

Examples:
Modelling formalisms, temporal logics,
model checking

dr. István Majzik
BME Department of Measurement and Information Systems

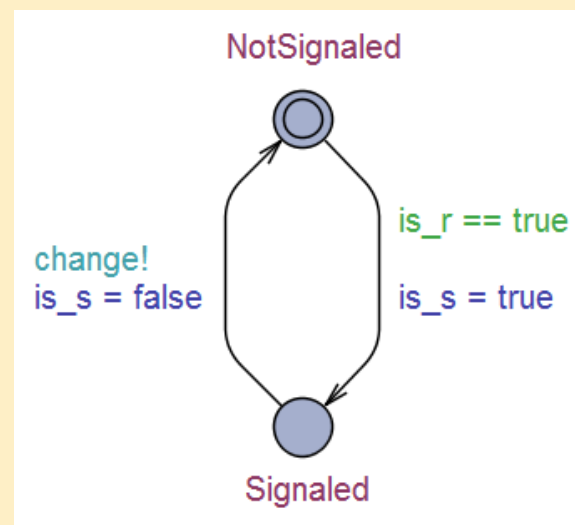
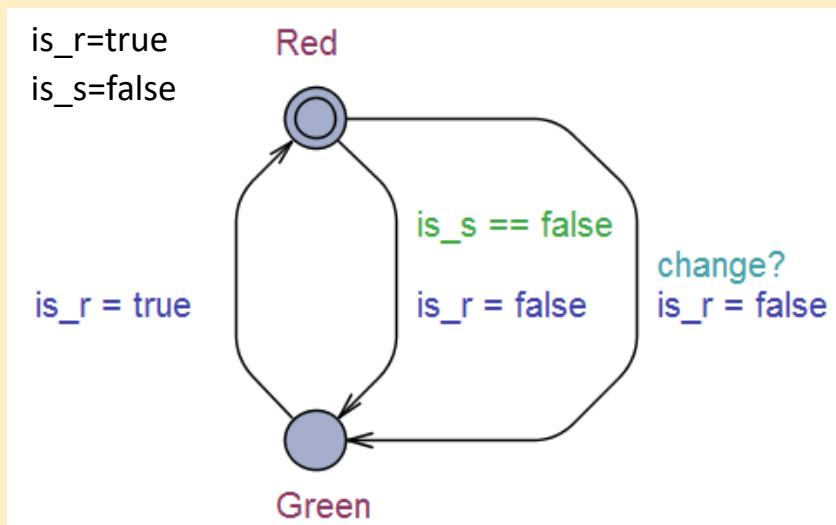
Interpretation of formal models

Interpretation of automata models

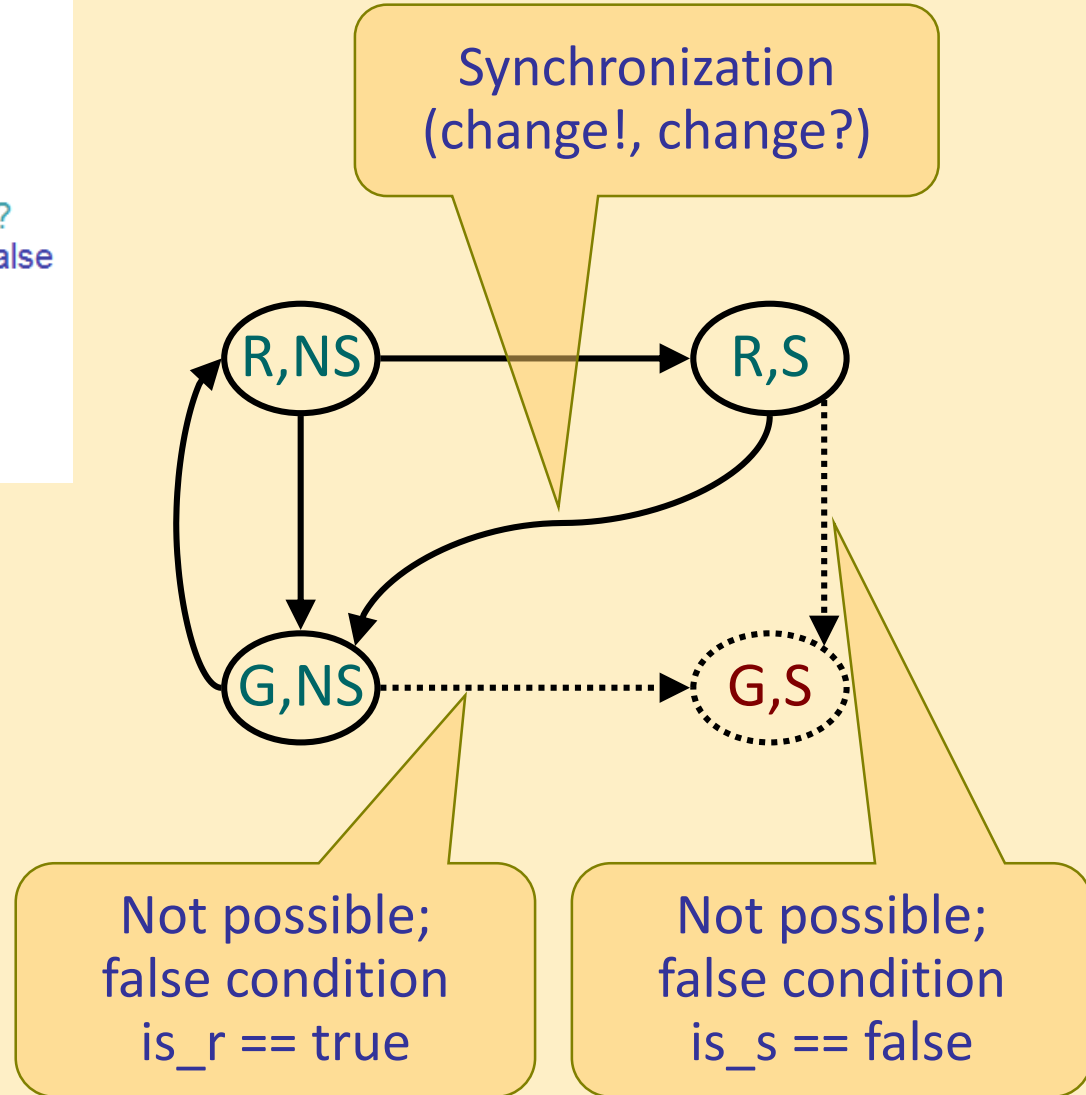
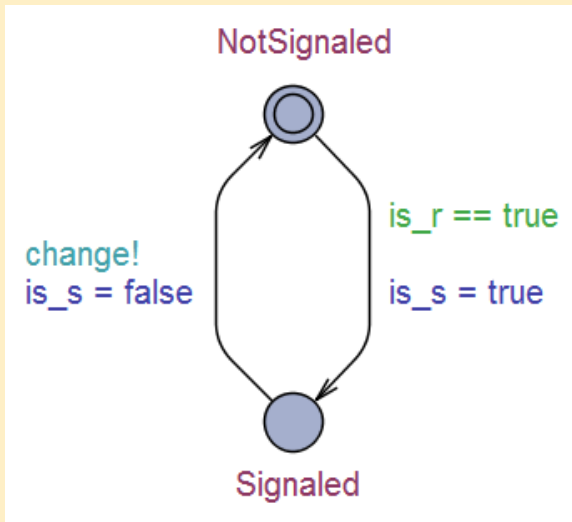
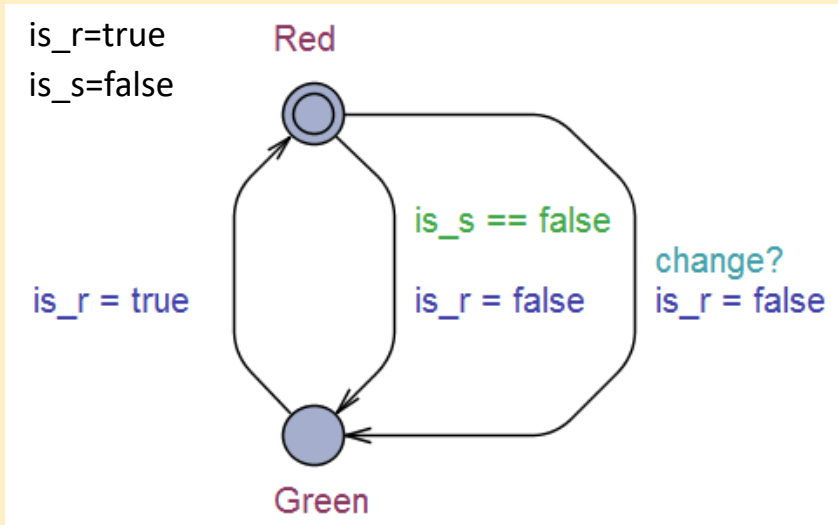
Consider the following two automata models (constructed in the UPPAAL tool) that model the behavior of a traffic light and a pedestrian. In the initial state $is_r=true$ and $is_s=false$.

