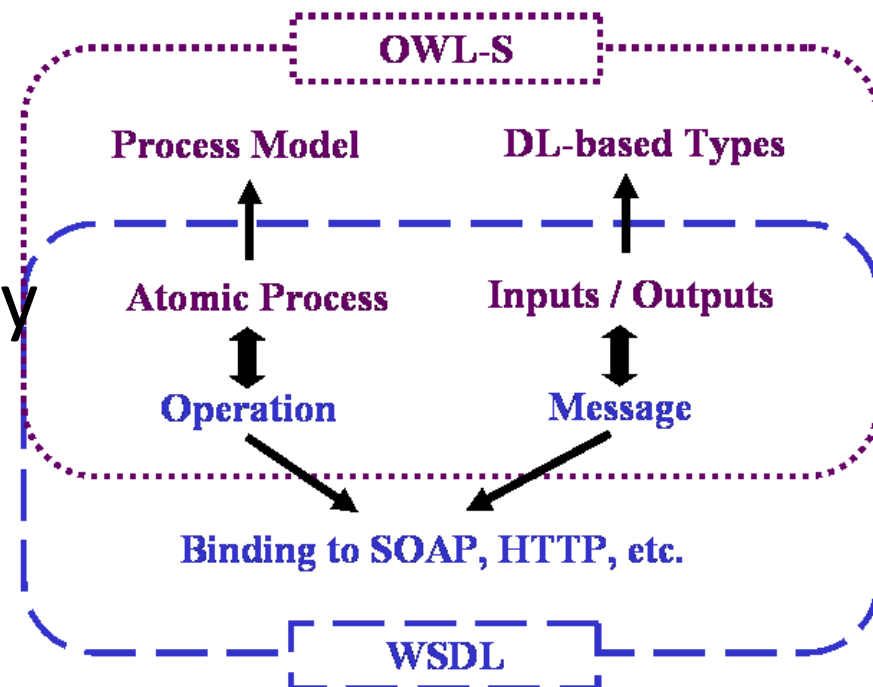
Warehousing

Federation



Semantic Service Integration

- Ontology-based Semantic Data Integration
 - Local scheme explained with linked ontologies
 - Semantic mapping between schemes
- Semantic Web Services
 - OWL-S
 - Process Model, DL types
- Semantic Service Discovery



SEMANTIC DATA REPRESENTATION

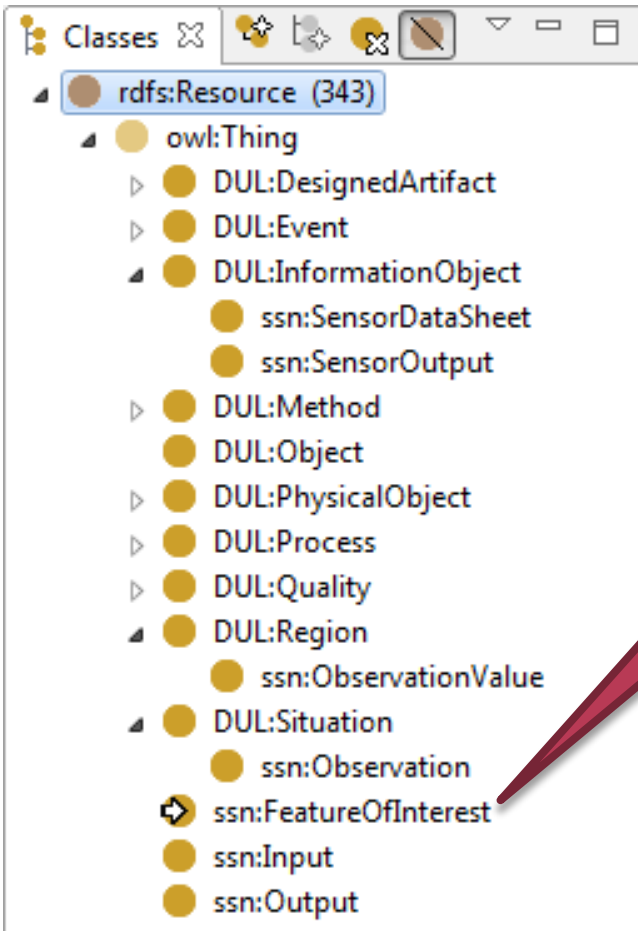
Problems to be solved:

- Transducer metadata as knowledge
 - Store and query
 - Search & discovery
- Application-generated data as “derived sensor” data
- Approach:
 - Semantic framework to describe knowledge

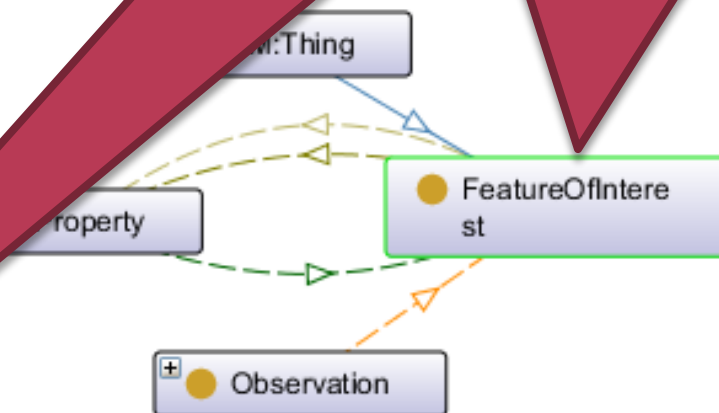
Semantic Sensor Network (SSN)

- W3C Incubator Group (2009-2011)
- <http://www.w3.org/2005/Incubator/ssn/>
- Describes capabilities of sensors and sensor networks
 - Formal ontology in OWL 2
 - Built on DOLCE Ultra Lite (DUL) upper ontology
- Covers:
 - system, deployment, sensing device, process
 - observed phenomenon (e.g. wind)
 - sensor type (e.g. ultrasonic wind sensor)
 - property (e.g. wind direction)
 - meaning (e.g. blows from direction)
 - unit of measure (e.g. radian)
 - operating / survival range (e.g. temperature, humidity, power...)

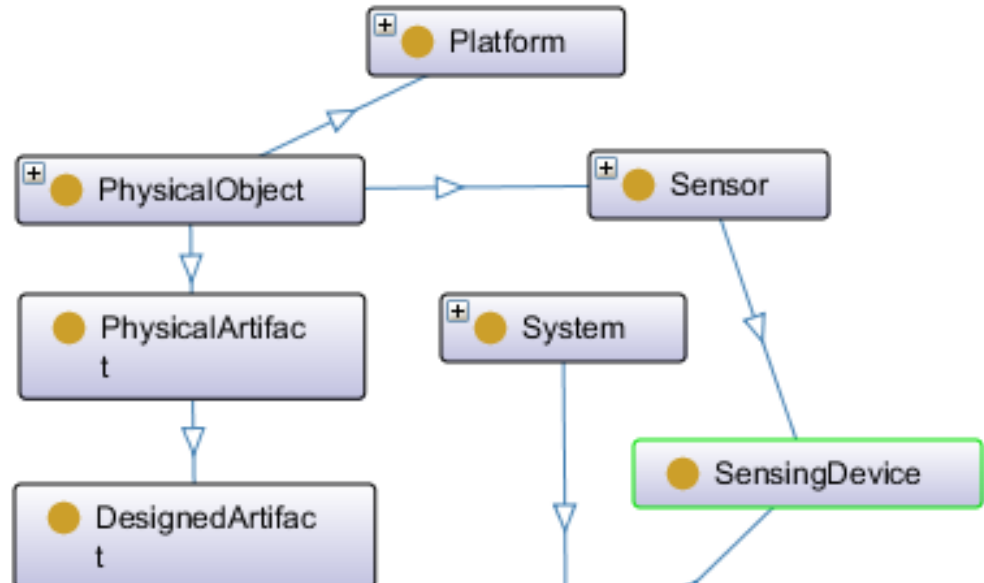
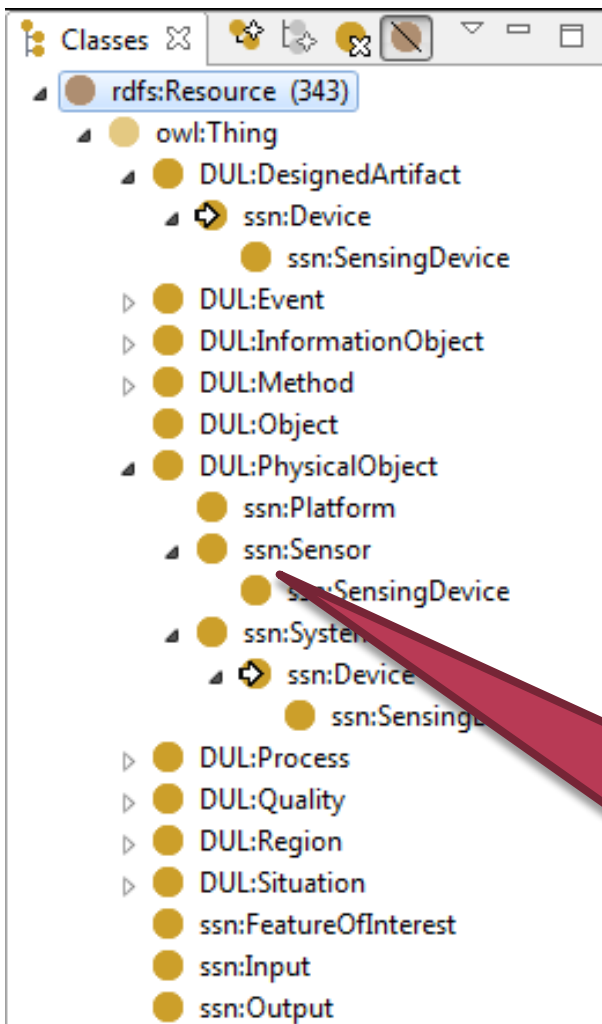
SSN – Feature of Interest



A feature abstraction of real world phenomena

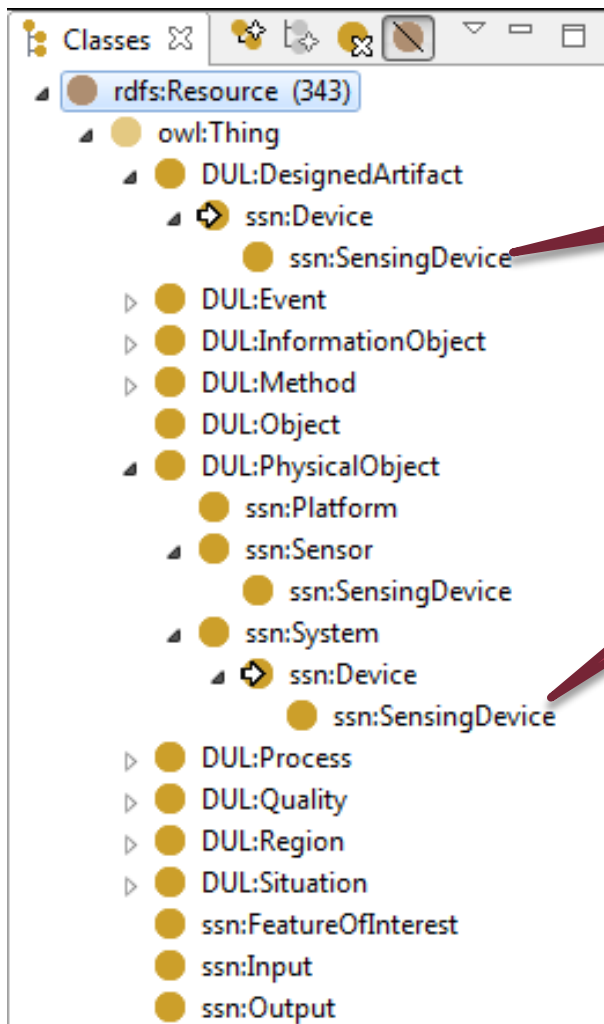


SSN – Sensor

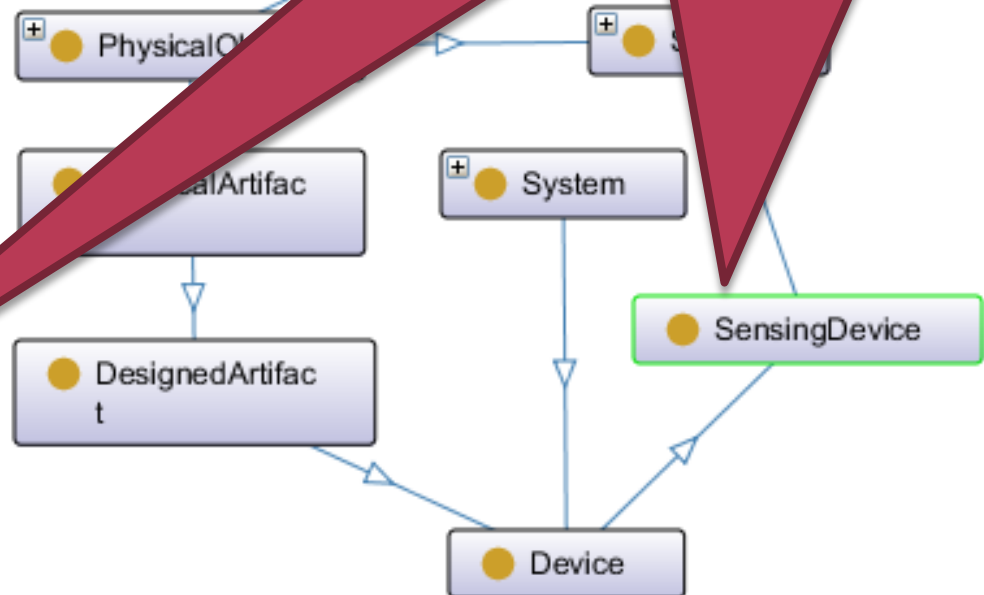


- sensing method
- observes some Property of a FeatureOfInterest.

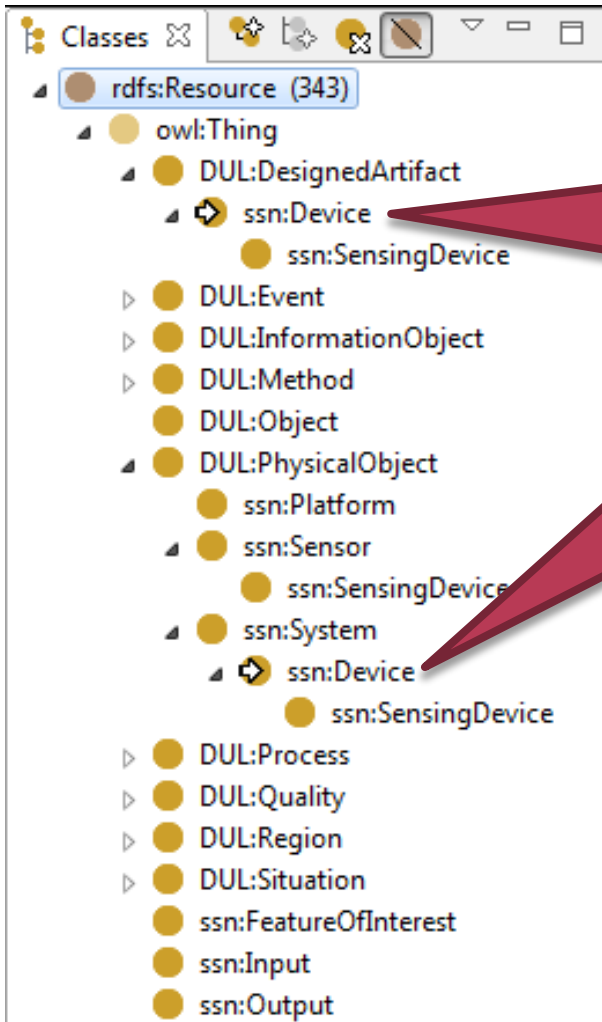
SSN – Sensing Device



device implements sensing.