- Draw the Kripke structure corresponding to the **whole system**, i.e., the reachable **combinations of the states** of the traffic light and the pedestrian, and the related transitions!

Label each combined state with the names of the states that it represents (you can use the initial letters of the states).



Interpretation of automata models – Solution



Formalization of properties using temporal logics

Theoretical questions

Argue if the following LTL equivalences are correct or not:

1. $F(\text{Start} \vee \text{Stop}) \equiv (F \text{ Start}) \vee (F \text{ Stop})$
2. $G \text{ Stop} \equiv \text{not } F(\text{not Stop})$

Argue if the following CTL equivalences are correct or not:

1. $AF(\text{Start} \vee \text{Stop}) \equiv (AF \text{ Start}) \vee (AF \text{ Stop})$
2. $AF(\text{Start} \wedge \text{Stop}) \equiv (AF \text{ Start}) \wedge (AF \text{ Stop})$
3. $EF(\text{Start} \wedge \text{Stop}) \equiv (EF \text{ Start}) \wedge (EF \text{ Stop})$

Argue if the following formula are syntactically correct in CTL or not:

1. $A(X \text{ Stop} \vee F \text{ Start})$
2. $A(\text{Stop} U (AX \text{ Start}))$

Theoretical questions – Solution 1/3

Argue if the following LTL equivalences are correct or not:

1. $F(\text{Start} \vee \text{Stop}) \equiv (F \text{ Start}) \vee (F \text{ Stop})$

Correct: Left side of the equivalence follows from the right side of the equivalence and vice versa.

2. $G \text{ Stop} \equiv \text{not } F(\text{not Stop})$

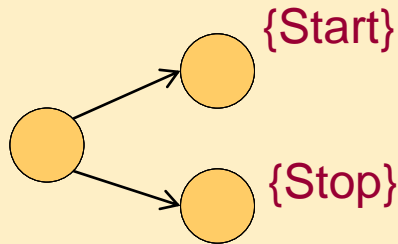
Correct: Left side of the equivalence follows from the right side of the equivalence and vice versa.

Theoretical questions – Solution 2/3

Argue if the following CTL equivalences are correct or not:

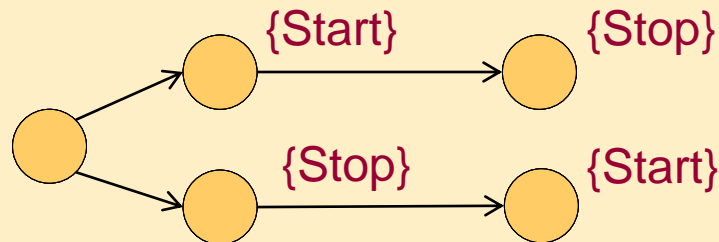
1. $AF (Start \vee Stop) \equiv (AF Start) \vee (AF Stop)$

Counterexample 1: Left side of the equivalence is true but right is not.



2. $AF (Start \wedge Stop) \equiv (AF Start) \wedge (AF Stop)$

Counterexample 2: Right side of the equivalence is true but left is not.



3. $EF (Start \wedge Stop) \equiv (EF Start) \wedge (EF Stop)$

Counterexample 1 above: Right side is true but left is not.

Theoretical questions – Solution 3/3

Argue if the following formula are syntactically correct in CTL or not:

1. $A (X \text{ Stop} \vee F \text{ Start})$

Not syntactically correct in CTL: There is Boolean operator \vee between two path expressions $X \text{ Stop}$ and $F \text{ Start}$ (and this is not allowed in CTL)

2. $A (\text{Stop} U (AX \text{ Start}))$

Correct: Here the operator AU is applied on two state expressions Stop and $AX \text{ Start}$

Requirement formalization: Railway crossing

- We model the behavior of a railway crossing **signal** with the following atomic labels:
{off, white, red}
- The behavior of the car **driver** arriving at the crossing is modeled with the following atomic labels:
{arriving, looking, stopping, crossing}
- Use LTL expressions to formalize the following properties which apply to the behavior of the driver **in every case (continuously)**:
 1. If the signal is **off**, the driver will be **looking** and then in the next moment either **stopping** or **crossing**.
 2. The driver will eventually **cross** the crossing.
 3. If upon **arrival**, the signal is **red**, the driver will not cross until the signal is **white**.

Railway crossing – Solution

- Labels for the signal:
{off, white, red}
- Labels for the driver:
{arriving, looking, stopping, crossing}
- LTL expressions formalizing the properties:
Note: “apply ... in every case (continuously)”: initial **G** operator
 1. If the signal is off, the driver will be looking and then in the next moment either stopping or crossing.
 $\mathbf{G} (\text{off} \rightarrow (\text{looking} \wedge \mathbf{X} (\text{stopping} \vee \text{crossing})))$
 2. The driver will eventually cross the crossing.
 $\mathbf{G F} \text{crossing}$
 3. If upon arrival, the signal is red, the driver will not cross until the signal is white.
 $\mathbf{G} ((\text{arrival} \wedge \text{red}) \rightarrow ((\neg \text{crossing}) \mathbf{U} \text{white}))$

Requirement formalization: Server room

- We model the states of a **server** performing complex simulation with the following atomic labels:
{off, waiting, warm-up, simulation}
- The **air-conditioning system** is modeled with the following atomic labels:
{stand-by, normal, maximal}
- Use LTL expressions to formalize the following properties which apply to the behavior of the **server continuously**:
 1. If in any moment the **simulation** is performed with the air-conditioning system being in the **stand-by** state, then in the next moment, the server will move to the **waiting** state.
 2. Eventually, the **simulation** will be started.
 3. The **simulation** can be performed only if it was preceded by a **warm-up** phase with the air-conditioning in the **normal** state.

Server room – Solution

- Labels for the server:
 {off, waiting, warm-up, simulation}
- Labels for the air-conditioning system:
 {stand-by, normal, maximal}

- LTL expressions formalizing the properties:

Note: “apply ... continuously”: initial **G** operator

1. If in any moment the **simulation** is performed with the air-conditioning system being in the **stand-by** state, then in the next moment, the server will move to the **waiting** state.

G ((**simulation** \wedge **stand-by**) \rightarrow **X** **waiting**)

2. Eventually, the **simulation** will be started.

G F **simulation**

3. The **simulation** can be performed only if it was preceded by a **warm-up** phase with the air-conditioning in the **normal** state.

G ((**X** **simulation**) \rightarrow (**warm-up** \wedge **normal**))

Model checking algorithms

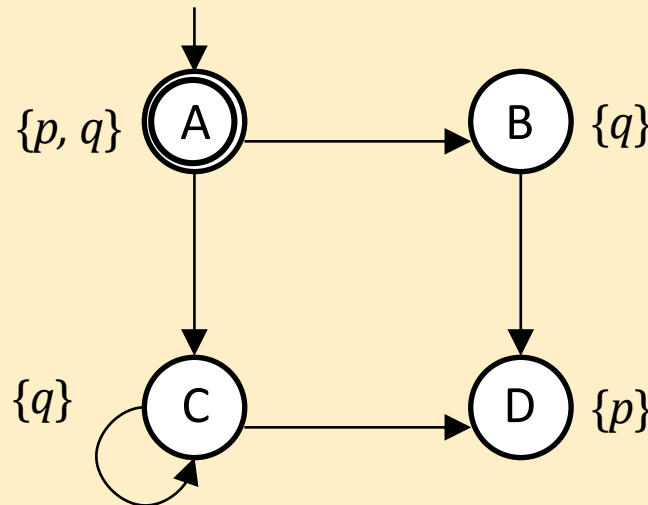
Checking CTL using iterative labeling

Consider the Kripke structure given below.

- Check if the following CTL expression holds from the initial state using the iterative labeling algorithm presented in the lectures:

$$A(p \text{ U } (\text{EX } \neg q))$$

For each iteration give the expression that is currently used for labeling and enumerate the states that are labeled!

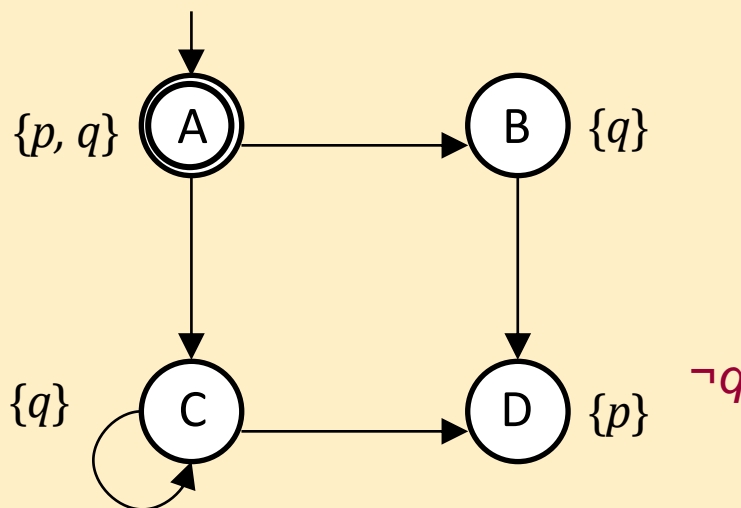


Checking CTL using iterative labeling – Solution 1/4

Check if the following CTL expression holds from the initial state using the iterative labeling algorithm:

$$A(p \text{ U } (\text{EX } \neg q))$$

1. Labeling D with $\neg q$

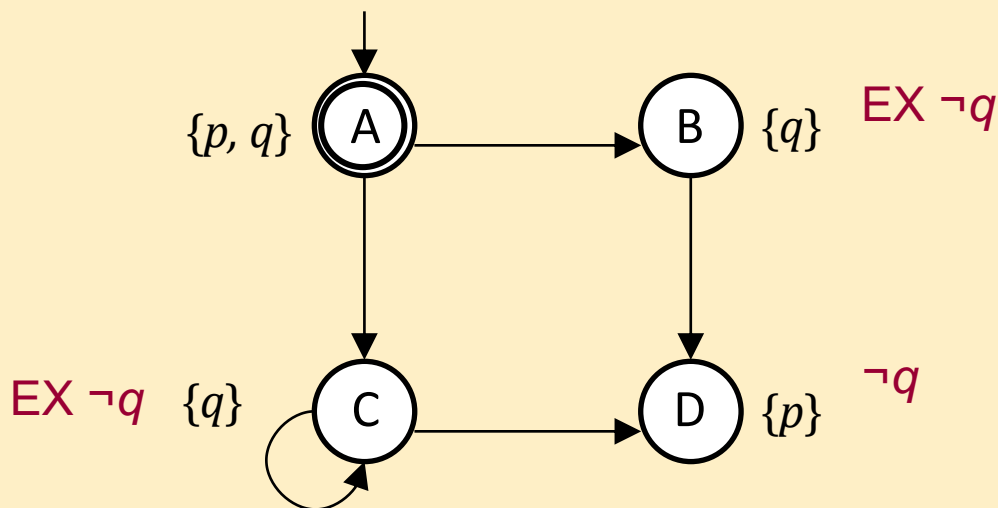


Checking CTL using iterative labeling – Solution 2/4

Check if the following CTL expression holds from the initial state using the iterative labeling algorithm:

$$A(p \text{ U } (\text{EX } \neg q))$$

1. Labeling D with $\neg q$
2. Labeling B and C with $\text{EX } \neg q$

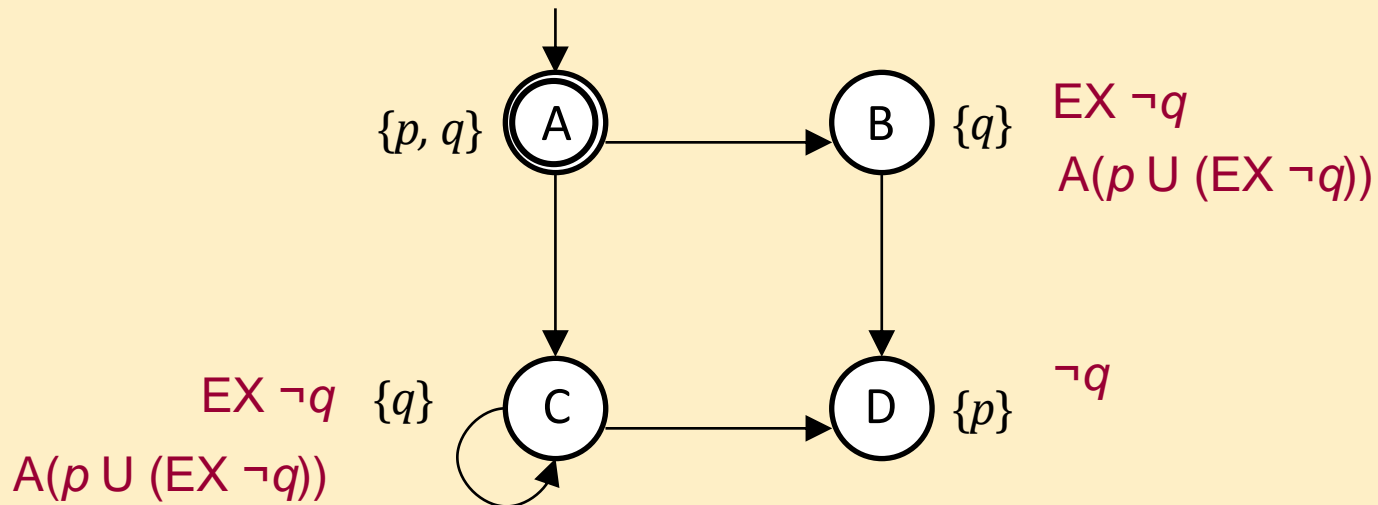


Checking CTL using iterative labeling – Solution 3/4

Check if the following CTL expression holds from the initial state using the iterative labeling algorithm:

$$A(p \text{ U } (EX \neg q))$$

1. Labeling D with $\neg q$
2. Labeling B and C with $EX \neg q$
3. Labeling B and C with $A(p \text{ U } (EX \neg q))$



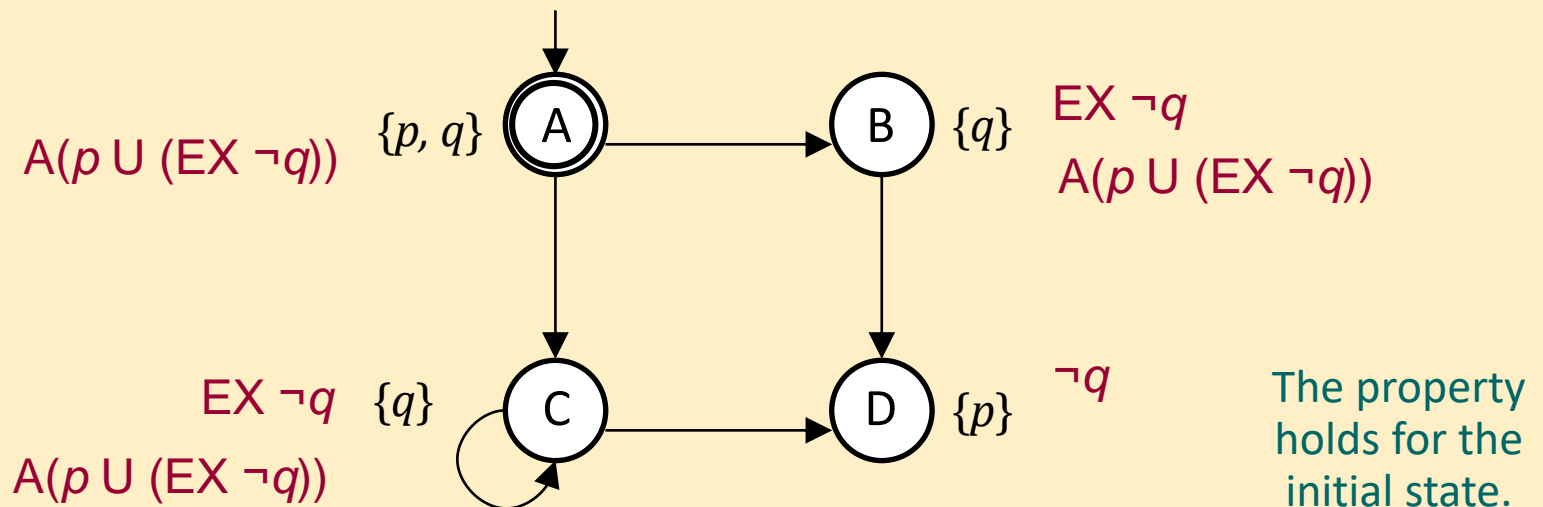
Checking CTL using iterative labeling – Solution 4/4

Check if the following CTL expression holds from the initial state using the iterative labeling algorithm:

$$A(p \text{ U } (EX \neg q))$$

1. Labeling D with $\neg q$
2. Labeling B and C with $EX \neg q$
3. Labeling B and C with $A(p \text{ U } (EX \neg q))$
4. Labeling A with $A(p \text{ U } (EX \neg q))$

End of the iteration.