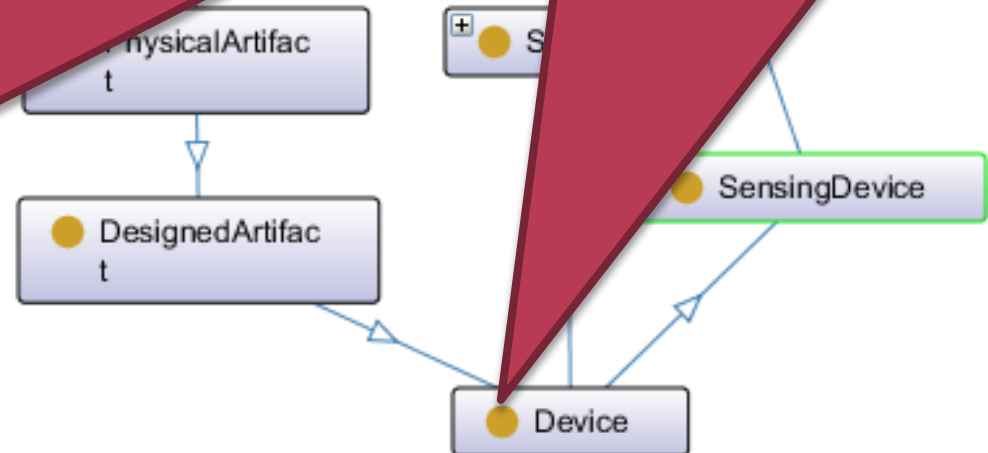


SSN –Device

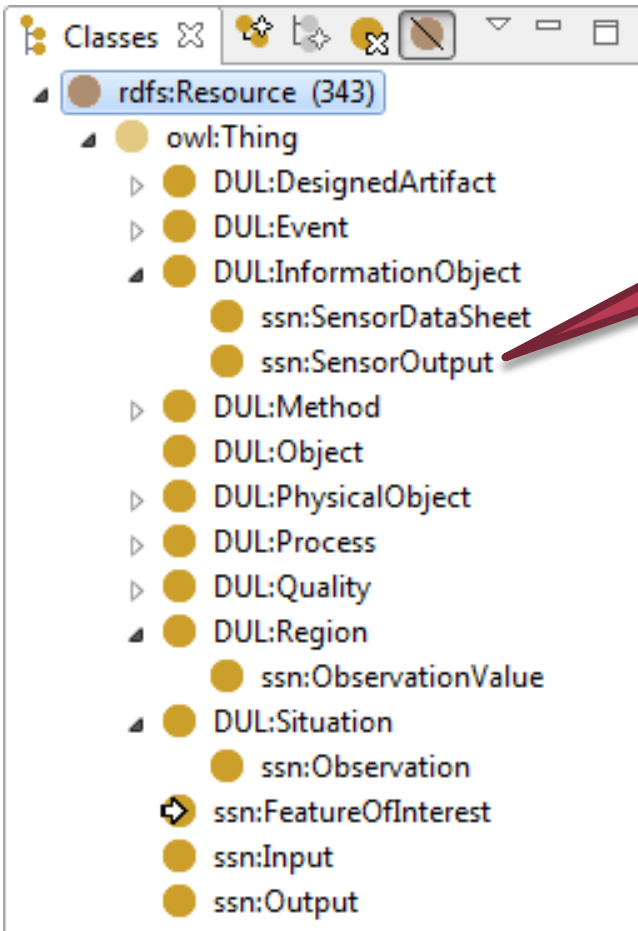


A device

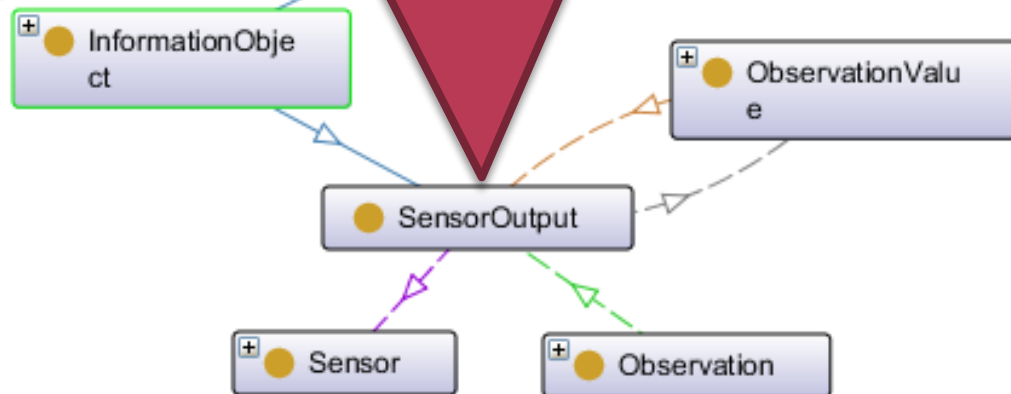
- physical piece of technology - a system in a box
- may be built of smaller devices and SW components



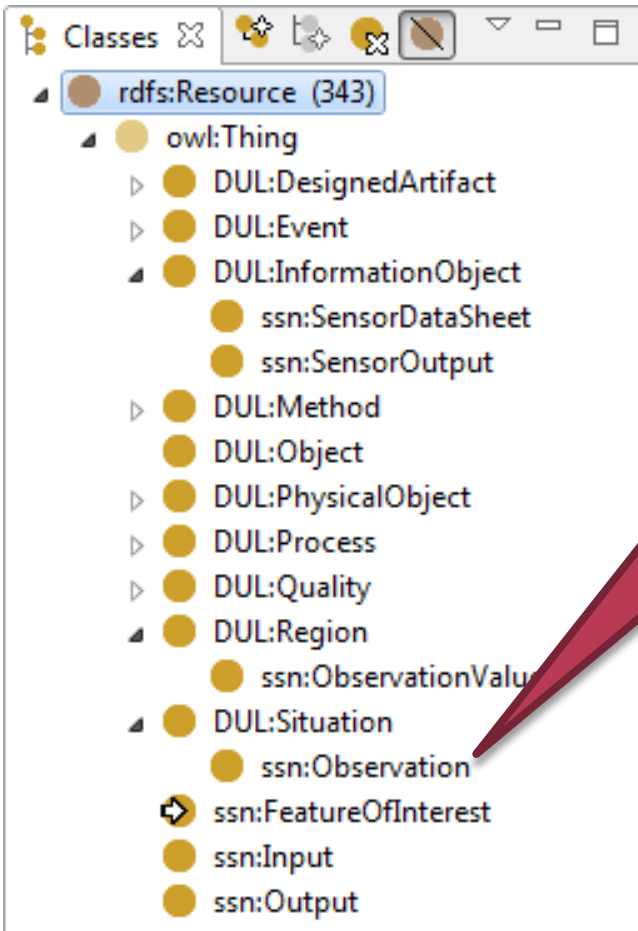
SSN – SensorOutput



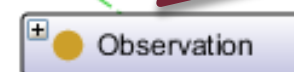
A sensor outputs a piece of information (an observed value), ObservationValue.



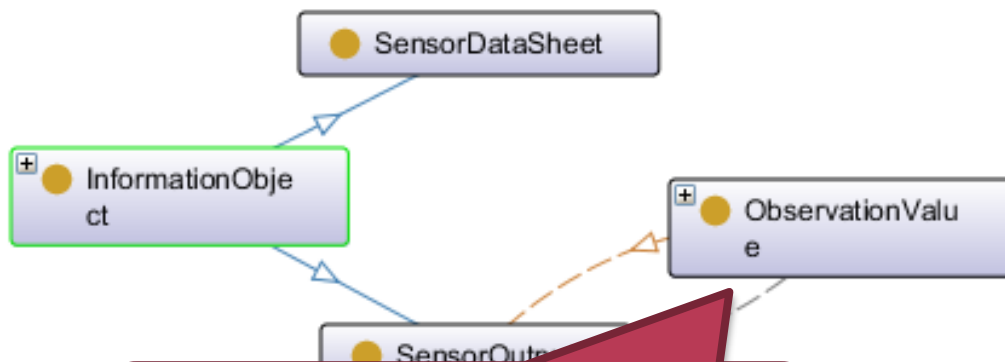
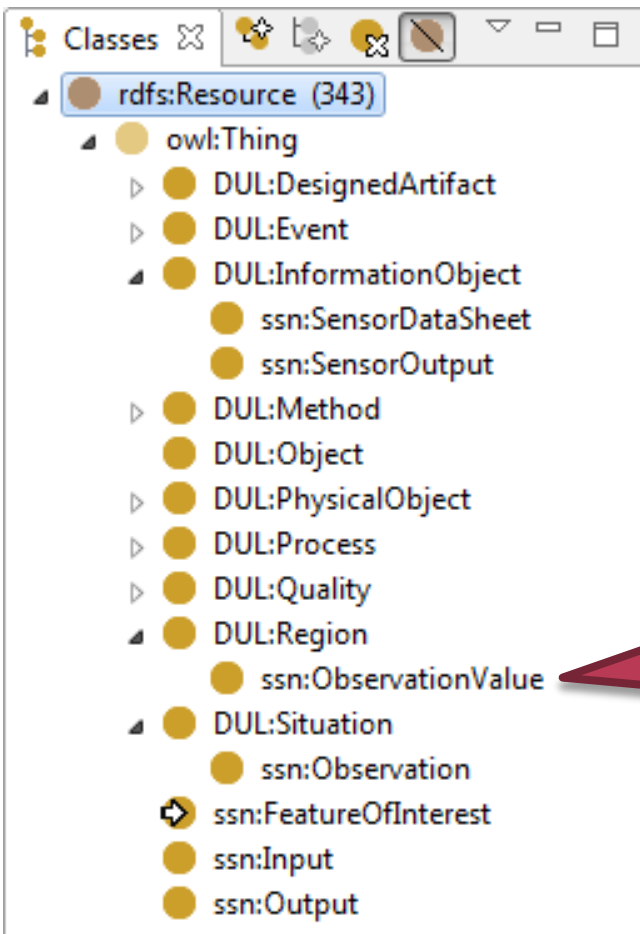
SSN – Observation



Sensing method estimated or calculated:
value of a Property of a FeatureOfInterest.
Links to Sensing and Sensor:
what made the Observation and how;
Links to Property and Feature
what was sensed;
Result : the output of a Sensor
Other metadata: times etc.

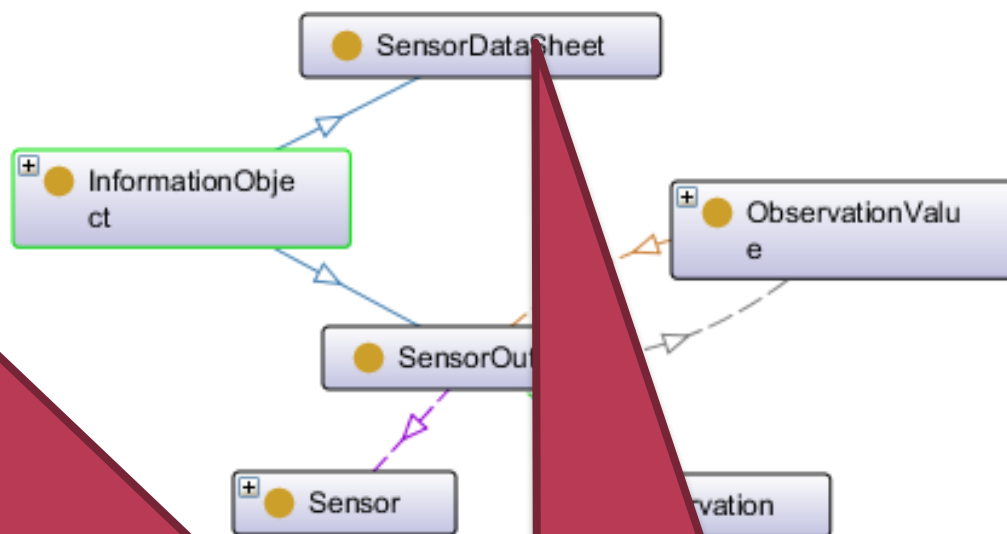
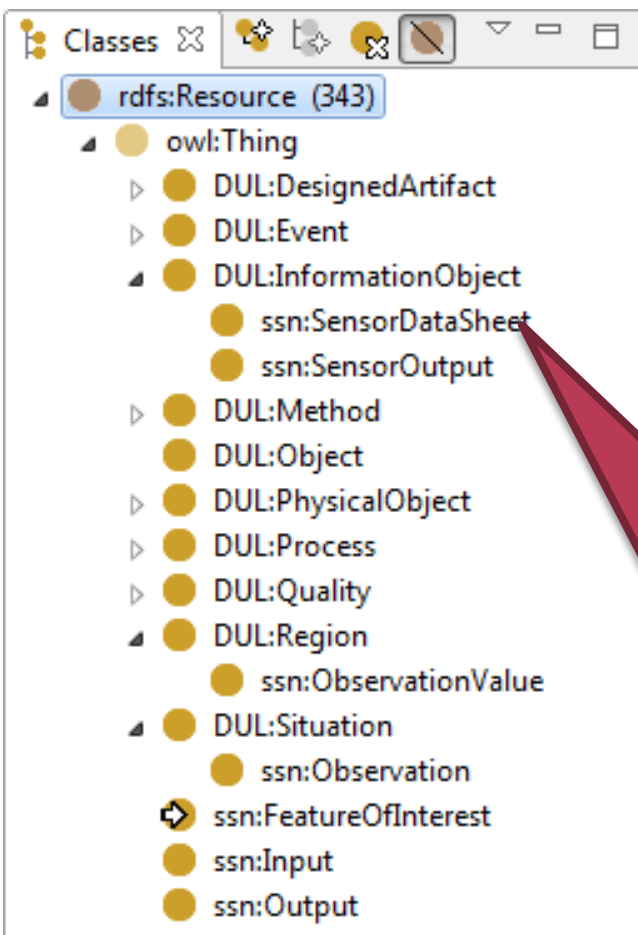


SSN – ObservationValue



The value of the result of an Observation = some value for a Feature.

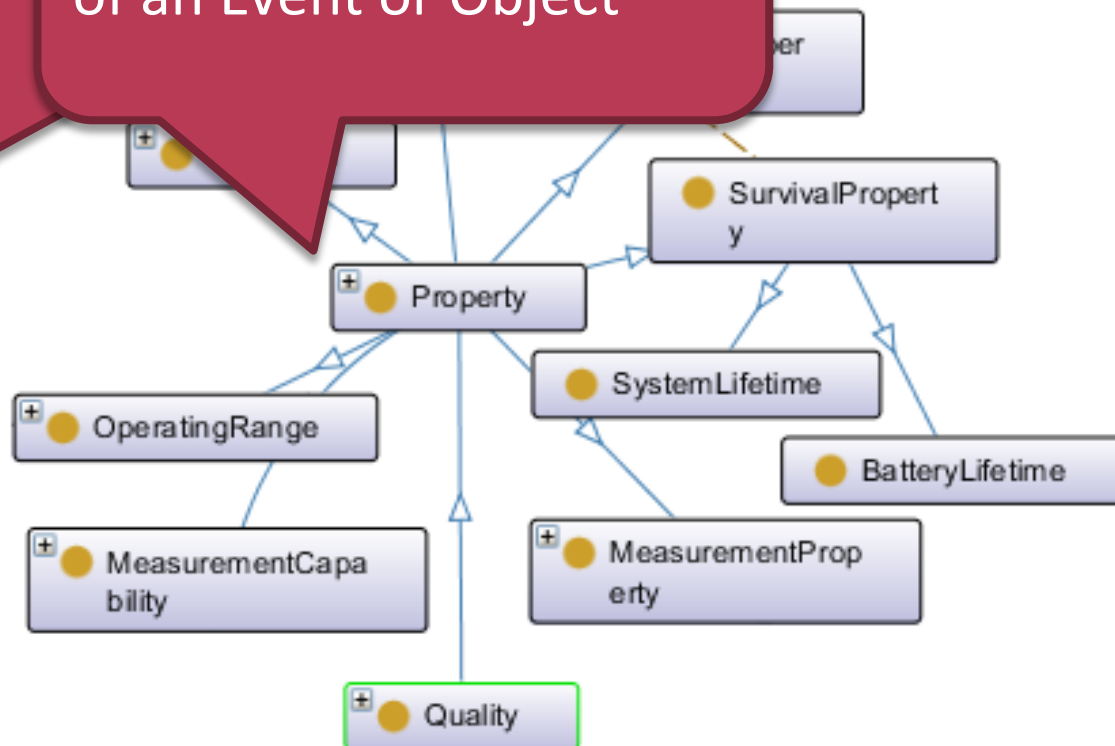
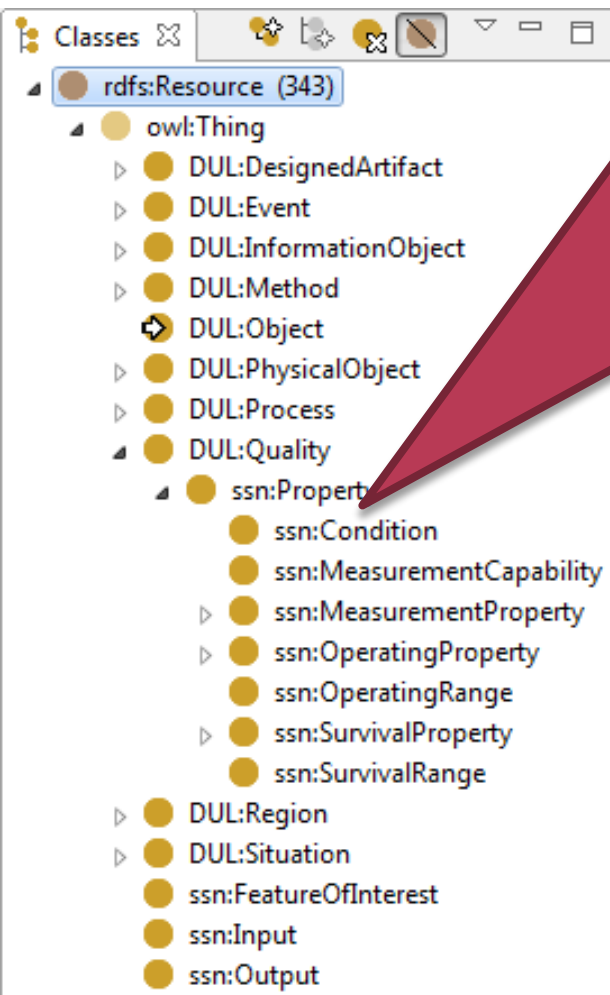
SSN – SensorDataSheet