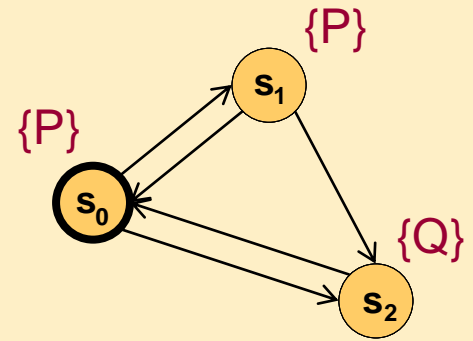


Model checking with the tableau method

Consider the Kripke structure on the right.

Perform the model checking of the following formula with the tableau method:

$$\neg (P \cup Q)$$

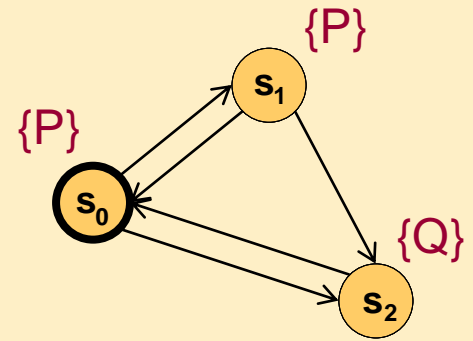


Model checking with the tableau method

Consider the Kripke structure on the right.

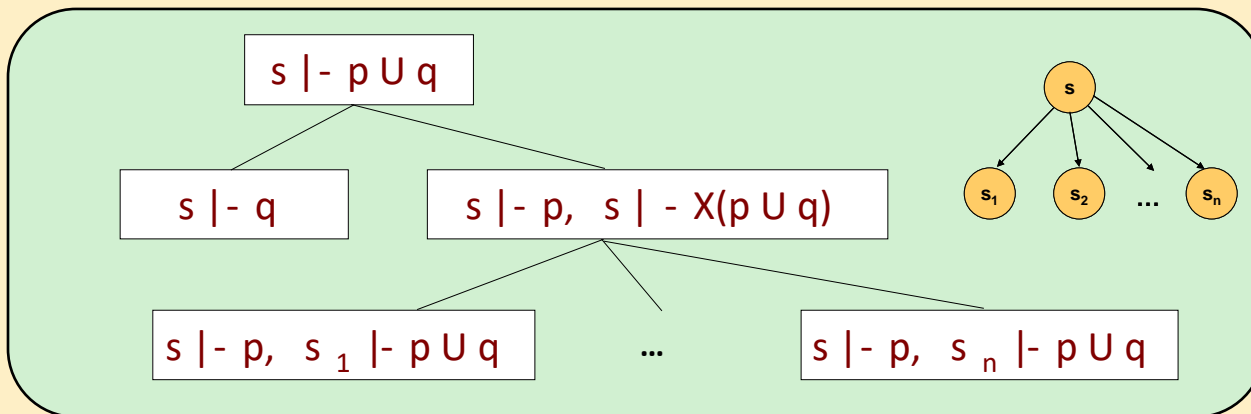
Perform the model checking of the following formula with the tableau method:

$$\neg (P \cup Q)$$



Things to know:

- Negation (to look for counterexamples): $(P \cup Q)$
- Tableau rule: $(P \cup Q) = Q \vee (P \wedge X(P \cup Q))$

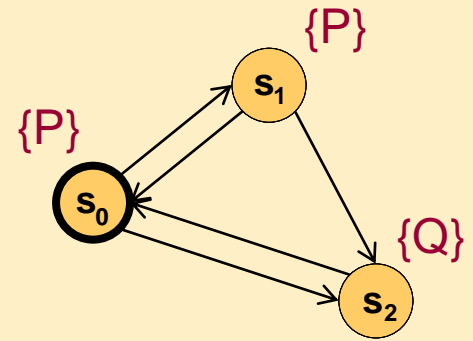


Model checking with the tableau method

Consider the Kripke structure on the right.

Perform the model checking of the following formula with the tableau method:

$$\neg (P \cup Q)$$

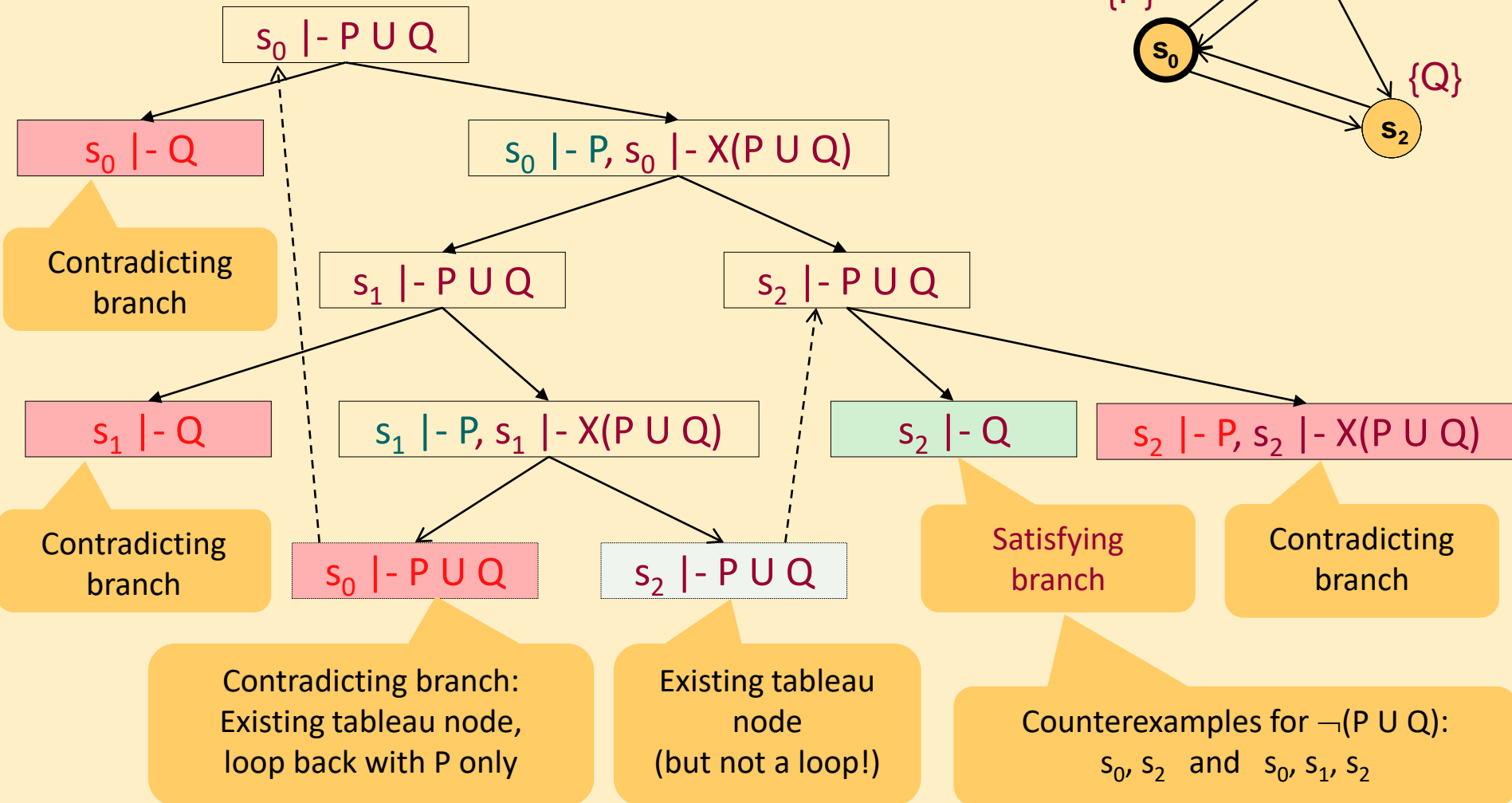
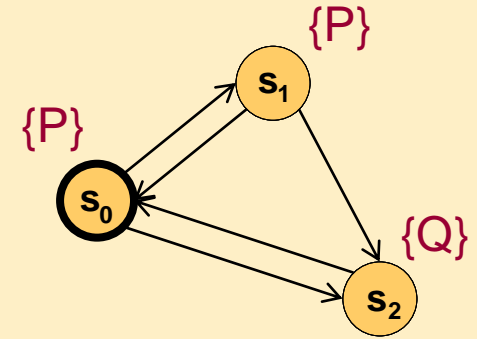