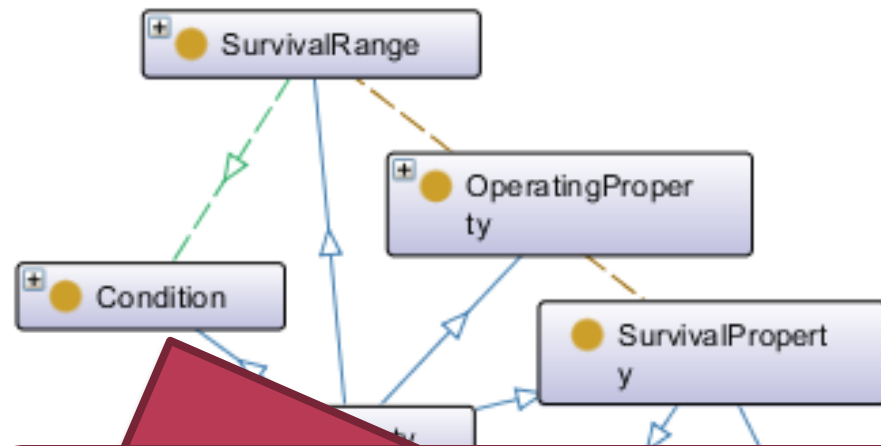
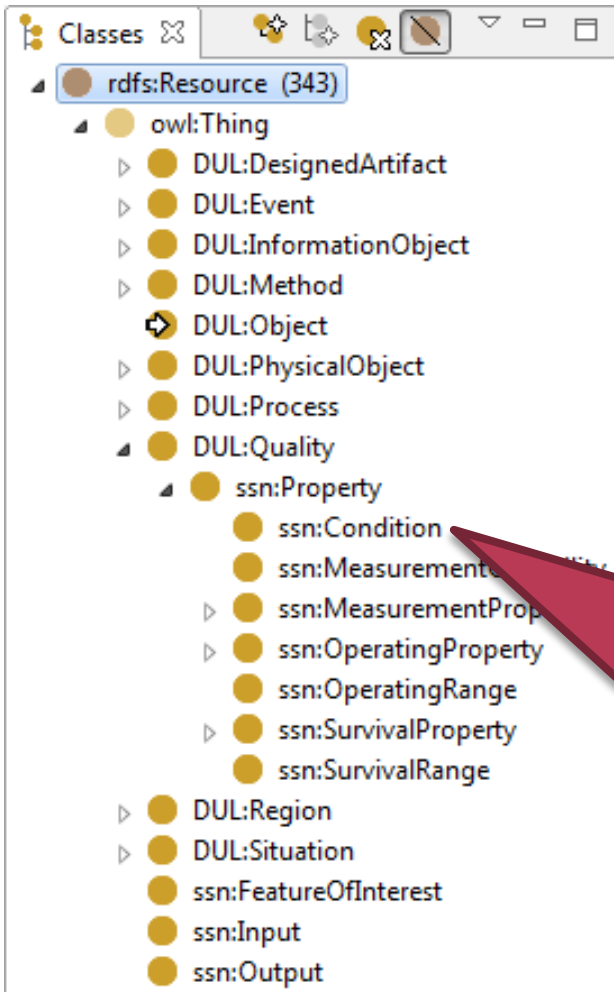
A data sheet:
properties of a sensor.

SSN - Property

An observable Quality of an Event or Object

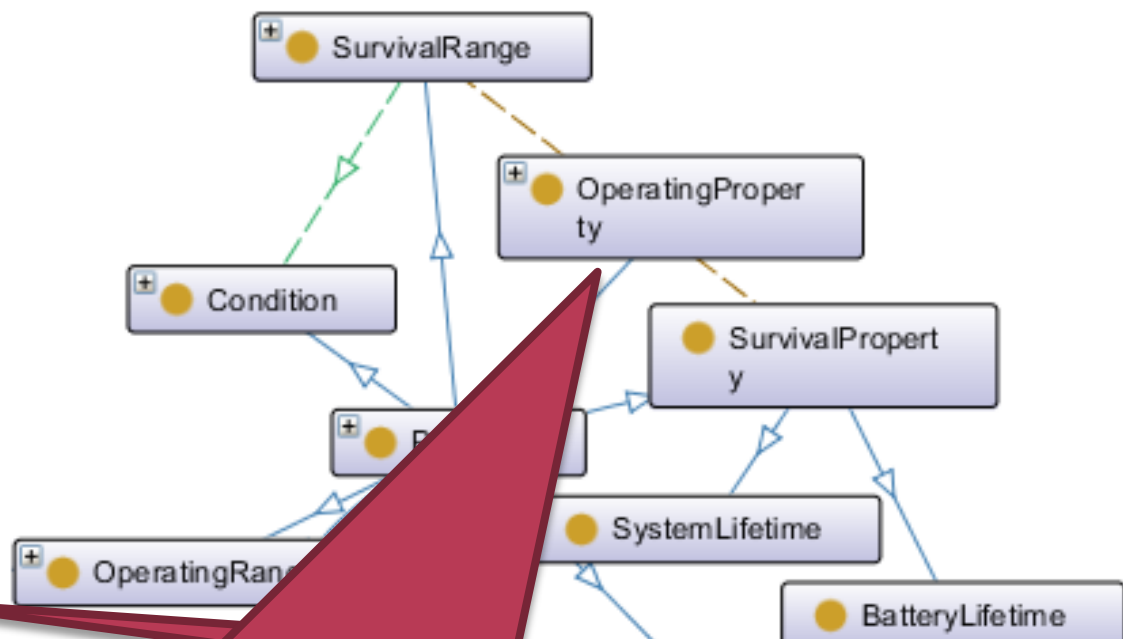
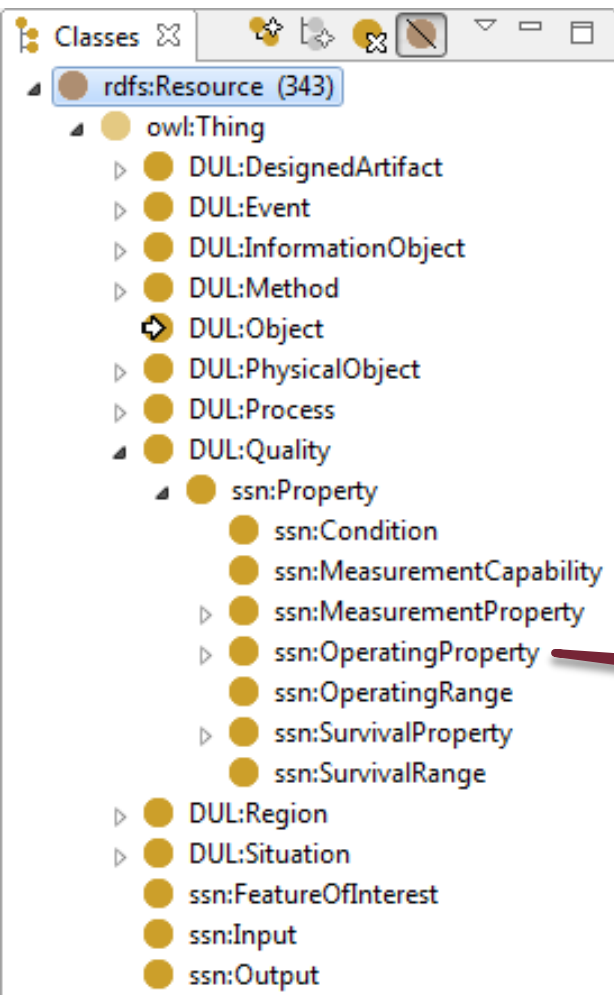


SSN - Condition



Ranges for conditions on a system/sensor's operation.

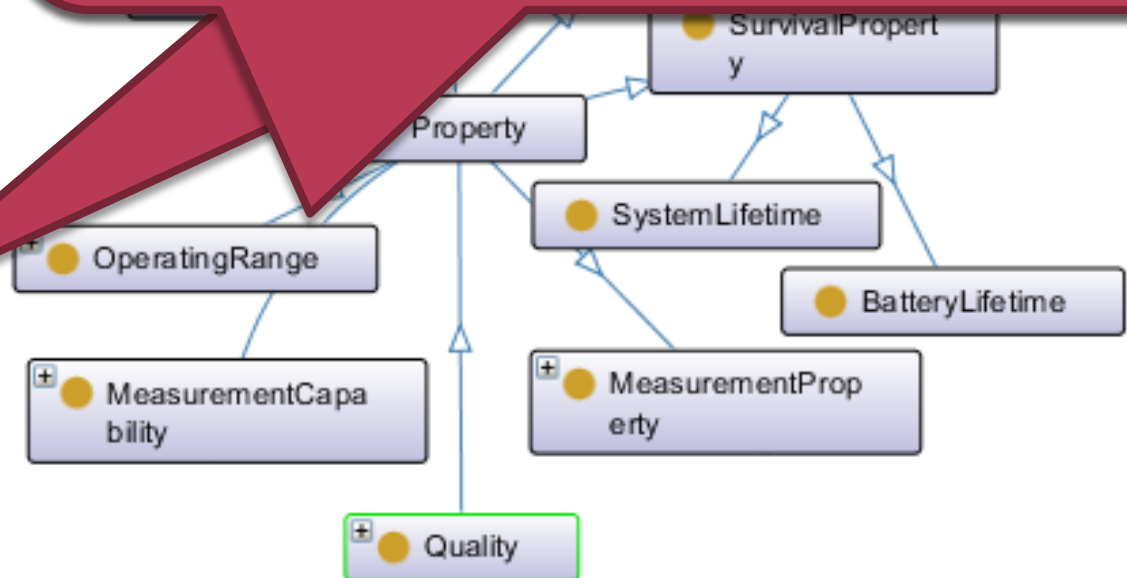
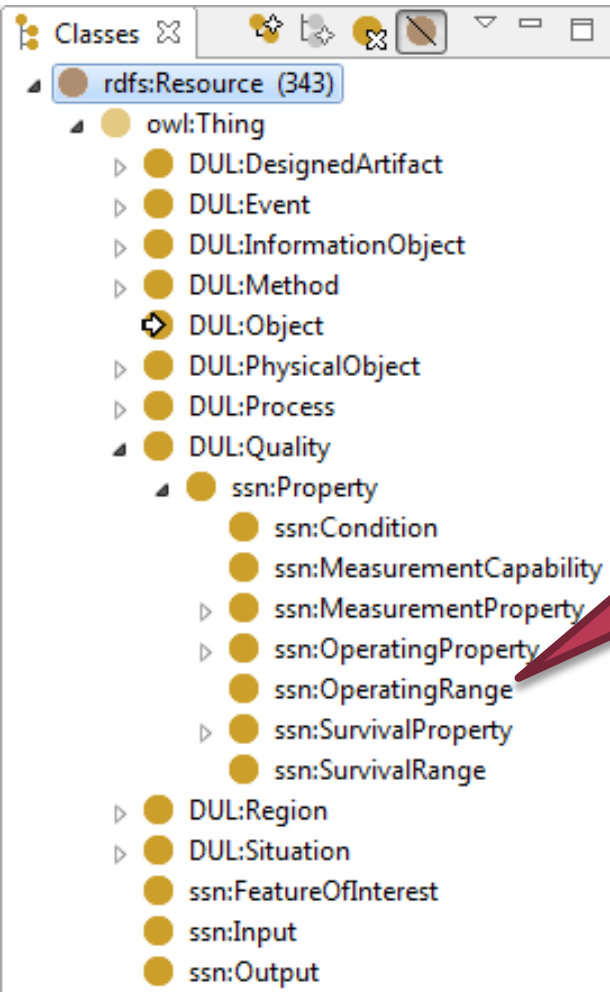
SSN - OperatingProperty



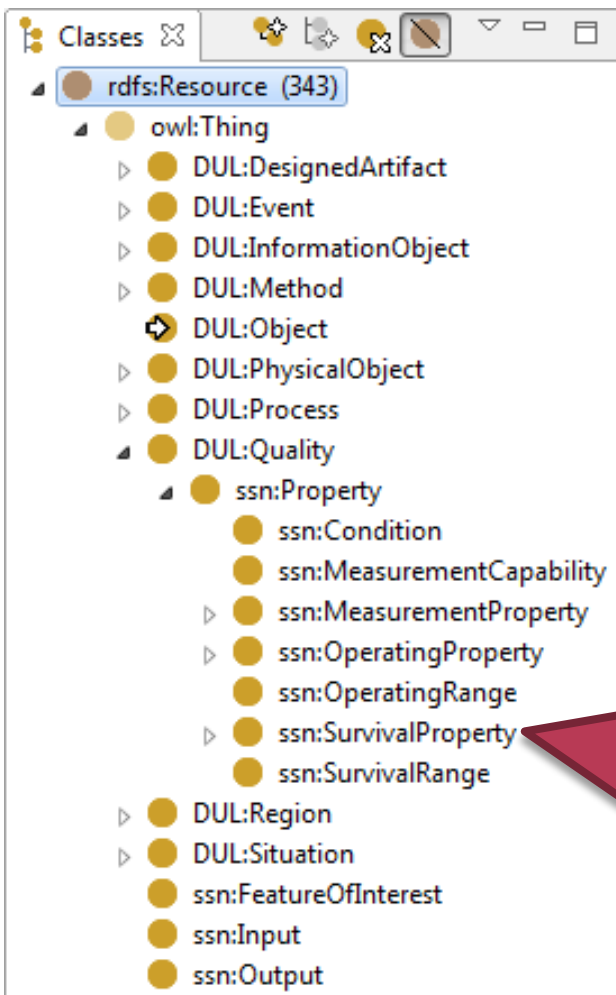
An identifiable characteristic of the environmental and other conditions in which the sensor is intended to operate.

SSN - OperatingRange

The environmental conditions of a system/sensor's normal operating environment.

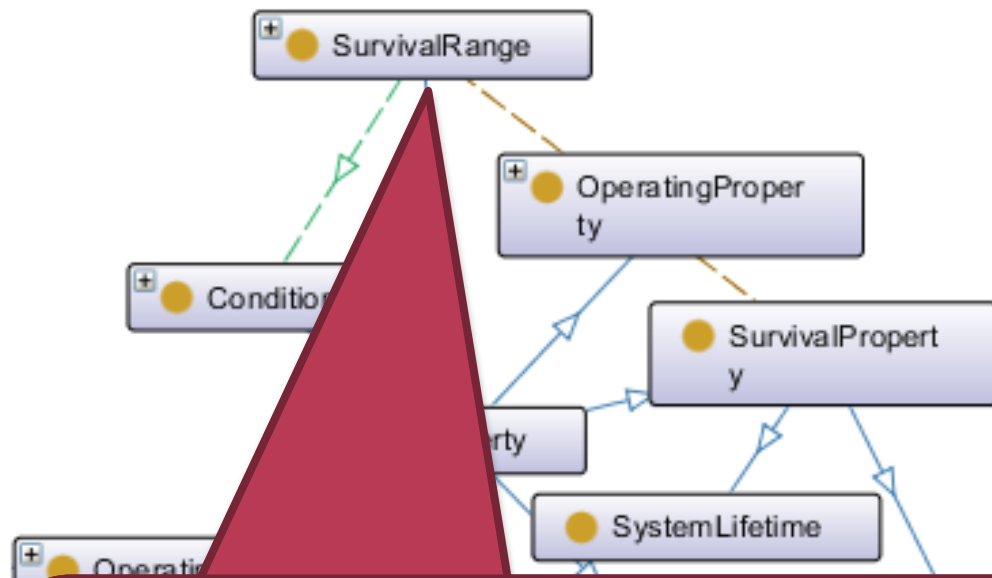
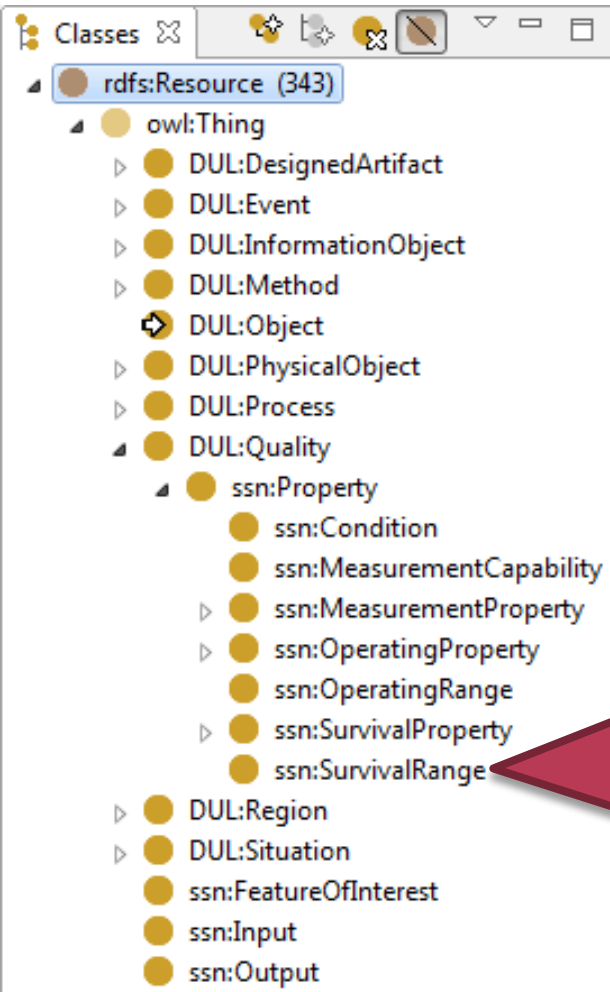


SSN - SurvivalProperty



Extent of the sensors useful life.

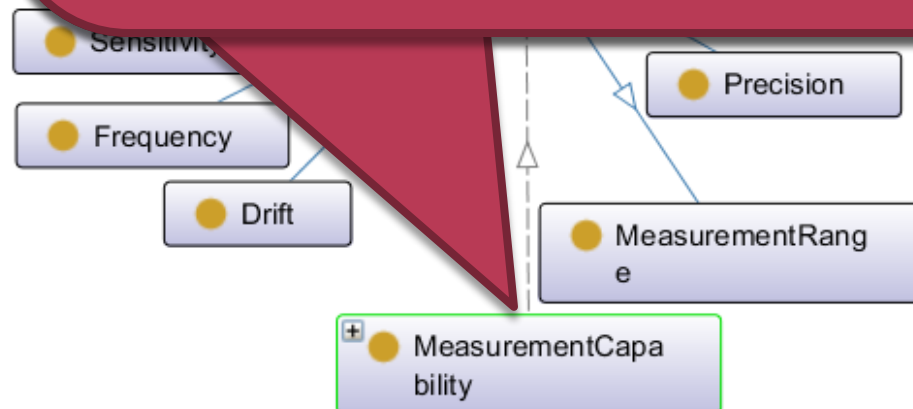
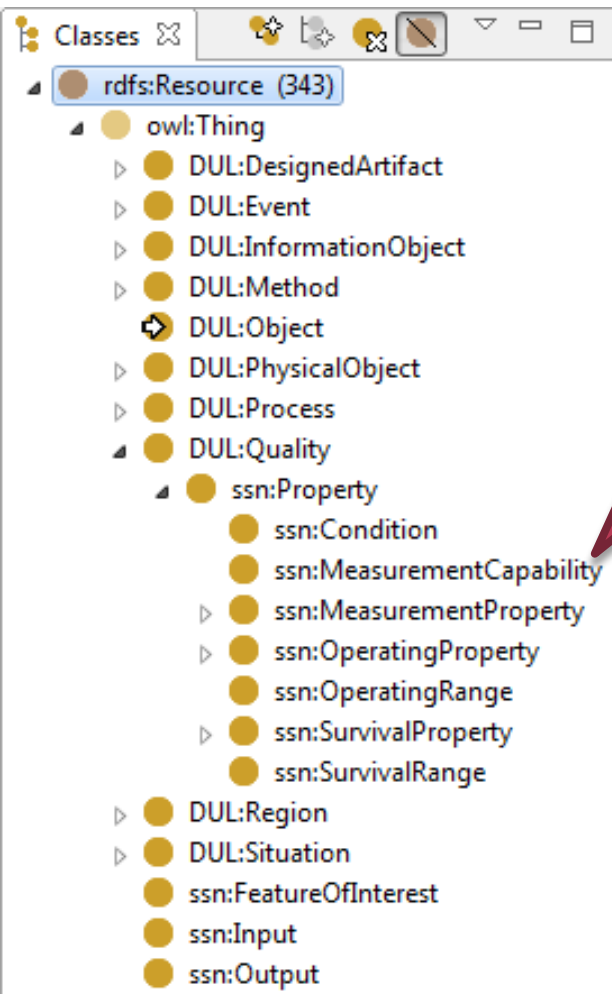
SSN – SurvivalRange



The conditions a sensor can be exposed to no damage:
i.e., the sensor continues to operate as defined using MeasurementCapability.

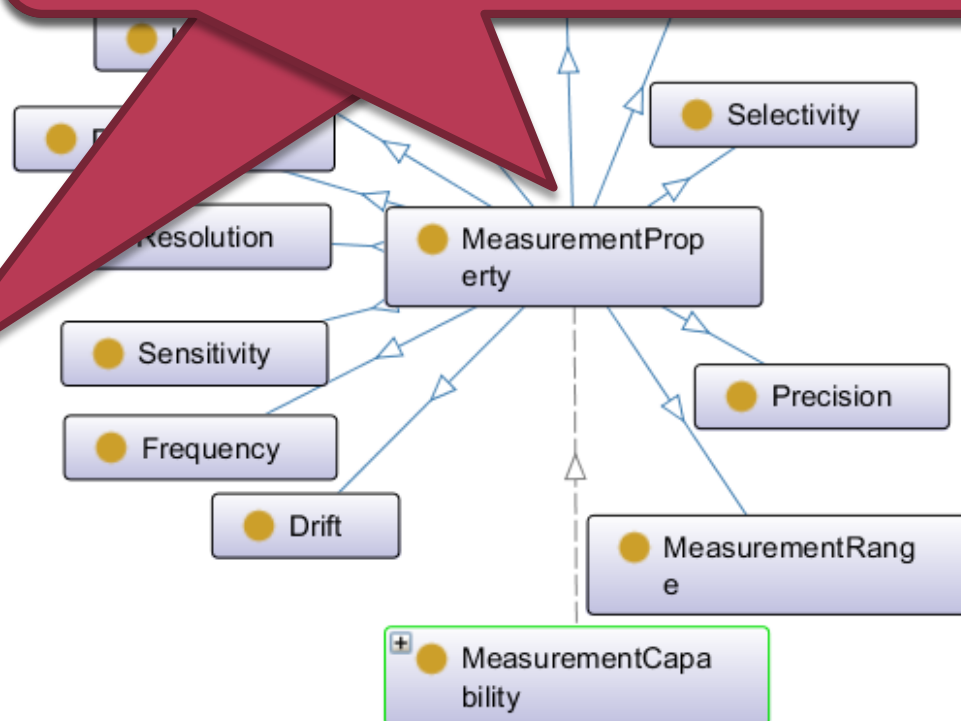
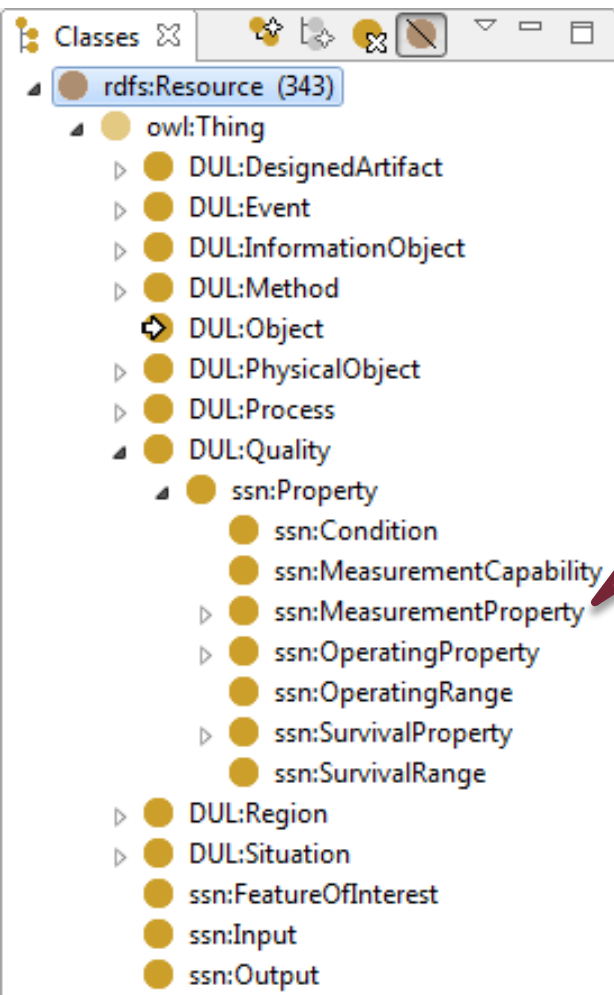
SSN - Measurement Capability

Measurement properties
(accuracy, range, precision, etc)
+
Environmental conditions

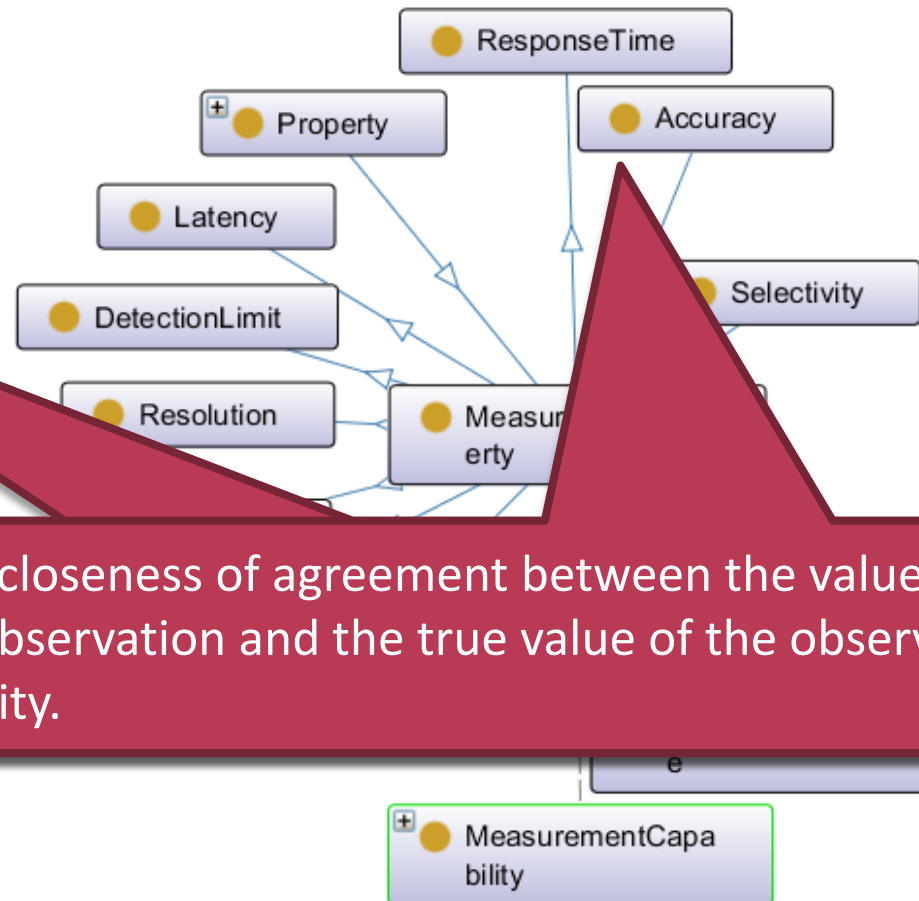
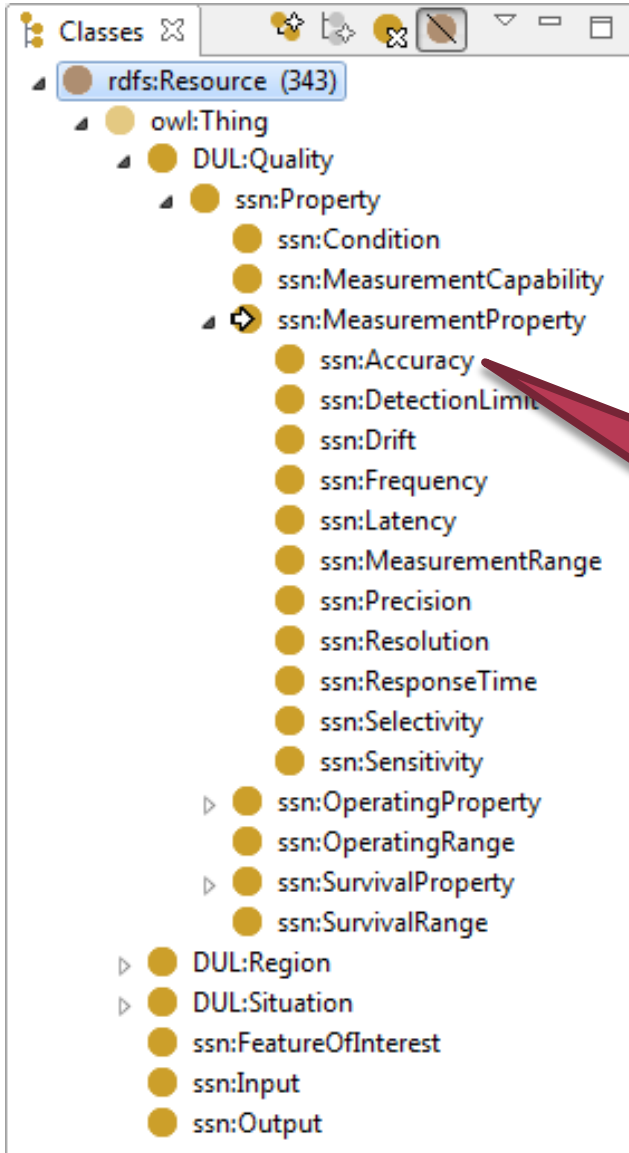


SSN - Measurement Property

An identifiable and observable characteristic of a sensor's observations or ability to make observations.