Things to know:

- Negation (to look for counterexamples): $\neg (P \cup Q)$
- Tableau rule: $\neg (P \cup Q) = \neg Q \vee (\neg P \wedge X\neg (P \cup Q))$
- Contradicting branch if:
 - Atomic proposition does not hold in a state
 - X operator but no outgoing transition from a state
 - Loop in the tableau with P, but without Q
- Satisfying branch (here: giving counterexamples) if:
 - Only atomic propositions, and all of them hold in the state
 - Loop in the table without contradiction

Model checking with the tableau method

Tableau construction:



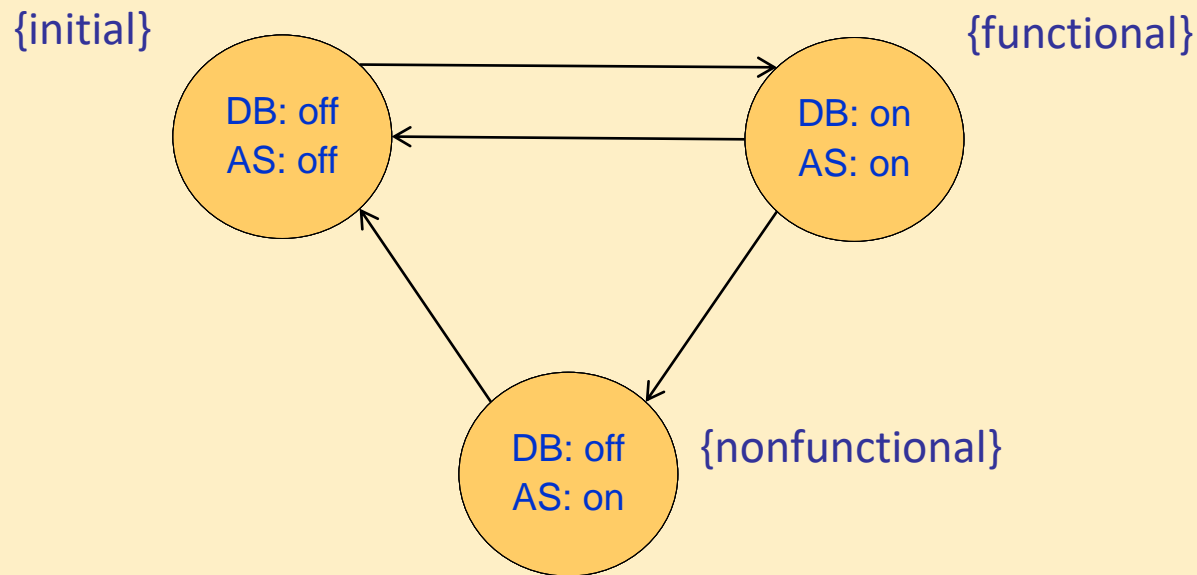
Model checking: Servers

- An IT system has two servers, a **database server** (DB) and an **application server** (AS), both of which can be turned on or off.
- **Initially**, both servers are off. During normal operation, the servers are turned on and off simultaneously.
- The system is **functional** if both servers are on.
- If – in the functional state – the database server is turned off due to an error, then the system becomes **nonfunctional**. After this, the application server is also turned off, then the system is restarted by turning both servers on again.
- Tasks:
 1. Create a **Kripke structure** modeling the behavior of the **system** described above with regard to the states of the servers! Label the states with the following atomic propositions (based on the informal description):
 $\{\text{initial, functional, nonfunctional}\}$
 2. Check if the following CTL formula holds for the **functional** state of the Kripke structure:
 $E(\neg \text{nonfunctional} \cup \text{initial})$

Model checking: Servers – Solution 1/2

- An IT system has two servers, a **database server (DB)** and an **application server (AS)**, both of which can be turned on or off.
- **Initially**, both servers are off. During normal operation, the servers are turned on and off simultaneously.
- The system is **functional** if both servers are on.
- If – in the functional state – the database server is turned off due to an error, then the system becomes **nonfunctional**. After this, the application server is also turned off, then the system is restarted by turning both servers on again.

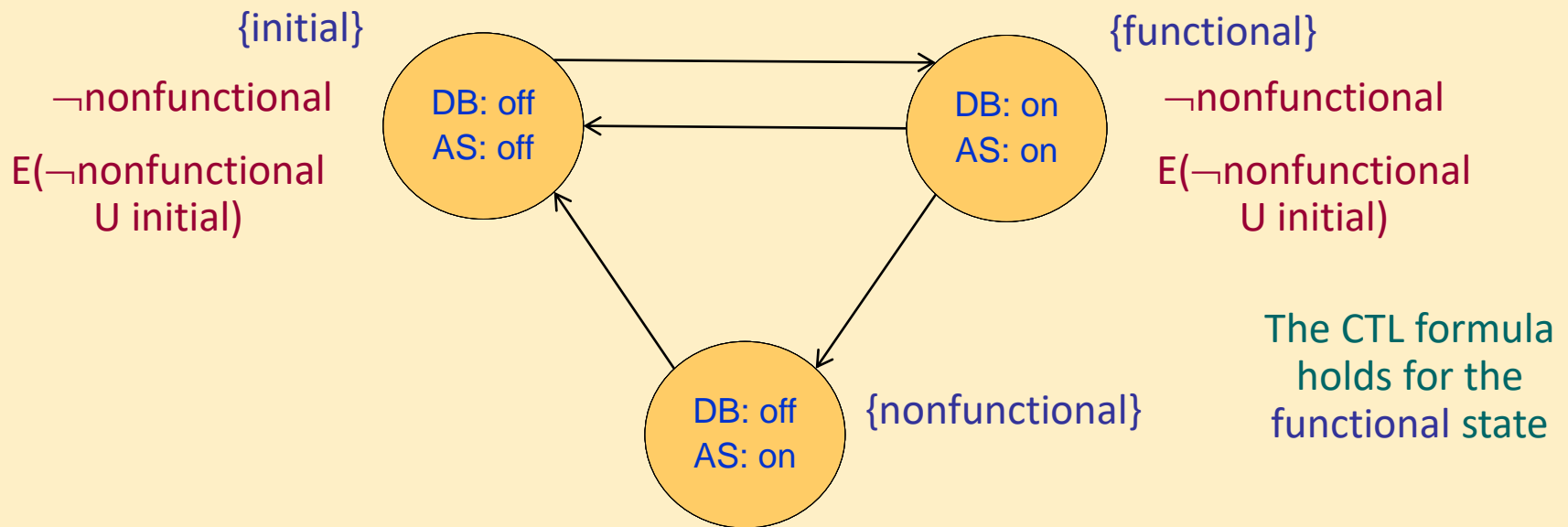
Kripke structure of the system:



Model checking: Servers – Solution 2/2

- An IT system has two servers, a **database server (DB)** and an **application server (AS)**, both of which can be turned on or off.
- **Initially**, both servers are off. During normal operation, the servers are turned on and off simultaneously.
- The system is **functional** if both servers are on.
- If – in the functional state – the database server is turned off due to an error, then the system becomes **nonfunctional**. After this, the application server is also turned off, then the system is restarted by turning both servers on again.