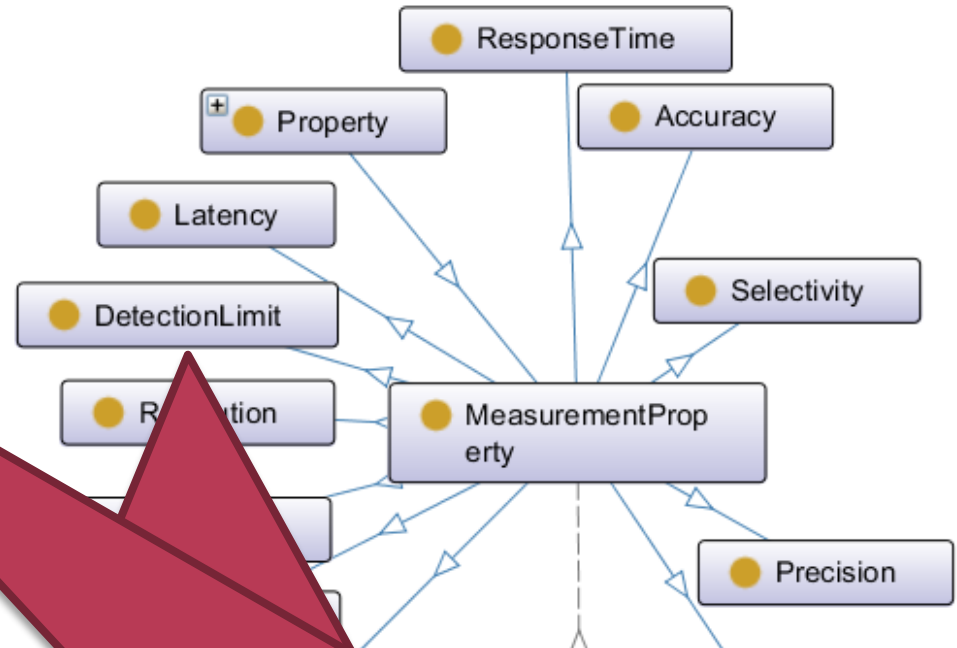
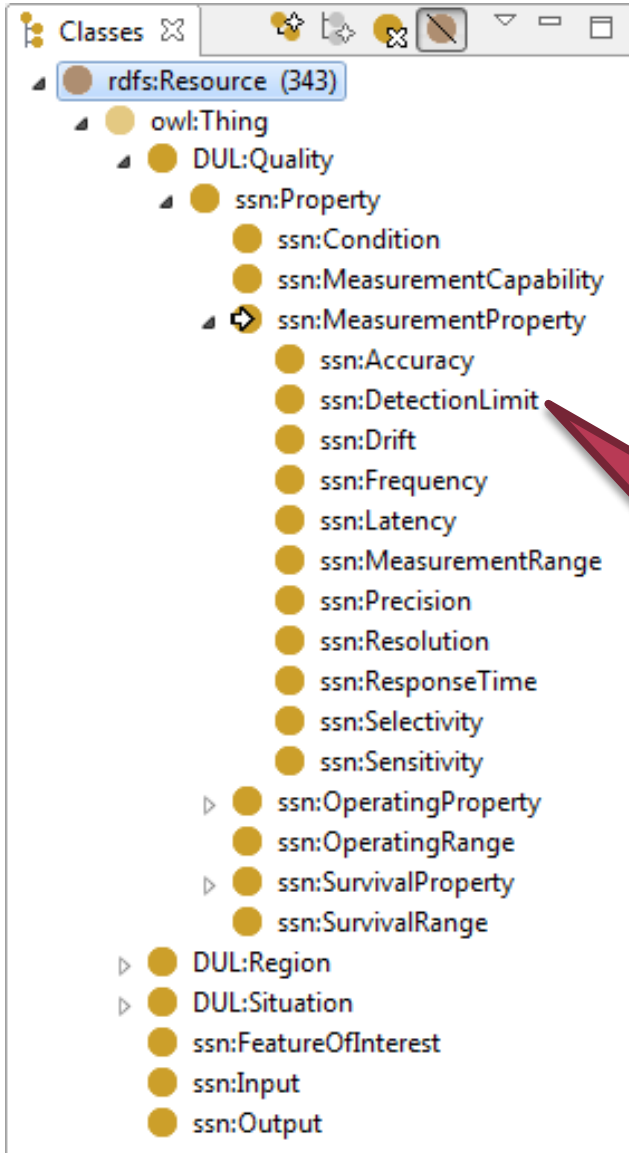


SSN - Accuracy



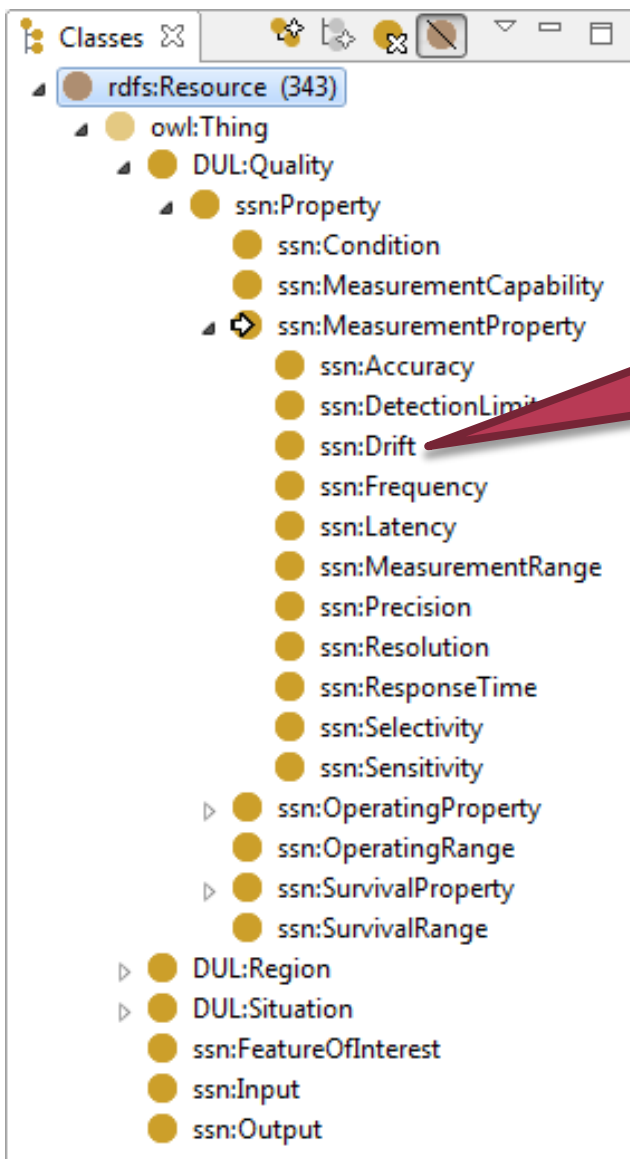
The closeness of agreement between the value of an observation and the true value of the observed quality.

SSN - DetectionLimit

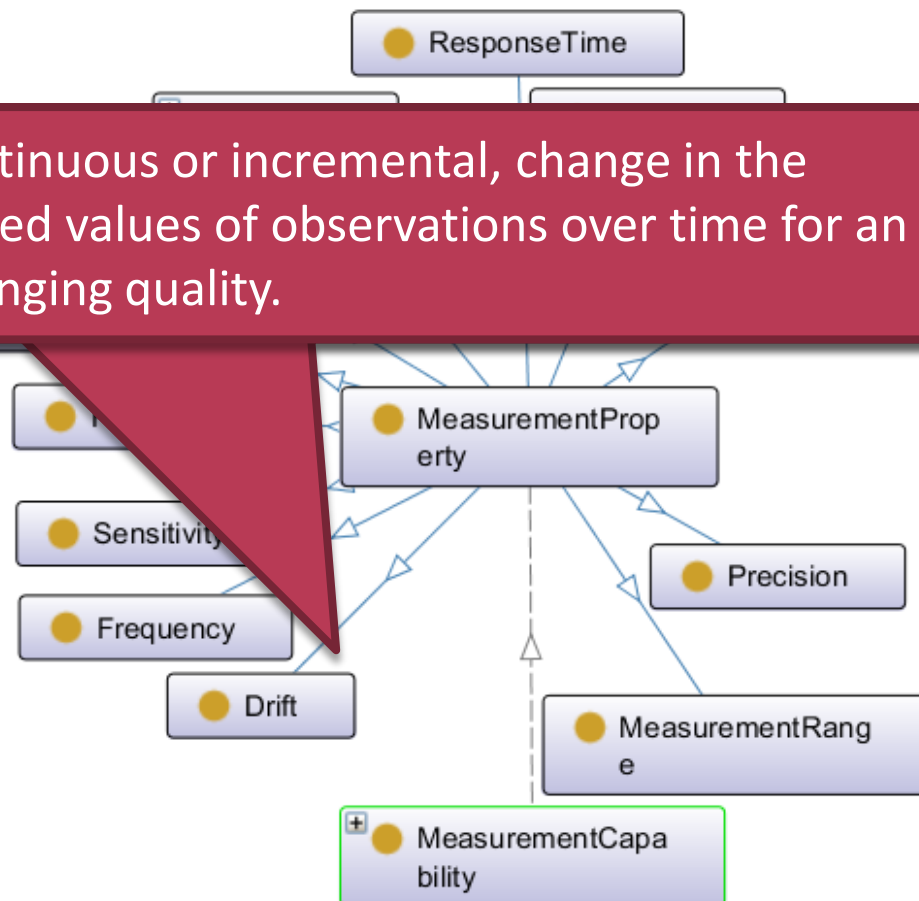


An observed value for which the probability of falsely claiming the absence of a component in a material is $\hat{I}^2$, given a probability $\hat{I} \pm$ of falsely claiming its presence.

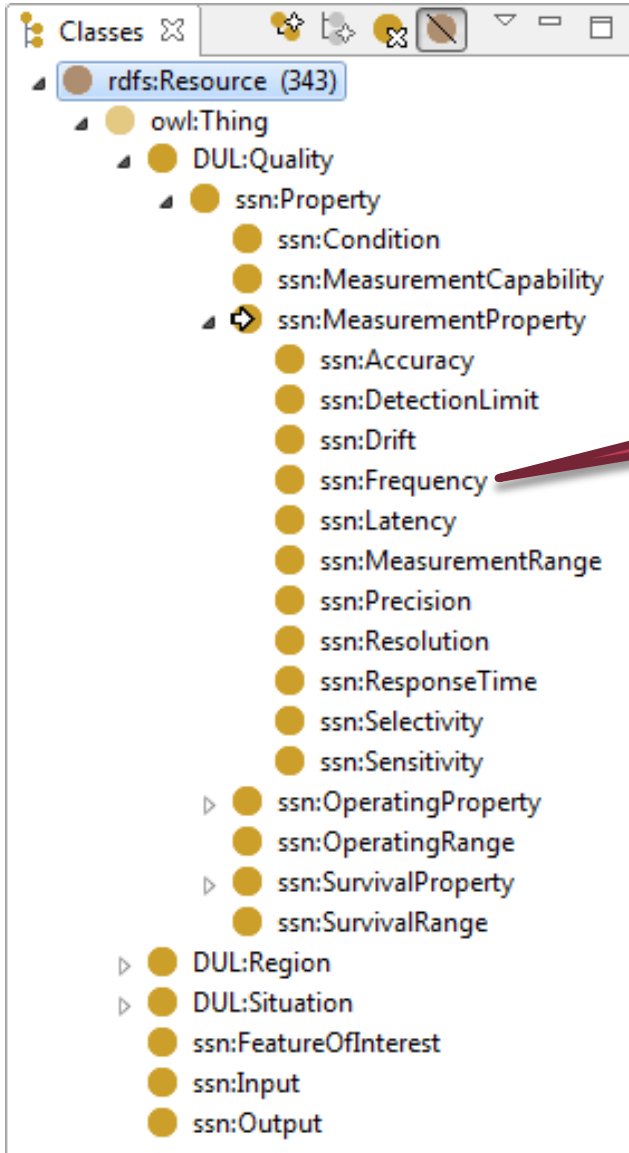
SSN - Drift



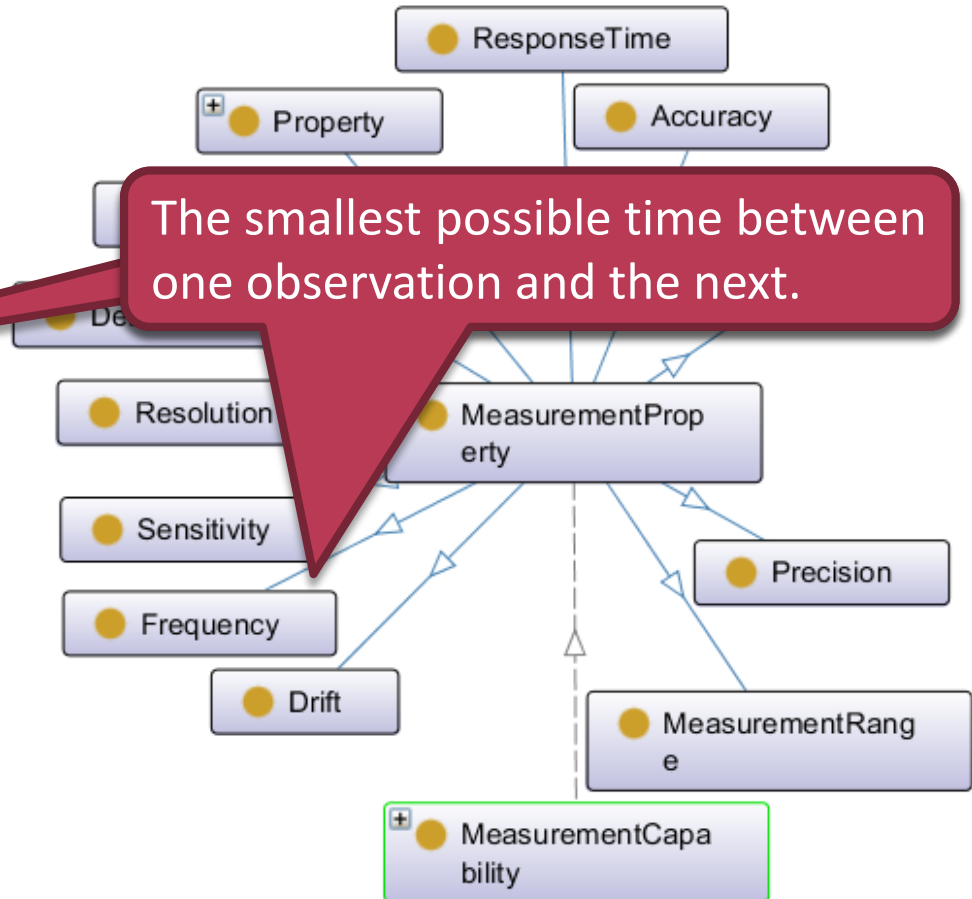
A, continuous or incremental, change in the reported values of observations over time for an unchanging quality.



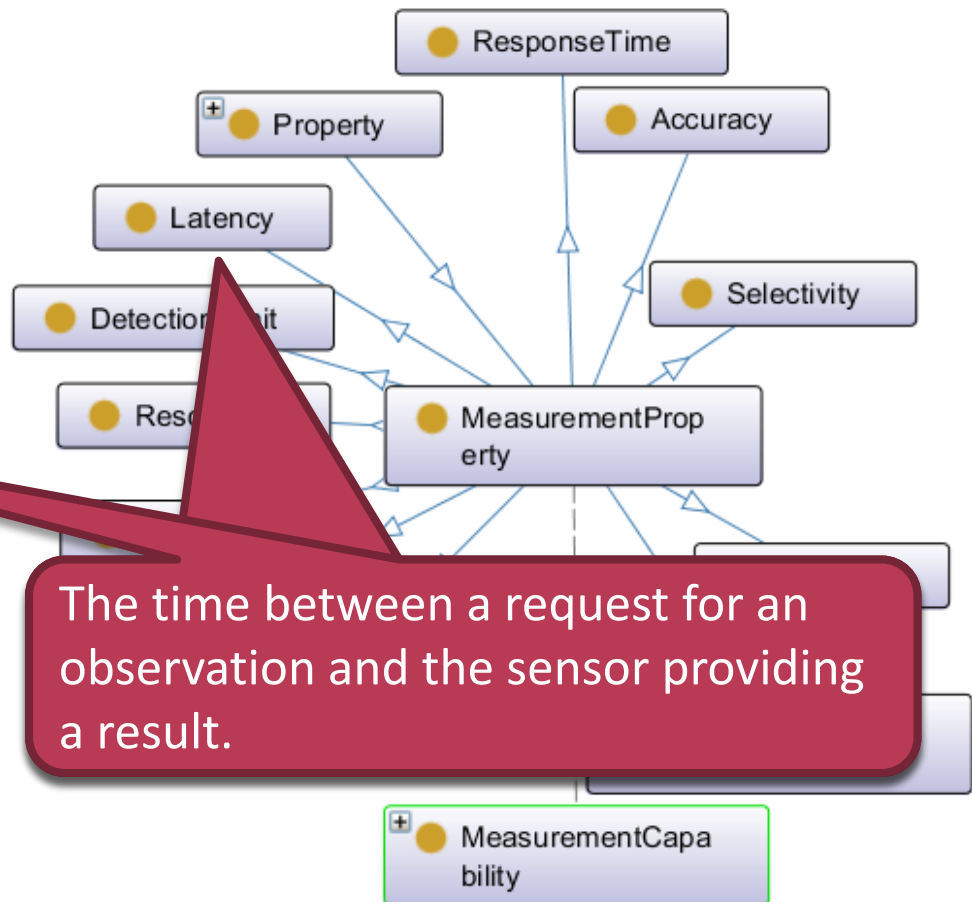
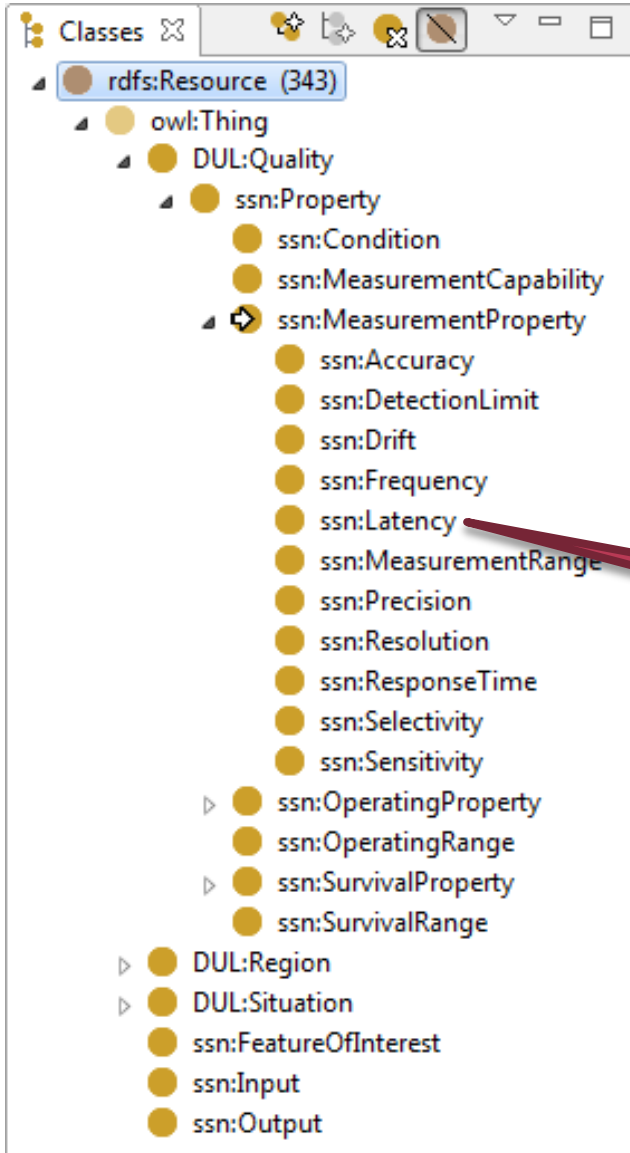
SSN - Frequency



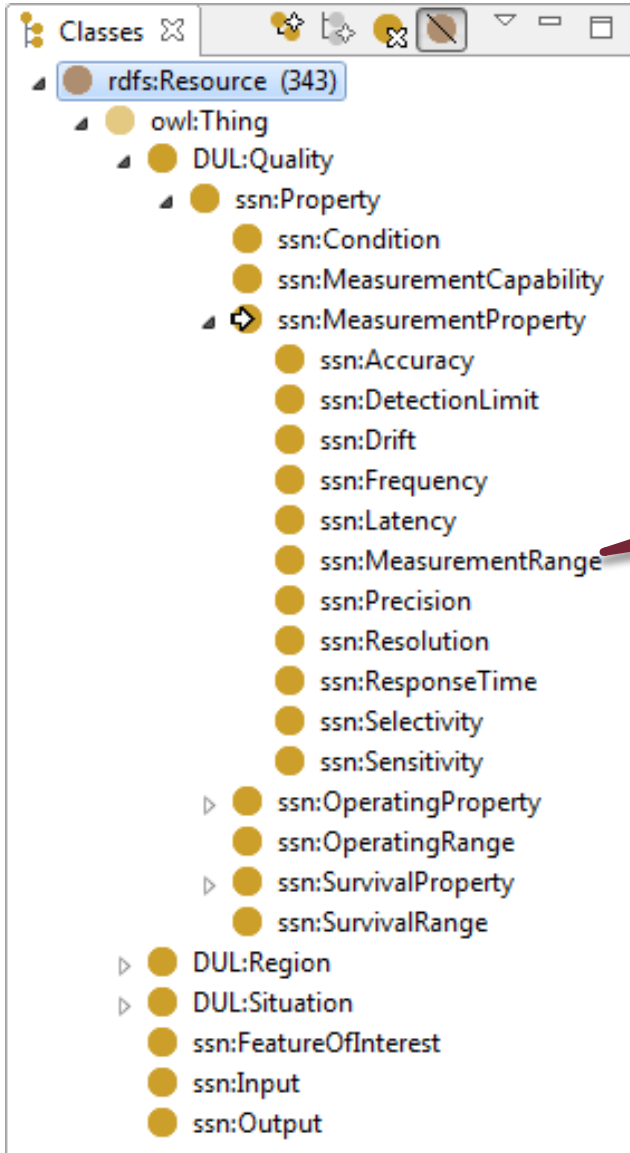
The smallest possible time between one observation and the next.



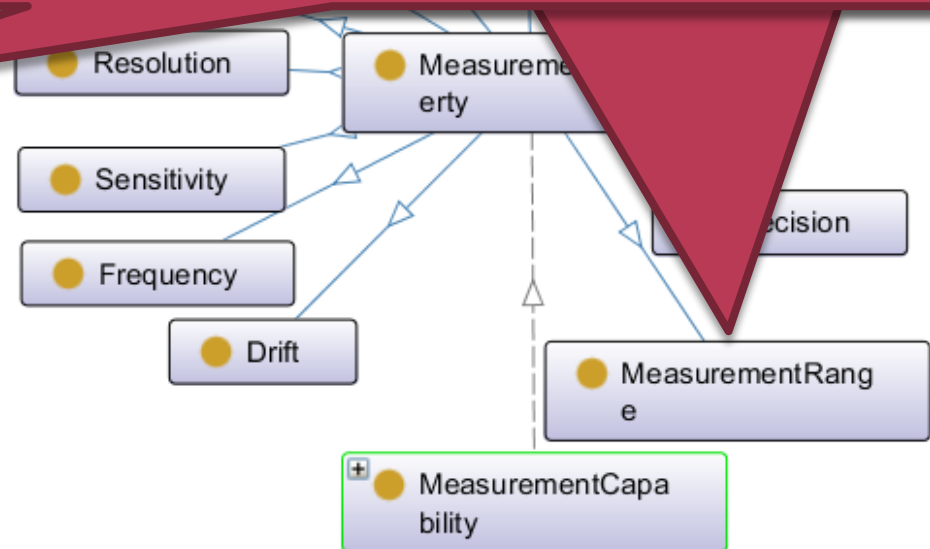
SSN - Latency



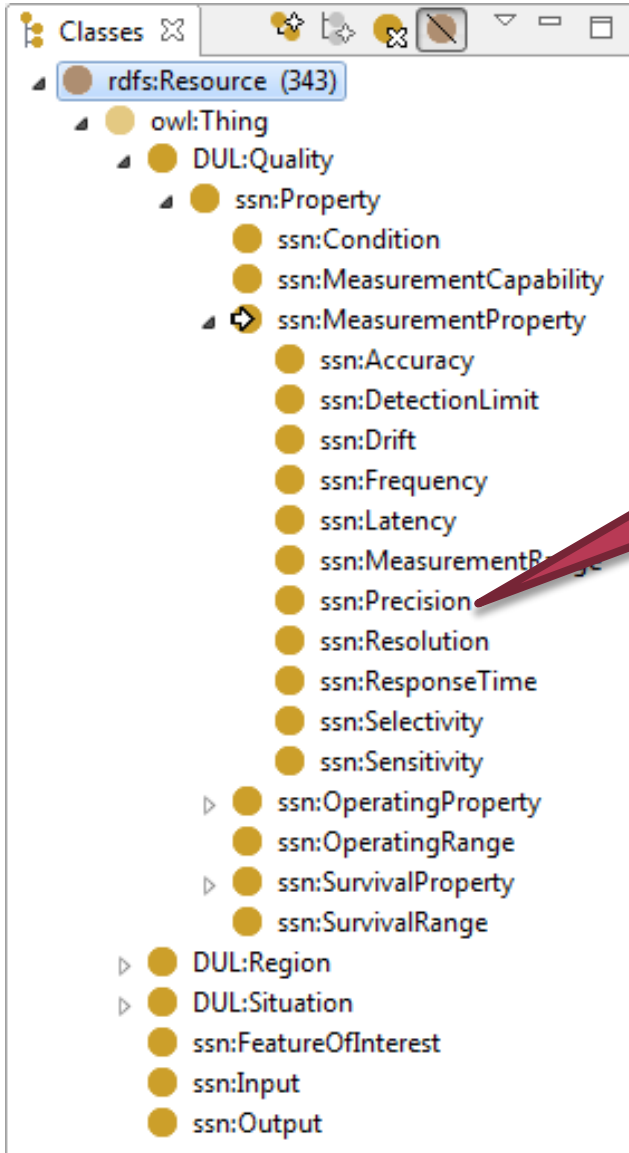
SSN - Measurement Range



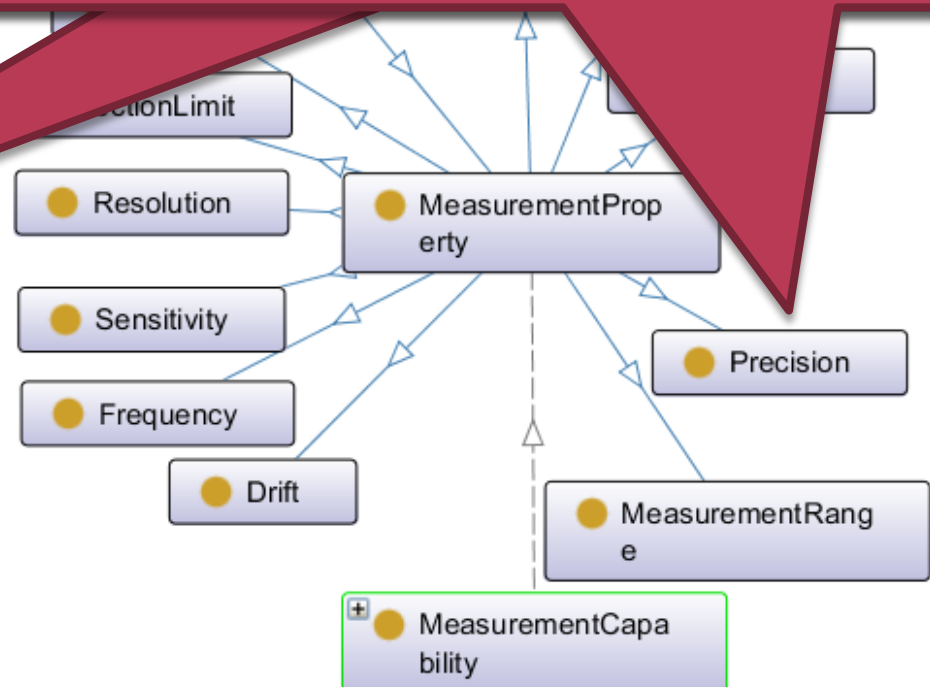
The domain of measurement results under the defined conditions



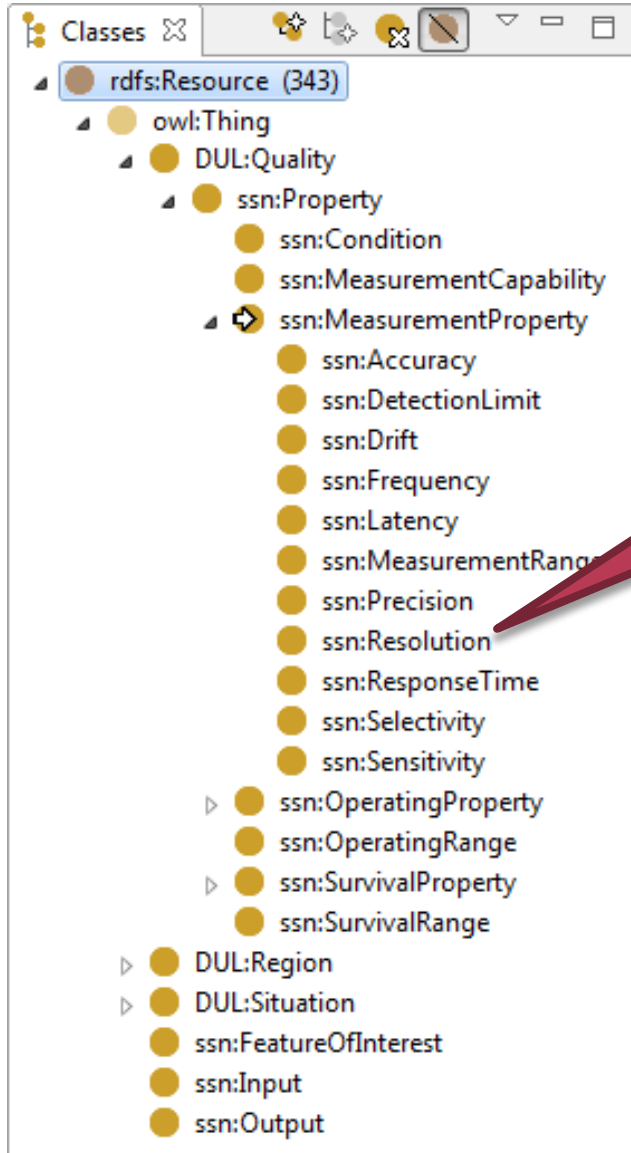
SSN - Precision



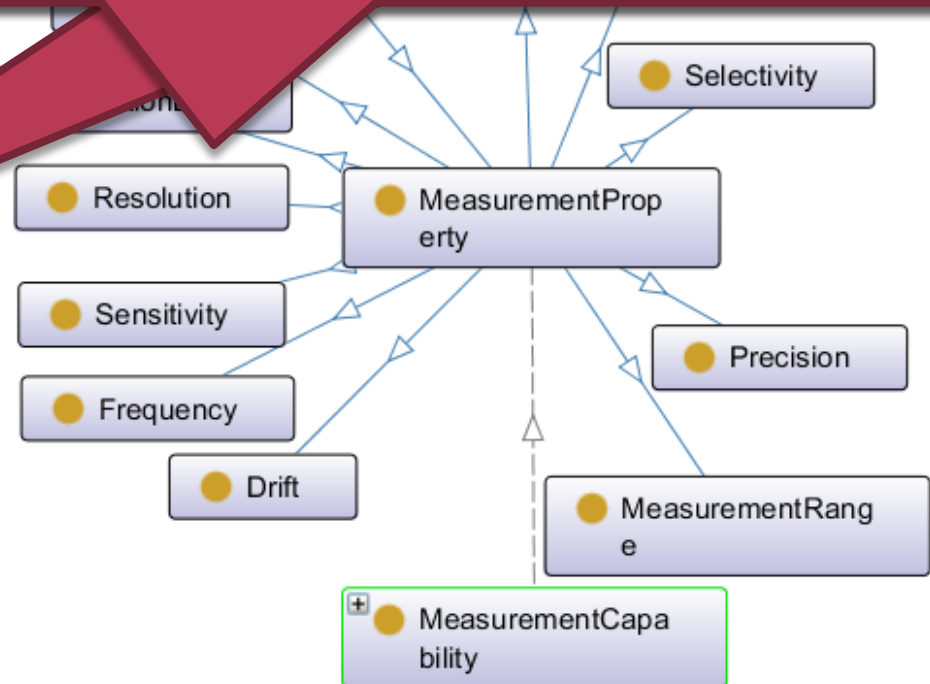
The closeness of replicated observations on an unchanged quality value:
a measure of a reproducibility