Labeling the Kripke structure with the properties:



ROBDD: Building ROBDD

Consider the following Boolean function g :

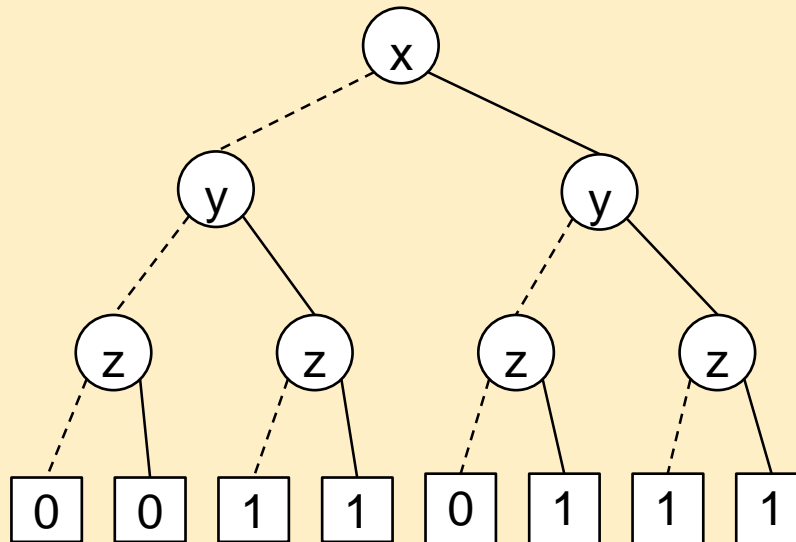
x	y	z	f(x,y,z)
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1

1. Construct the **decision tree** representing g ! Use the variable ordering used in the table: x, y, z .
2. Based on this, construct the **reduced ordered binary decision diagram** (ROBDD) representation of g !
3. Give the algebraic form of the function!

ROBDD: Building ROBDD – Solution 1/3

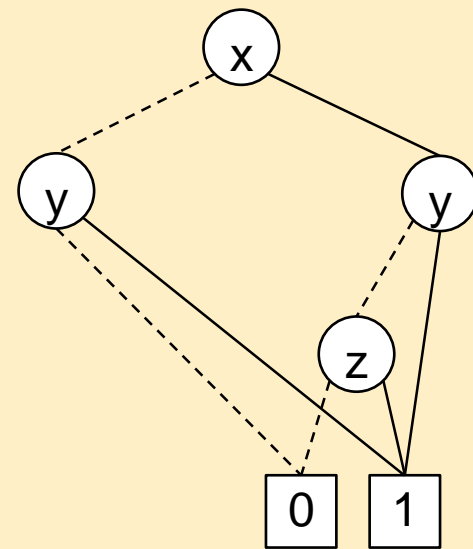
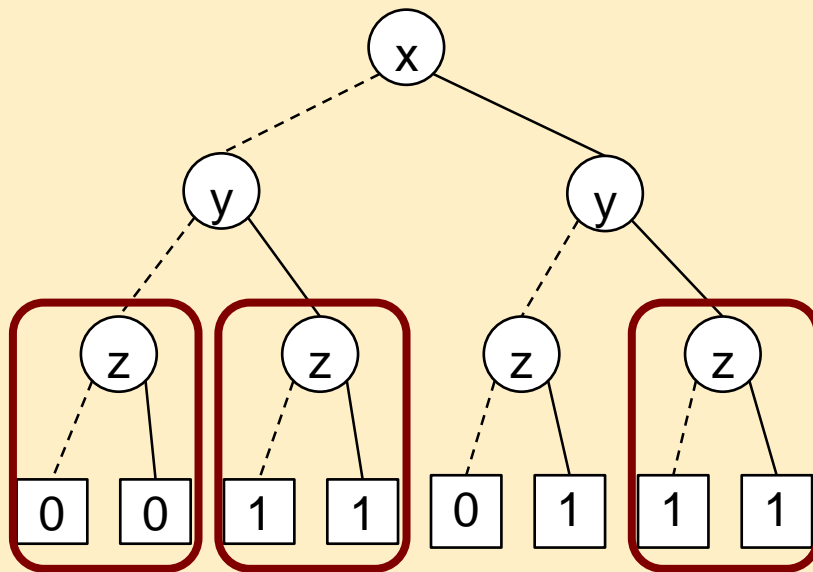
Constructing the decision tree for function g :

x	y	z	f(x,y,z)
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	1
1	0	0	0
1	0	1	1
1	1	0	1
1	1	1	1



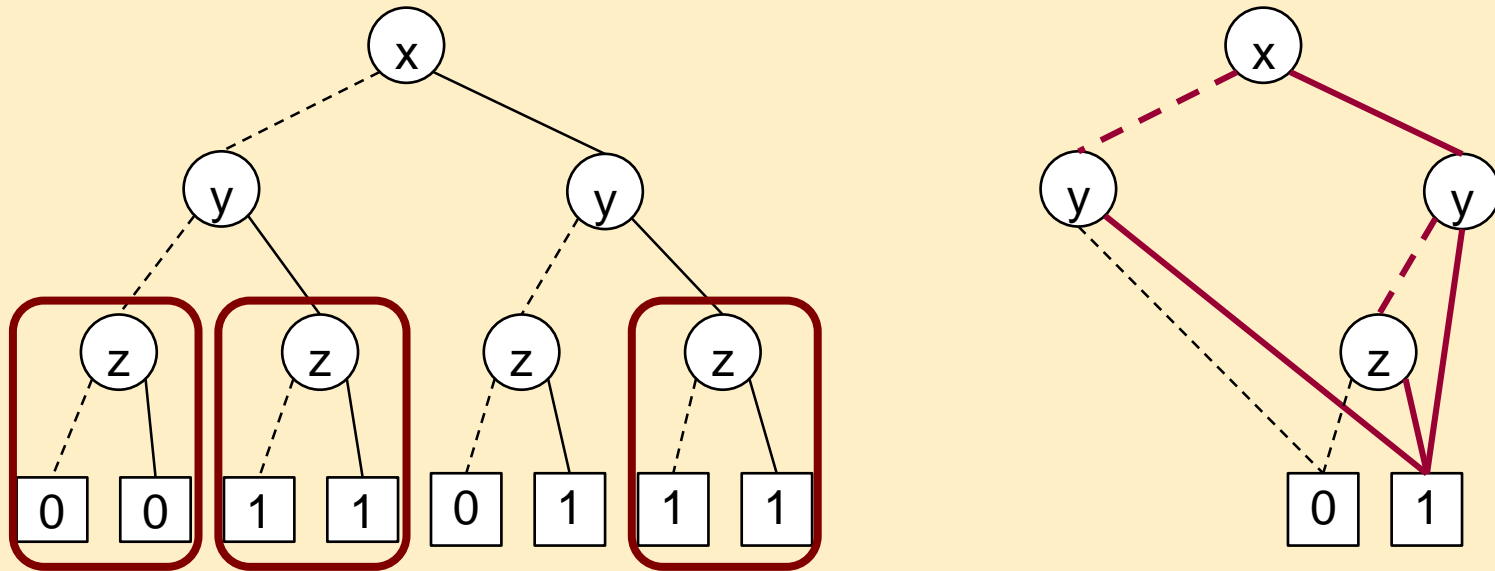
ROBDD: Building ROBDD – Solution 2/3

Constructing the ROBDD for function g :



ROBDD: Building ROBDD – Solution 3/3

Constructing the ROBDD for function g :

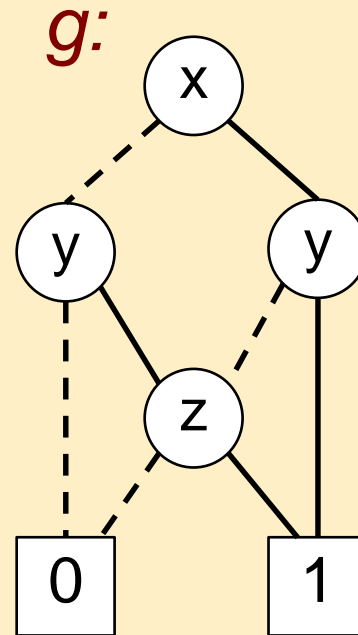
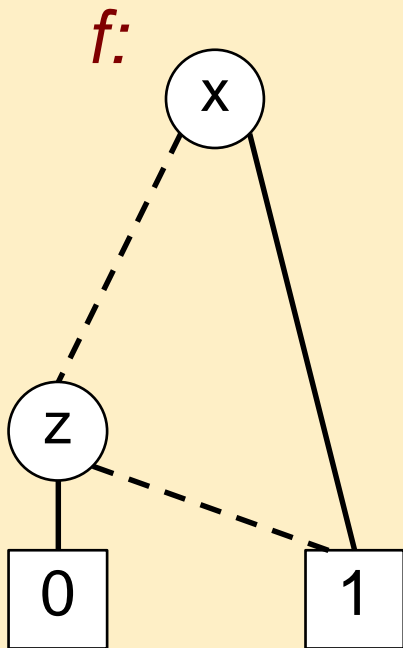