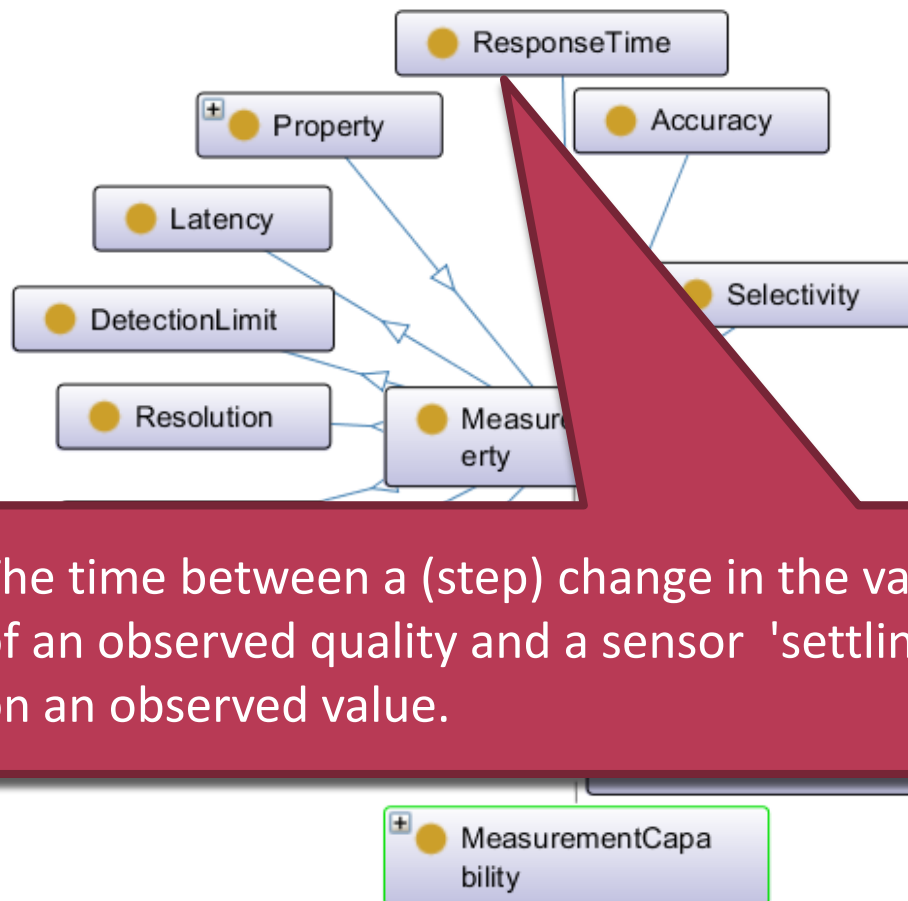
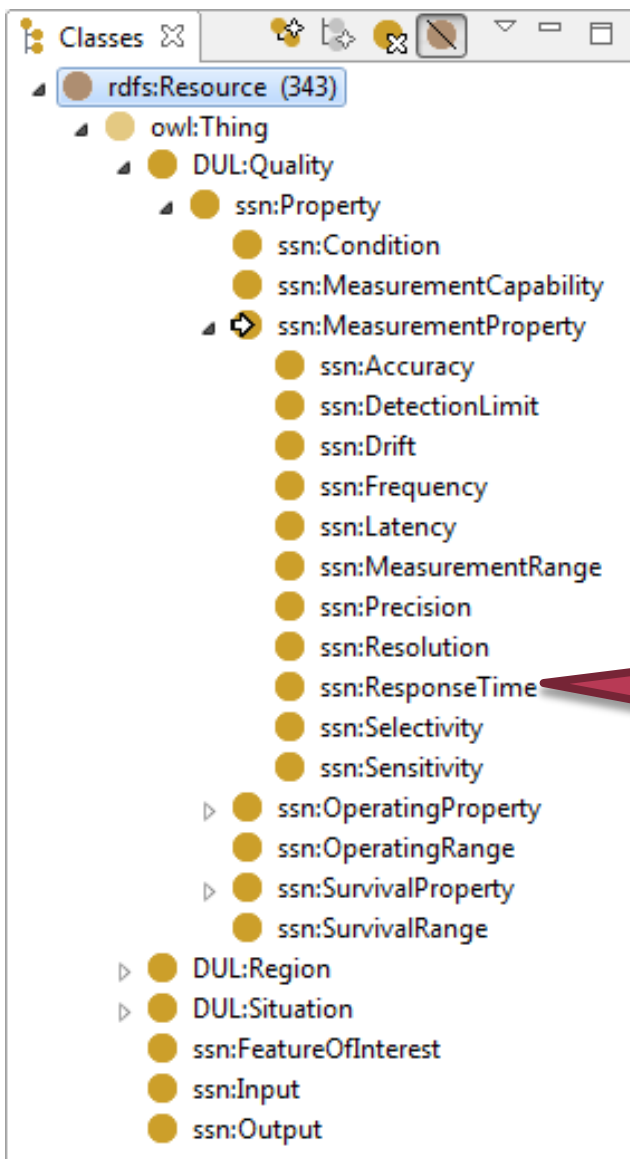
SSN - Resolution



The smallest difference in observation results.

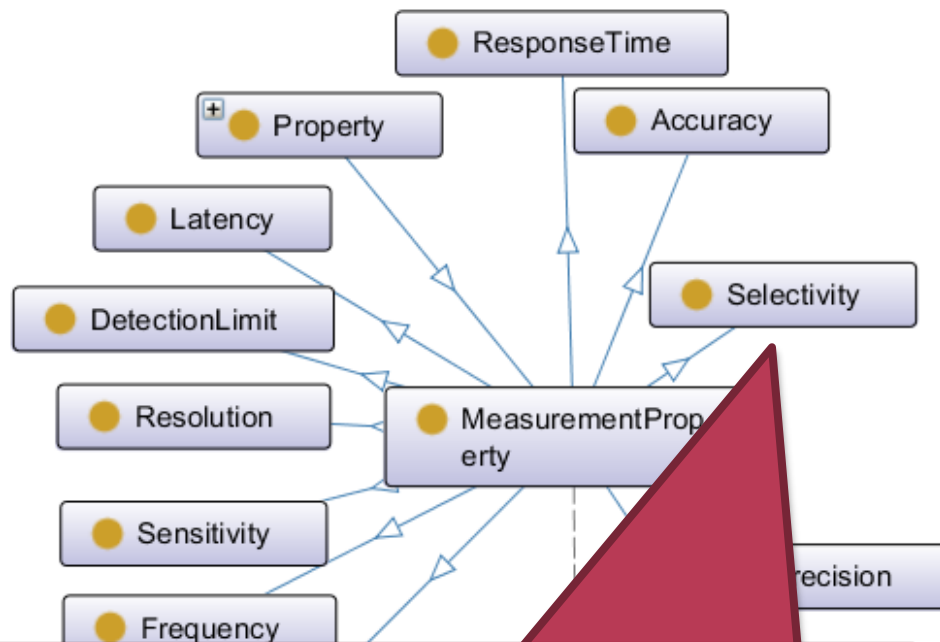
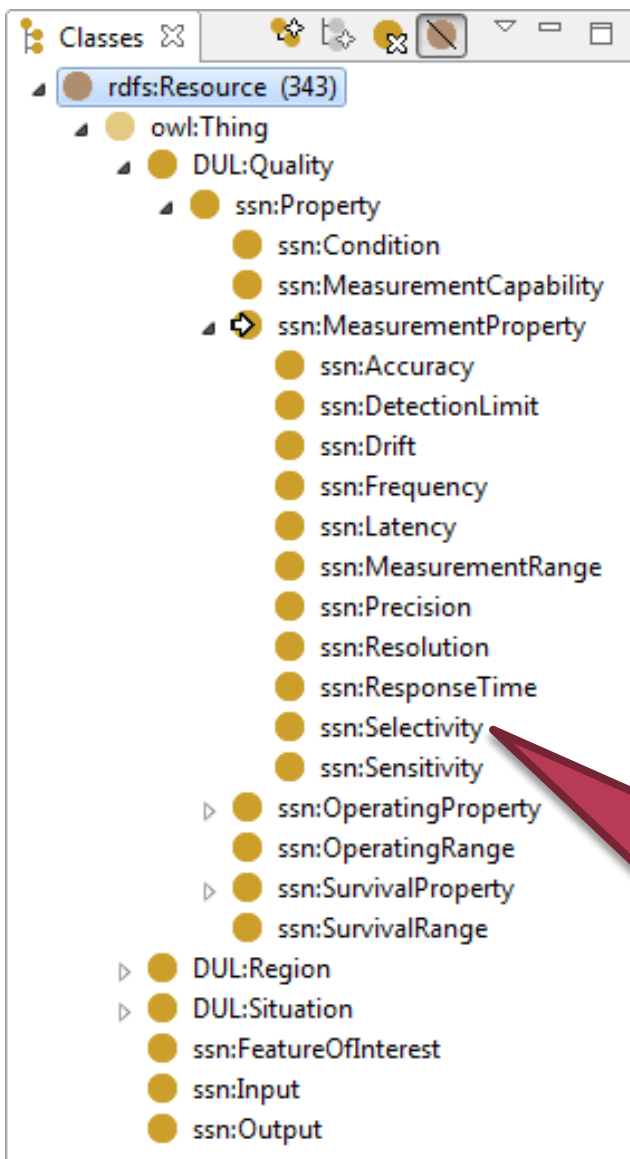


SSN – ResponseTime



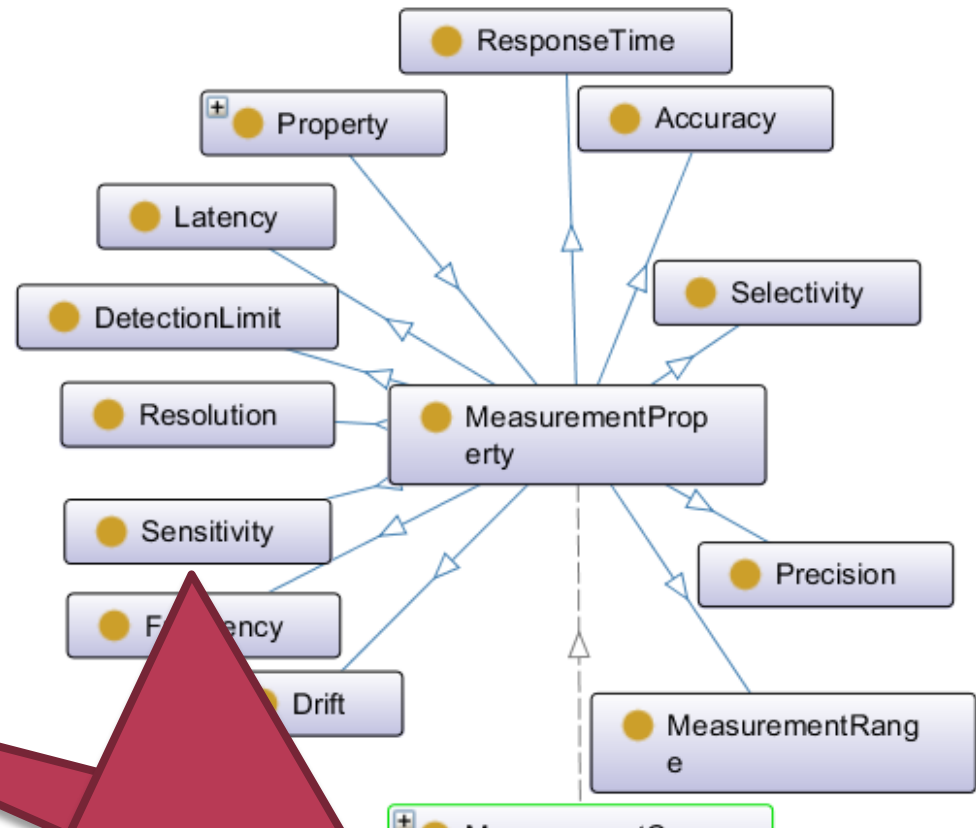
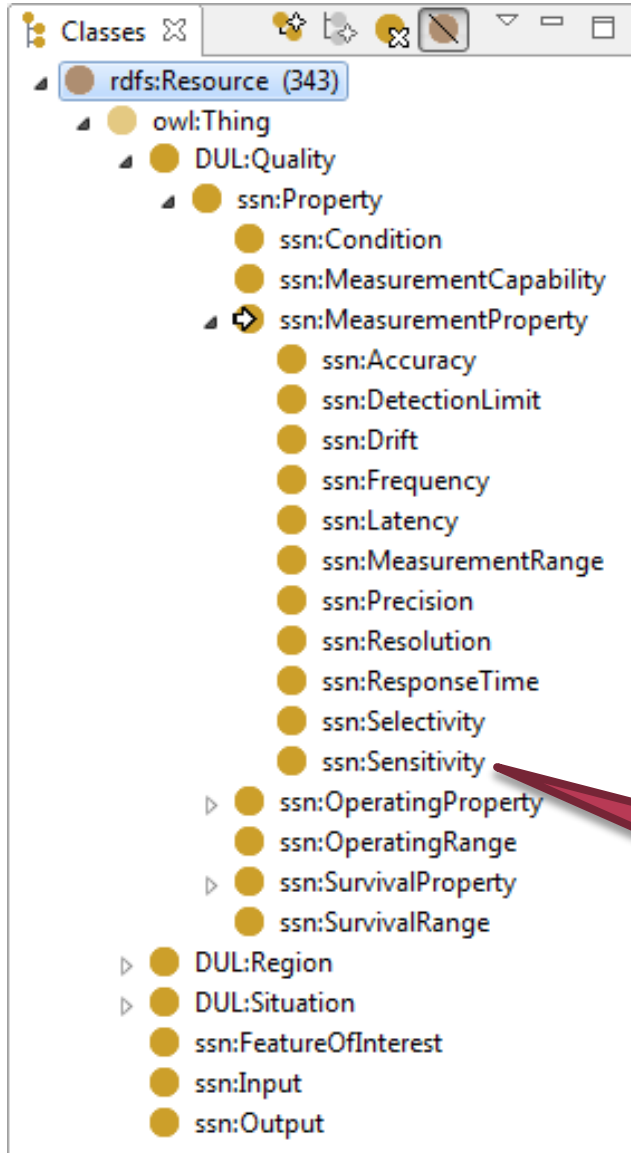
The time between a (step) change in the value of an observed quality and a sensor 'settling' on an observed value.

SSN - Selectivity



Selectivity is a property of a sensor whereby it provides observed values for one or more qualities such that the values of each quality are independent of other qualities in the phenomenon, body, or substance being investigated.

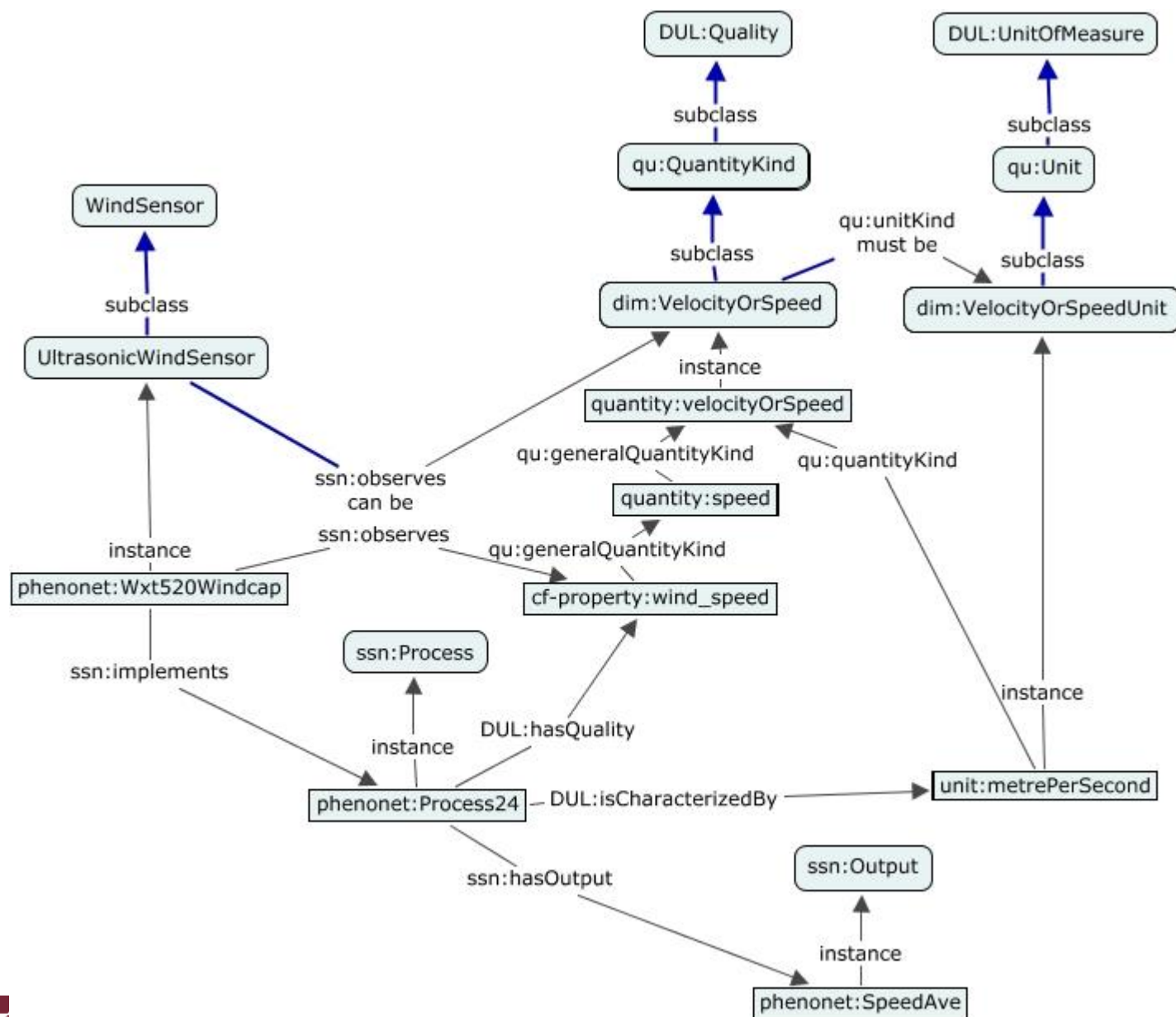
SSN - Sensitivity



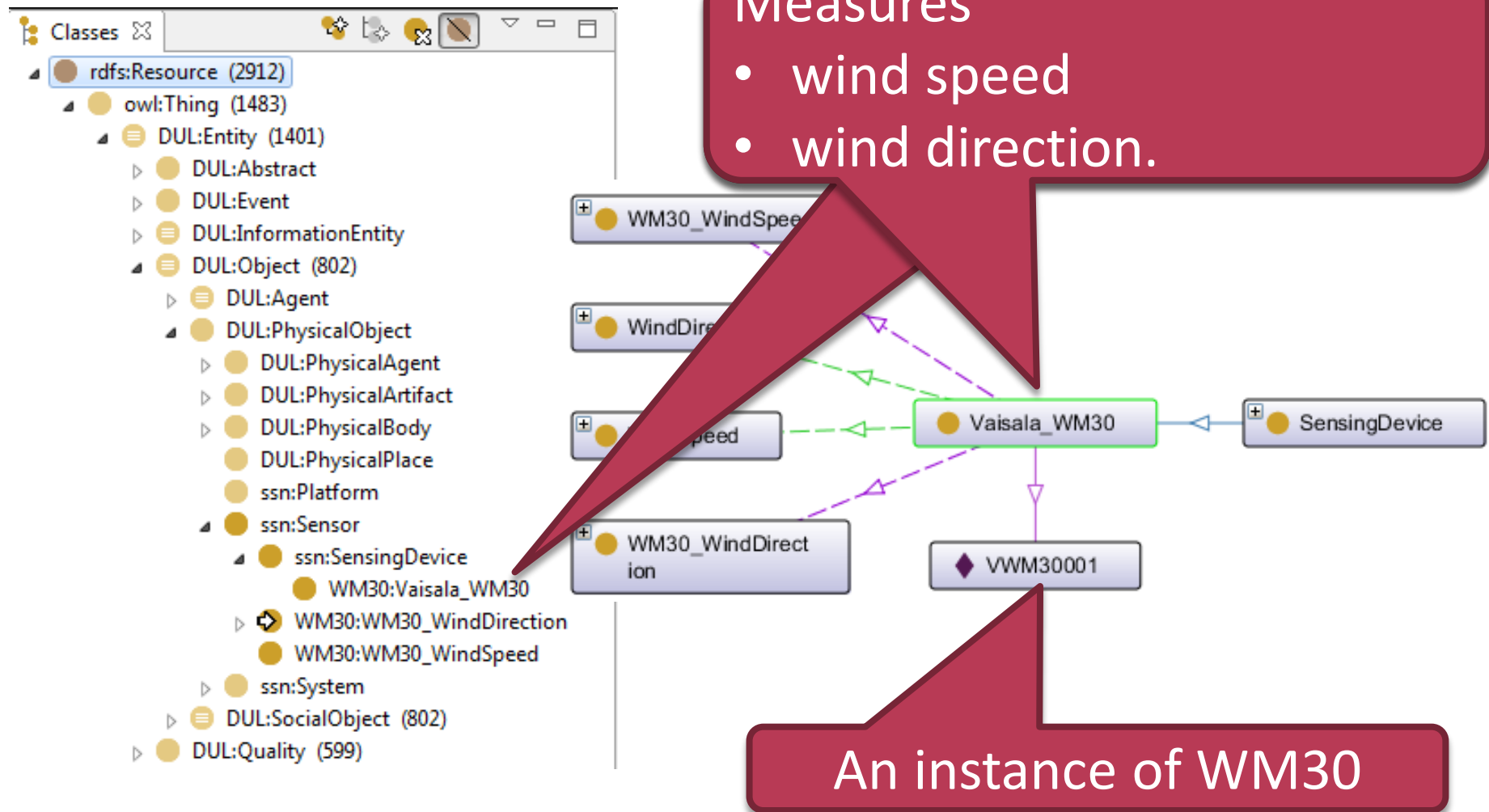
Sensitivity is the quotient of the change in a result of sensor and the corresponding change in a value of a quality being observed.

EXAMPLE: WIND SENSOR

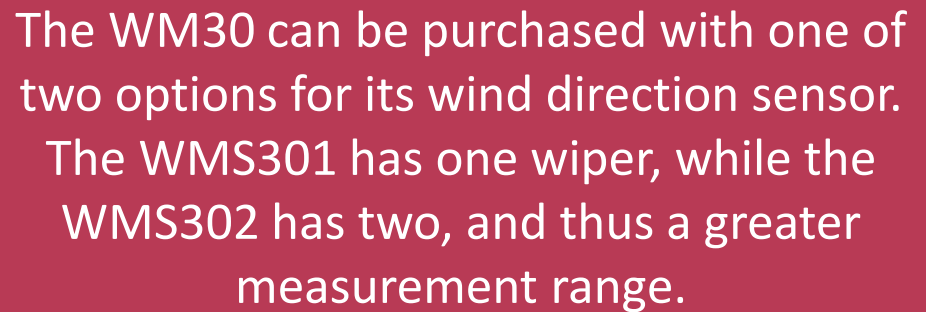
SSN example: wind sensor



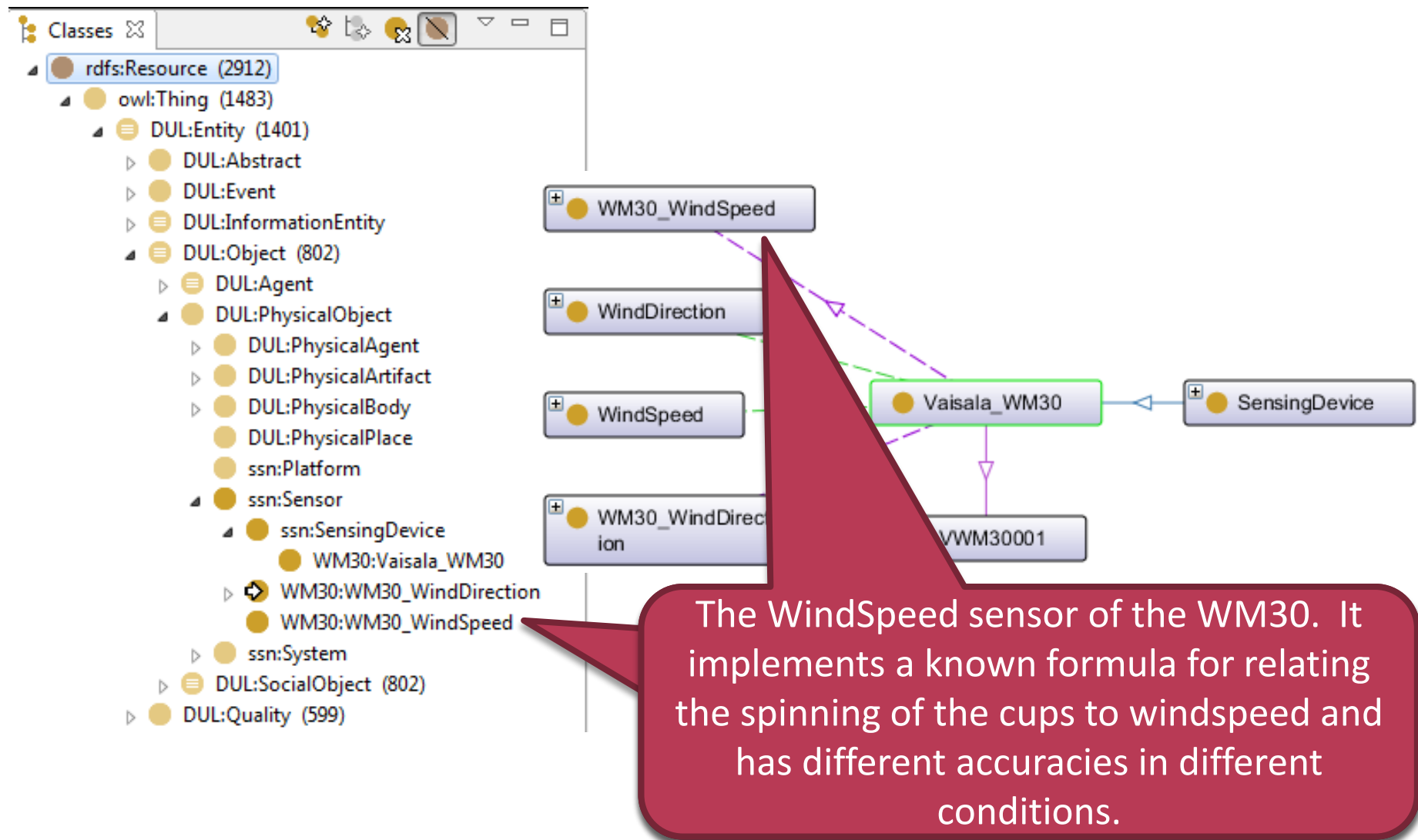
SSN – Wind Sensor



SSN – Wind Sensor



SSN – Wind Sensor



SSN – Query

Result: set of triples

The screenshot shows a SPARQL query editor with the following query:

```
SELECT ?sensing_device ?relation ?property
WHERE {
  ?sensing_device rdfs:subClassOf ssn:SensingDevice .
  ?sensing_device rdfs:subClassOf ?observes .
  ?observes owl:isProperty ssn:observes .
  ?observes owl:isProperty ?relation .
  ?observes owl:hasValuesFrom ?property .
}
```

The results table displays the following data:

[?sensing_device]	relation	property
WM30:Vaisala_WM30	ssn:observes	WM30:WindSpeed
WM30:Vaisala_WM30	ssn:observes	WM30:WindDirection

Get the all sensing device and the
observed properties of it

(sensing_device, relation, property)
→
(Viasala_WM30, observes, WindSpeed)

MEASUREMENTS IN IT INFRASTRUCTURES

SSN – Sensing Device in IT

SPARQL Execution



Query Saved Queries

Default Graph IRI

Query

```
PREFIX ssn: <http://purl.oclc.org/NET/ssnx/ssn#>
SELECT *
WHERE {
  ?sensing_device a ssn:SensingDevice .
  ?sensing_device ssn:onPlatform ?platform .
  ?sensing_device ssn:observes ?observes .
  ?platform a ?platform_is_a .
}
```

Execute

Save

Load

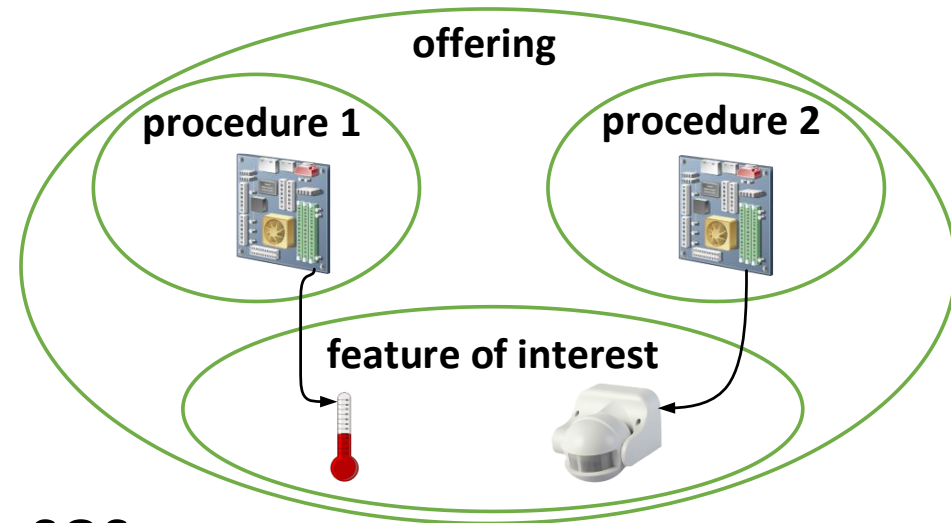
Clear

sensing_device	platform	observes	platform_is_a
http://cloudpaw/cwpoc1#beren.ftslab.local_ESXi	http://cloudpaw/cwpoc1#beren.ftslab.local	http://inf.mit.bme.hu/ontologies/cloudperf/vmware#Metric	http://inf.mit.bme.hu/ontologies/cloudperf/virtualization#PhysicalMachine
http://cloudpaw/cwpoc1#Clearwater_ESXi	http://cloudpaw/cwpoc1#Clearwater	http://inf.mit.bme.hu/ontologies/cloudperf/vmware#Metric	http://inf.mit.bme.hu/ontologies/cloudperf/virtualization#VirtualDomain
http://cloudpaw/cwpoc1#elrond.ftslab.local_ESXi	http://cloudpaw/cwpoc1#elrond.ftslab.local	http://inf.mit.bme.hu/ontologies/cloudperf/vmware#Metric	http://inf.mit.bme.hu/ontologies/cloudperf/virtualization#PhysicalMachine
http://cloudpaw/cwpoc1#luthien.ftslab.local_ESXi	http://cloudpaw/cwpoc1#luthien.ftslab.local	http://inf.mit.bme.hu/ontologies/cloudperf/vmware#Metric	http://inf.mit.bme.hu/ontologies/cloudperf/virtualization#PhysicalMachine

ONTOLOGIES AS STORAGE SCHEMA MODELS

Sensor Observation Service (SOS)

- Abstracts sensor data and communication
 - Self-describing sensor information database
 - Stores sensor data with geographic relevance
 - Efficient data queries
 - temporal or spatial filters
- Members of the CPS
 - direct communication with the SOS



RDF datastore

- Resource Description Framework (RDF)
- Stores statements:
 - { subject, predicate, object } triples
- OWL → RDF
 - ABox axioms:
 - { Instance1 rdf:type Class1 }
 - { Instance1 hasProperty “value”^^xsd:string }
 - OWL: schema, RDF: data
- NoSQL, graph-based databases
 - SPARQL: query language, based on pattern matching
 - OWL reasoning

Architecture