Algebraic function: Following the paths to 1:

$$g = (\neg x \wedge y) \vee (x \wedge \neg y \wedge z) \vee (x \wedge y)$$

ROBDD: Operations on functions

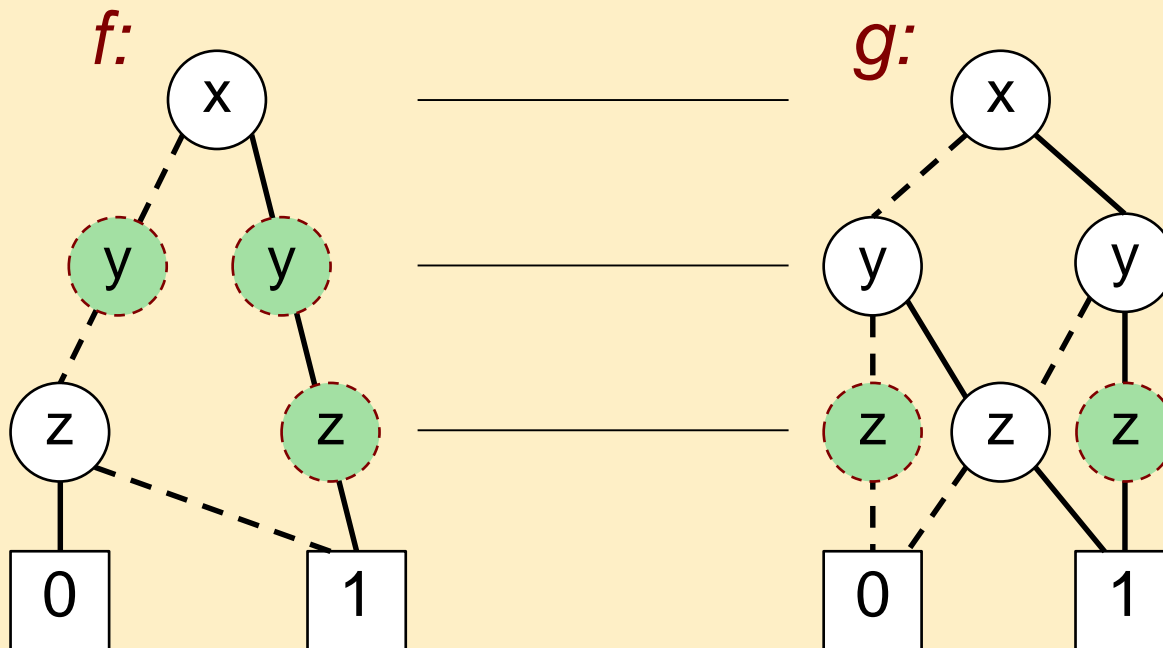
Consider the following functions f and g given in ROBDD form. Construct the ROBDD representing $f \wedge g$!



ROBDD: Operations on functions

Consider the following functions f and g given in ROBDD form. Construct the ROBDD representing $f \wedge g$!

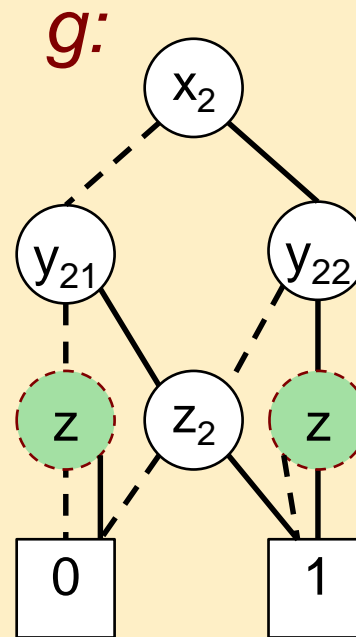
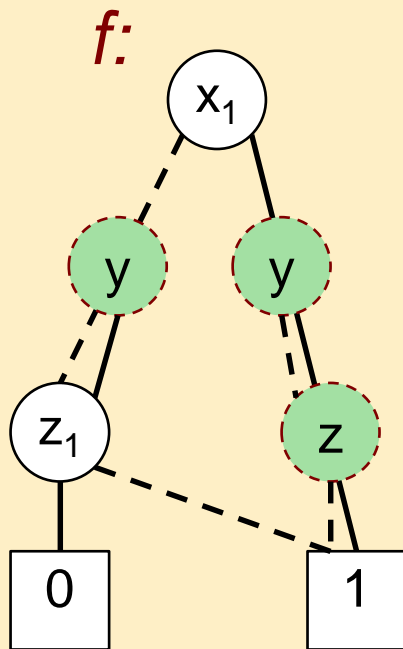
Missing (reduced) nodes:



ROBDD: Operations on functions

Consider the following functions f and g given in ROBDD form. Construct the ROBDD representing $f \wedge g$!

Identifying the existing nodes:

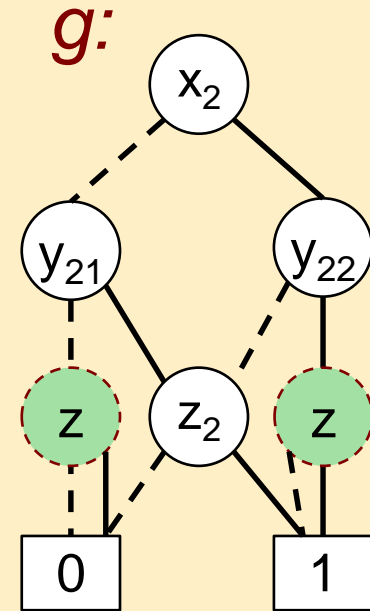
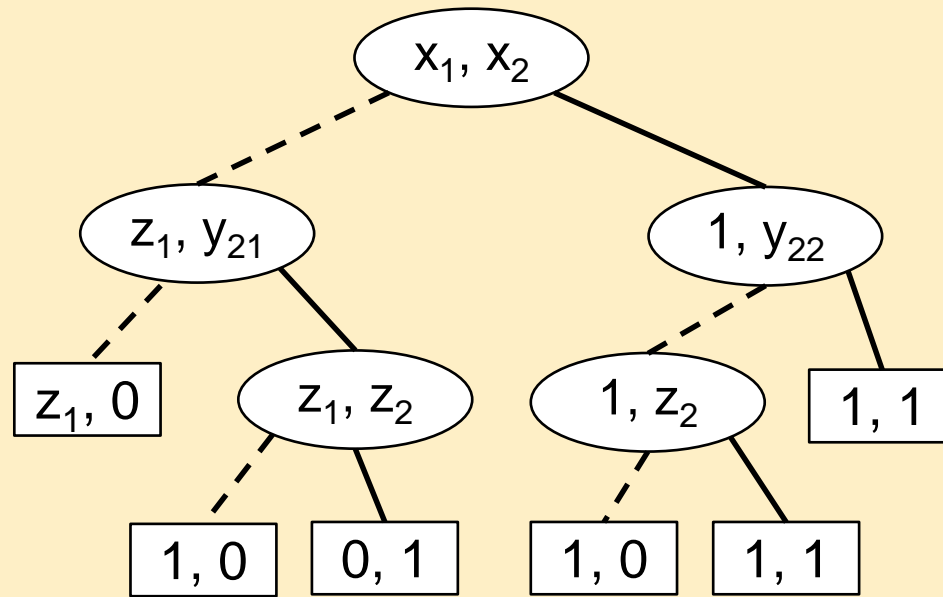
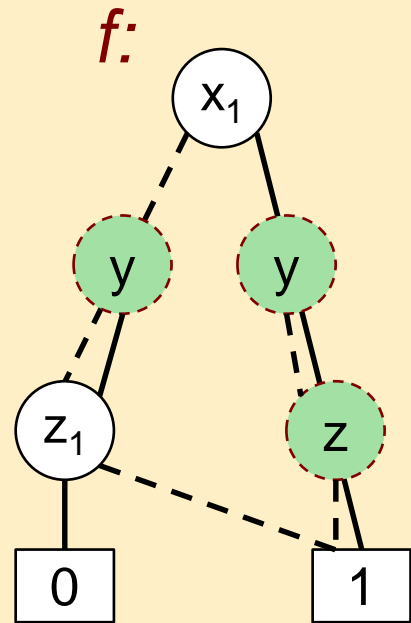


ROBDD: Operations on functions – Solution

Constructing the ROBDD representing $f \wedge g$!

“Combining” the nodes:

$f \wedge g$:

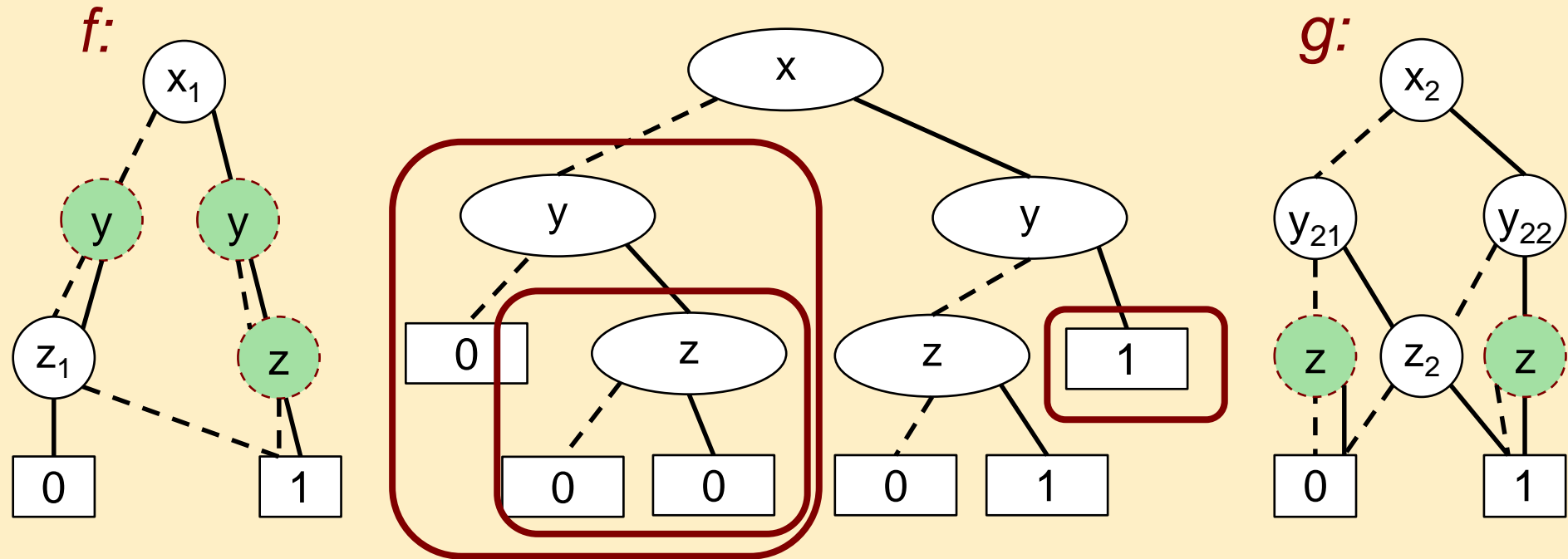


ROBDD: Operations on functions – Solution

Constructing the ROBDD representing $f \wedge g$!

Reducing some nodes:

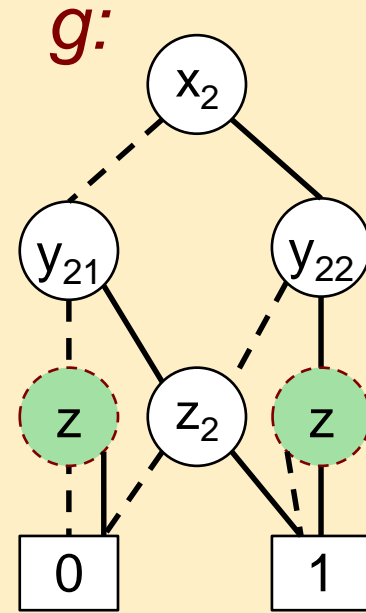
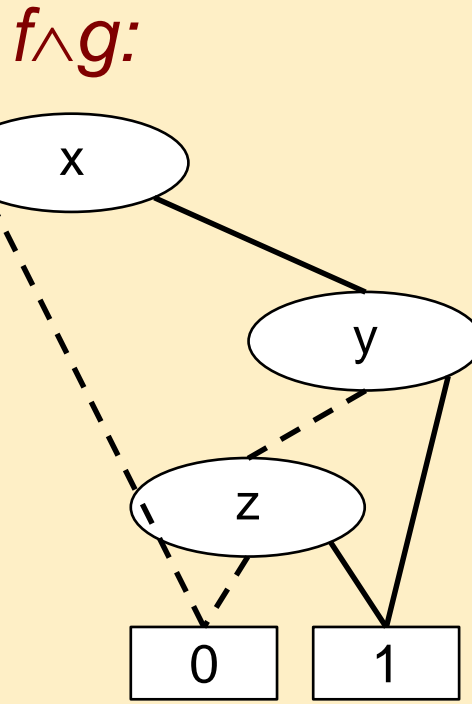
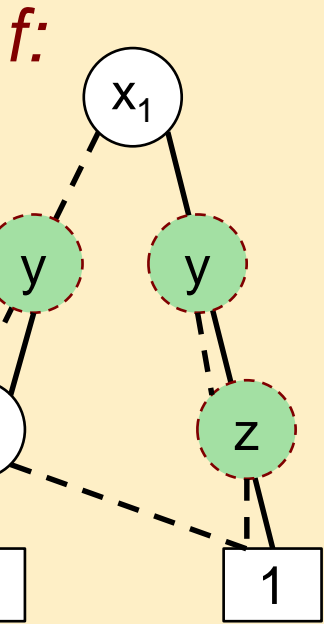
$f \wedge g$:



ROBDD: Operations on functions – Solution

Constructing the ROBDD representing $f \wedge g$!

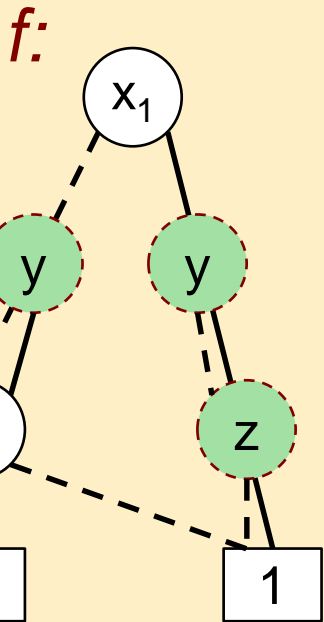
Reducing some nodes:



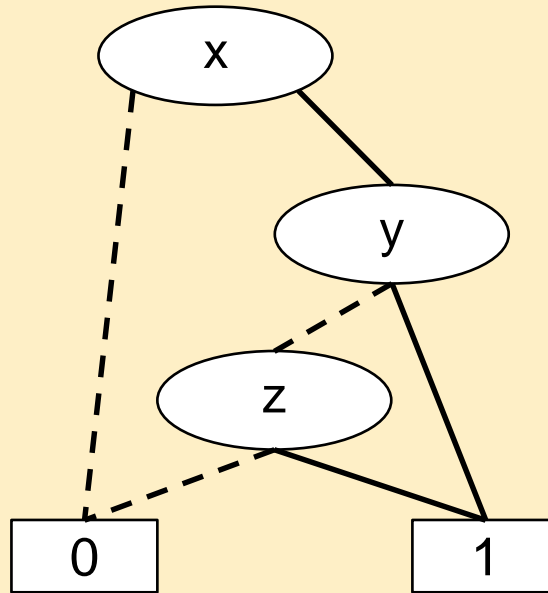
ROBDD: Operations on functions – Solution

Constructing the ROBDD representing $f \wedge g$!

The resulting ROBDD:



f \wedge *g:*



g:

